Mixing rates for almost Anosov maps and flows

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October 26, Colloquium, Leiden

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Lorenz Flow



The appropriate Navier-Stokes equations reduce (via Galerkin method) to the Lorenz Equations:

$$\begin{cases} \dot{x} = \sigma(y - x) \\ \dot{y} = \rho x - xz - y \\ \dot{z} = xy - \beta z \end{cases}$$

 $\sigma, \rho, \beta > 0$ relate to the Prandl and Rayleigh numbers

Lorenz Flow

$$\begin{cases} \dot{x} = \sigma(y - x) & \sigma, \rho, \\ \dot{y} = \rho x - xz - y & \text{to th} \\ \dot{z} = xy - \beta z & \text{Rayl} \end{cases}$$

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For certain parameters (classical choice $\sigma = 10, \beta = \frac{8}{3}, \rho = 28$) the Lorenz equations have a chaotic attractor.



http://www.malinc.se/m/Lorenz.php

Lorenz Flow

Afraĭmovič, Bykov, & Shilnikov and independently Guckenheimer & Williams made geometrical models to explain the dynamics of the Lorenz system.



Mixing (formal definitions)

A measure μ is invariant for the flow ϕ^t if

 $\mu(\phi^{-t}(A)) = \mu(A)$ for all t > 0 and measurable A.

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We think of physical measures, i.e., those μ for which

$$\mu(\mathbf{A}) = \inf_{\varepsilon \to 0} \lim_{T \to \infty} \frac{1}{T} \int_0^T \mathbf{1}_{B(\mathbf{A};\varepsilon)} \circ \phi^t(\mathbf{x}) \, dt$$

for x in a set of positive Lebesgue measure.

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for x in a set of positive Lebesgue measure.

The measure mixing if the correlation coefficients tend to 0:

$$\rho_t(\mathbf{v}, \mathbf{w}) := \int_X (\mathbf{v} \circ \phi^t) \cdot \mathbf{w} \, d\mu \to 0$$

for appropriate observables $v, w : X \to \mathbb{R}$.

The speed at which ρ_t tends to 0 is called the rate of mixing.

Mixing (heuristics)

Dynamical systems that are **uniformly** hyperbolic, i.e., which have **uniformly** exponential contraction (in stable direction) and exponential expansion (in unstable directions, tend to have exponentially mixing physical measures.

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Toy examples: Gauss map: $d\nu = \frac{1}{\log 2} \frac{dx}{1+x}$ and baker map: $\nu = Leb$.

A classical system with **non-uniform** expansion is the Pomeau-Manneville map with parameter $\alpha > 0$:

$$\mathcal{T}_{lpha}: [0,1]
ightarrow [0,1], \qquad x \mapsto x(1+x^{lpha}) model 1.$$

The neutral fixed point $(T'_{\alpha}(0) = 1)$ makes the expansion non-uniform.

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By taking the first return map to the right part, we obtain uniform expansion.





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Y is the domain of the second branch and $\tau(\mathbf{y}) = \min\{\mathbf{n} \ge \mathbf{1} : T^n(\mathbf{y}) \in \mathbf{Y}\}.$ The first return map $R_{\rm Y} = T^{\tau}$ is uniformly expanding, and preserves a measure $\nu \approx Leb.$ with big tails $\nu(\{\tau > n\}\}) \sim n^{1-1/\alpha}$.

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Theorem [Liverani-Saussol-Vaienti, Young, ...]

The Pomeau-Manneville map has an invariant measure $\mu \approx \textit{Leb}.$ This measure is

- infinite if $\alpha \geq 1$ (the physical measure is δ_0);
- finite if $\alpha < 1$, and μ is the physical measure.
- ▶ the rate of mixing is polynomial if $\alpha < \frac{1}{2}$: $\rho_f(v, w) \leq C_{v,w} n^{1-\frac{1}{\alpha}}$

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The upper bound in the rate of mixing is sharp. Techniques to prove this were developed by Sarig, Gouëzel (and by Melbourne & Terhesiu in infinite measure setting). Requires: "big tails" are regularly varying:

$$\nu(\tau > \mathbf{n}) = \mathbf{n}^{-\beta} \ell(\mathbf{n})$$

where ℓ is slowly varying (e.g. $\ell(n) \to C \neq 0$ or $\ell(n) = (\log n)^{\gamma}$).

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Mixing in the Lorenz system

Theorem [Tucker 2000, rigorous computer-assisted]

The geometric Lorenz model is a valid description of the Lorenz equations. In particular, the Lorenz attractor exists.

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Theorem [Araújo et al. 2009]

The Lorenz system has a physical measure μ supported on the Lorenz attractor *A*, and it has a positive Lyapunov exponent χ :

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For μ -a.e. $x \in A \exists v \in T_x \mathbb{R}^3$ s.t. $\lim_t \frac{1}{t} \log \|D\phi^t(v)\| = \chi > 0$.

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Theorem [Araújo & Melbourne 2016]

This physical measure is mixing at an exponential rate.

