

Bernoulli - Mixing - Ergodic - Recurrent

In this lecture we study the relation between properties of measure preserving systems, most of which we introduced before:

A measure preserving system $(X, \mathcal{B}, \mu; T)$ is

- ▶ **Bernoulli** if it is isomorphic to a two-sided Bernoulli shift.
- ▶ **strong mixing** if for all $A, B \in \mathcal{B}$

$$\mu(T^{-n}(A) \cap B) - \mu(A)\mu(B) \rightarrow 0.$$

- ▶ **weak mixing** if for all $A, B \in \mathcal{B}$ the average

$$\frac{1}{n} \sum_{i=0}^{n-1} |\mu(T^{-i}(A) \cap B) - \mu(A)\mu(B)| \rightarrow 0.$$

- ▶ **ergodic** if $T^{-1}(A) = A \bmod \mu$ implies $\mu(A) = 0$ or $\mu(A^c) = 0$.
- ▶ **recurrent** if for all $A \in \mathcal{B}$ with $\mu(A) > 0$ there is $n \geq 1$ such that $\mu(T^n(A) \cap A) > 0$.

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First an alternative way of stating ergodicity:

Lemma: A probability preserving dynamical system (X, \mathcal{B}, T, μ) is ergodic if and only if

$$\frac{1}{n} \sum_{i=0}^{n-1} \mu(T^{-i}(A) \cap B) - \mu(A)\mu(B) \rightarrow 0 \text{ as } n \rightarrow \infty,$$

for all $A, B \in \mathcal{B}$. (Compared to weak mixing, note the absence of absolute value bars.)

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Proof: Assume that T is ergodic, so by Birkhoff's Ergodic Theorem $\frac{1}{n} \sum_{i=0}^{n-1} 1_A \circ T^i(x) \rightarrow \mu(A)$ μ -a.e. Multiplying by 1_B gives

$$\frac{1}{n} \sum_{i=0}^{n-1} 1_A \circ T^i(x) 1_B(x) \rightarrow \mu(A) 1_B(x) \quad \mu\text{-a.e.}$$

Integrating over x (using the Dominated Convergence Theorem to swap limit and integral), gives

$$\lim_n \frac{1}{n} \sum_{i=0}^{n-1} \int_X 1_A \circ T^i(x) 1_B(x) d\mu = \mu(A) \mu(B).$$

Conversely, assume that $A = T^{-1}A$ and take $B = A$. Then we obtain $\mu(A) = \frac{1}{n} \sum_{i=0}^{n-1} \mu(A \cap T^{-i}(A)) \rightarrow \mu(A)^2$, hence $\mu(A) \in \{0, 1\}$.

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Theorem We have the implications:

Bernoulli \Rightarrow mixing \Rightarrow weak mixing \Rightarrow ergodic \Rightarrow recurrent.

None of the reverse implications holds.

Example We know already that irrational rotations $R_\alpha : \mathbb{S}^1 \rightarrow \mathbb{S}^1$ are ergodic (even uniquely ergodic). Let us show R_α is not mixing:

Take an interval A of length $\frac{1}{4}$. There are infinitely many n such that $R_\alpha^{-n}(A) \cap A = \emptyset$, so

$$\liminf_n \mu(R^{-n}(A) \cap A) = 0 \neq \left(\frac{1}{4}\right)^2.$$

Circle rotations are not weak mixing either.

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Proof Bernoulli \Rightarrow mixing holds for any pair of cylinder sets $Z = Z_{[a,b]}$, $Z' = Z_{[c,d]}$ because $\mu(\sigma^{-n}(Z) \cap Z') = \mu(Z)\mu(Z')$ for $n > d - a$. The property carries over to all measurable sets by the Kolmogorov Extension Theorem.

Mixing \Rightarrow weak mixing is immediate from the definition.

Weak mixing \Rightarrow ergodic is immediate from the characterization of ergodicity in the previous lemma.

Ergodic \Rightarrow recurrent. If $B \in \mathcal{B}$ has positive measure, then $A := \bigcup_{i \in \mathbb{N}} T^{-i}(B)$ is T -invariant up to a set of measure 0, see the Poincaré Recurrence Theorem. By ergodicity, $\mu(A) = 1$, and thus μ -a.e. $x \in B$ returns to B .

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An example of a **recurrent but not ergodic transformation** is the identity map $T : [0, 1] \rightarrow [0, 1]$ with $\mu = \text{Lebesgue}$.

There are standard examples to show that

- ▶ **weak mixing \nRightarrow mixing**. The first counter-example in the literature is Chácon's cutting and stacking example.
- ▶ **mixing \nRightarrow Bernoulli**.

But I will not cover these examples in class. (See the notes for Chacon's cutting and stacking example.)