Lorenz Flow - Local form at 0



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Lorenz Flow - Local form at 0



Differential equation near 0 (hyperbolic saddle):

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Dulac times have exponential tails.

Lorenz Flow - Surgery at 0



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Lorenz Flow - Surgery at 0



Differential equation near 0 (neutral saddle):

$$\begin{cases} \dot{x} = x(a_0x^2 + a_1xz + a_2z^2) \\ \dot{y} = -\lambda_1y \\ \dot{z} = -y(b_0x^2 + b_1xz + b_2z^2) \end{cases} + \mathcal{O}(4)$$

$$\begin{array}{l} a_0, a_2, b_0, b_2 \geq 0, \ a_1, b_1 \in \mathbb{R} \\ \Delta := a_2 b_0 - a_0 b_2 \neq 0 \\ a_1^2 < 4 a_0 a_2, \ b_1^2 < 4 b_0 b_2 \\ \frac{b_1}{a_1} = \frac{a_0 b_2 + a_2 + 2 b_0 b_2}{a_2 b_0 + a_2 + 2 a_0 a_2} \end{array}$$

Question: Do the Dulac times have polynomial tails?

Dulac times



The Dulac time *T* is the time needed to flow from an incoming transversal $\{z = \eta\}$ to an outgoing transversal $\{x = \zeta\}$.

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Dulac times

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Theorem (regularly varying Dulac times)

Define

$$\Gamma_0 := rac{2a_0}{a_0 + b_0}, \qquad \Gamma_2 := rac{2b_2}{a_2 + b_2}.$$

There exists $C_x, C_y > 0$ such that the Dulac times (as, $x, y \rightarrow 0$)

$$T = C_{x}x^{-\Gamma_{2}}(1 + \mathcal{O}(x^{\Gamma_{2}/2})) = C_{y}y^{-\Gamma_{0}}(1 + \mathcal{O}(y^{\Gamma_{0}/2})).$$

Neutral Lorenz flows

Consider the Lorenz flow after surgery; local form near 0:

 $\begin{cases} \dot{x} = x(a_0x^2 + a_1xz + a_2z^2) \\ \dot{y} = -\lambda_1y & + \mathcal{O}(4) \\ \dot{z} = -y(b_0x^2 + b_1xz + b_2z^2) \end{cases}$

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Theorem (Bruin & Canales, 2022)

The above neutral Lorenz flow has correlation coefficients:

$$ho_t(oldsymbol{v},oldsymbol{w}) \leq oldsymbol{C} \cdot (\|oldsymbol{v}\|_{C^\eta} + \|oldsymbol{v}\|_{C^{0,\eta}}) \cdot \|oldsymbol{w}\|_{C^{m,\eta}} \cdot t^{-eta}, \qquad eta = rac{oldsymbol{a}_2 + oldsymbol{b}_2}{2oldsymbol{b}_2},$$

for C > 0 depending only on the flow and η -Hölder functions v and w.

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for C > 0 depending only on the flow and η -Hölder functions v and w.

$$\|v\|_{C^{0,\eta}} = \sup_{x \in M, t > 0} \frac{|v(T^{t}(x)) - v(x)|}{t^{\eta}}, \qquad \|w\|_{C^{m,\eta}} = \sum_{k=0}^{m} \|\partial_{t}^{k}w\|_{C^{\eta}}.$$

or η -Hölder norm $\|v\|_{C^{\eta}} = \sup_{x \neq y} \frac{|v(x) - v(y)|}{|x - y|^{\eta}}.$

Definition: $T : X \to X$ is called an Anosov map if the whole space X is hyperbolic, i.e., the tangent bundle of X has a continuous splitting into stable and unstable spaces along which the contraction and expansion is uniform.

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Examples are linear toral automorphisms, e.g.

$$T(x) = Mx \mod 1, \qquad M = \begin{pmatrix} 1 & 1 \\ 1 & 0 \end{pmatrix}$$



Figure: The Markov partition for $T_M : \mathbb{T}^2 \to \mathbb{T}^2$; the catmap is T_M^2 .

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The notion of almost Anosov map goes back to Anatoli Katok [1979], who created area preserving examples. Later versions by Hu & Young [1995], Hu [2000] and Young & Zhang [2017]:

Let T be an almost Anosov map with fixed point 0 such that

(**)
$$T\binom{x}{y} = \binom{x(1+a_0x^2+a_1xy+a_2y^2)}{y(1-a_0x^2-a_1xy-b_2y^2)}$$

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in local coordinates near 0.

Theorem (Hu 2000)

- If a₂ > 2b₂ and a₁ = 0 = b₁ and a₀b₂ > a₂b₀, then T admits a physical probability measure.
- If a₂ < b₂/2 and a₁ ≠ 0 ≠ b₁, then T admits an infinite "physical" measure.

Hu & Zhang [2017] gave polynomial upper bounds for mixing rates of the physical measure of the almost Anosov map T.

But, T from (**) is the time-1 map of a flow in (*). The tail estimates of (*) are far more precise (exact exponent, slowly varying).

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Exact distinction between finite and infinite "physical" measure:

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Exact mixing rates: upper and lower, finite and infinite measure.

 $\rho_n(\mathbf{v}, \mathbf{w}) \sim C(\mathbf{v}, \mathbf{w}) n^{1-\beta} \quad \text{if } \beta > 1,$

Analogous formula on transfer operator $\mathcal{L}_{\mathcal{T}}$ if measure is infinite.

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Various other statistical limit theorems.

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with restrictions on parameters as before.

Theorem (Bruin & Terhesiu 2017, mixing for ∞ measure)

Let T be an almost Anosov map of the torus as in (**) with $\beta \in (\frac{1}{2}, 1)$, *i.e.*, there is an *infinite* "physical" measure μ .

Then for all observables $v, w \in C^1$ supported outside a neighbourhood of the fixed point, we have

$$\lim_{n\to\infty} n^{1-\beta} \int \mathbf{v} \cdot \mathbf{w} \circ T^n \, d\mu = \frac{C_0}{\Gamma(\beta)(1-\Gamma(\beta))} \int \mathbf{v} \, d\mu \int \mathbf{w} \, d\mu$$

for Γ -function Γ and C_0 comes from the big tails $\mu(\tau > n) \sim C_0 n^{-\beta}$.

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In case that T is the time-1 map of a cubic (*), i.e., without higher order terms, then the tail estimates can be improved to estimates of the small tails:

 $\mu(\tau = n) = C_0 n^{-(\beta+1)} (1 + o(1)).$

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Theorem (Bruin & Terhesiu 2017, mixing for ∞ measure)

Let T be an almost Anosov map above, with $\beta \in (\frac{1}{2}, 1)$ and

$$q = \max\{j \in \mathbb{N} : (j+1)\beta > j\}.$$

Then for all observables as previously there are (generically nonzero) real constants $d_1, \ldots, d_q \in \mathbb{R}$ such that

$$\int \mathbf{v} \cdot \mathbf{w} \circ T^n \, d\mu \sim \left(d_0 n^{\beta-1} + d_1 n^{2(\beta-1)} + \dots + d_q n^{(q+1)(\beta-1)} \right) \\ \times \int \mathbf{v} \, d\mu \int \mathbf{w} \, d\mu.$$

Almost Anosov flows (volume-preserving)

The almost Anosov flow can be made volume preserving by setting the divergence of the vector field equal to zero. For the local parameters this means:

$$3a_0 = b_0$$
 $a_1 = b_1$ $a_2 = 3b_2$.

Then the condition $\frac{b_1}{a_1} = \frac{a_0b_2 + a_2 + 2b_0b_2}{a_2b_0 + a_2 + 2a_0a_2}$ is automatically satisfied. Use the change of coordinates

$$\bar{x} = \sqrt{a_0}x, \ \bar{y} = \sqrt{b_2}y, \ \bar{\gamma} = a_1/\sqrt{a_0b_2} \in (-4,4)$$

to transform the differential equation into

$$\begin{pmatrix} \dot{\bar{x}} \\ \dot{\bar{y}} \\ \dot{\bar{z}} \end{pmatrix} = \begin{pmatrix} \bar{x}(\bar{x}^2 + \bar{\gamma}\bar{x}\bar{y} + 3\bar{y}^2) \\ -\bar{y}(3\bar{x}^2 + \bar{\gamma}\bar{x}\bar{y} + \bar{y}^2)) \\ 1 + \bar{w}(\bar{x},\bar{y}) \end{pmatrix} + \mathcal{O}(4),$$

for some real-valued function \bar{w} .

Almost Anosov flows (volume-preserving)

Theorem (Bruin, 2020)

Let $\bar{\gamma} \in (-4, 4)$ and $v = v_0 + o(\rho)$, where $\int_0^{\tau} v_0 \circ \phi^t dt$ is homogeneous of order $\rho > -2$ in local coordinates.

1. If $\rho \in (0,\infty)$, then v satisfies the Central Limit Theorem, i.e.,

$$rac{\int_0^t v \circ \phi^s \, ds - t \int v \, dV ol}{\sigma \sqrt{t}} \Rightarrow_{\mathit{dist}} \mathcal{N}(0,1) \quad \textit{as } t o \infty,$$

where the variance σ² > 0 unless ∫₀^τ v ∘ φ^t dt is a coboundary.
2. If ρ = 0, then v satisfies the Central Limit Theorem with non-standard scaling √t log t, i.e.,

$$\frac{\int_0^t v \circ \phi^s \, ds - t \int v \, dVol}{\sigma \sqrt{t \log t}} \Rightarrow_{dist} \mathcal{N}(0, 1) \quad \text{ as } t \to \infty,$$

and the variance $\sigma^2 > 0$ unless $\int_0^{\tau} v \circ \phi^t dt$ is a coboundary. 3. If $\rho \in (-2, 0)$ then v satisfies a Stable Law of order $\frac{4}{2-\rho} \in (1, 2)$.

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En toen kwam er een olifant met een heel erg lange snuit....

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