On Asymptotic Stability of Solitary Waves in Discrete Schrödinger Equation Coupled to Nonlinear Oscillator

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Abstract

The long-time asymptotics is analyzed for finite energy solutions of the 1D discrete Schrödinger equation coupled to a nonlinear oscillator. The coupled system is invariant with respect to the phase rotation group U(1). For initial states close to a solitary wave, the solution converges to a sum of another solitary wave and dispersive wave which is a solution to the free Schrödinger equation. The proofs use the strategy of Buslaev-Perelman [2]: the linerization of the dynamics on the solitary manifold, the symplectic orthogonal projection, method of majorants, etc.

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1 Introduction

Our main goal is the study of the distinguished dynamical role of the "quantum stationary states" for a model U(1)-invariant nonlinear discrete Schrödinger equation

$$i\dot{\psi}(x,t) = -\Delta_L \psi(x,t) - \delta(x)F(\psi(0,t)), \quad x \in \mathbb{Z}.$$
(1.1)

Here F is a continuous function, $\delta(x) = \delta_{0x}$ and Δ_L stands for the difference Laplacian in \mathbb{Z} , defined by

$$\Delta_L \psi(x) = \psi(x+1) - 2\psi(x) + \psi(x-1), \quad x \in \mathbb{Z}$$

for functions $\psi : \mathbb{Z} \to \mathbb{C}$. Physically, equation (1.1) describes the system of the free discrete Schrödinger equation coupled to an oscillator attached at the point x = 0: F is a nonlinear "oscillator force".

We identify a complex number $\psi = \psi_1 + i\psi_2$ with the real two-dimensional vector $\Psi = (\psi_1, \psi_2) \in \mathbb{R}^2$ and assume that the vector version **F** of the oscillator force *F* admits a real-valued potential,

$$\mathbf{F}(\Psi) = -\nabla U(\Psi), \quad \Psi \in \mathbb{R}^2, \quad U \in C^2(\mathbb{R}^2).$$
(1.2)

Then (1.1) is a Hamiltonian system with Hamiltonian

$$\mathcal{H}(\Psi) = \frac{1}{2} \langle -\Delta_L \Psi, \Psi \rangle + U(\Psi(0)) = \frac{1}{2} \langle \nabla_L \Psi, \nabla_L \Psi \rangle + U(\Psi(0)), \qquad (1.3)$$

where $\langle \cdot \rangle$ stands for the scalar product in $l^2(\mathbb{Z})$, and $\nabla_L \psi(x) = \psi(x+1) - \psi(x)$.

We assume that $U(\psi) = u(|\psi|^2)$ with $u \in C^2(\mathbb{R})$. Therefore, by (1.2),

$$F(\psi) = a(|\psi|^2)\psi, \quad \psi \in \mathbb{C}, \qquad a \in C^1(\mathbb{R}), \tag{1.4}$$

where $a(|\psi|^2)$ is real. Then $F(e^{i\theta}\psi) = e^{i\theta}F(\psi)$, $\theta \in [0, 2\pi]$ and F(0) = 0 for continuous F. Hence, $e^{i\theta}\psi(x,t)$ is a solution to (1.1) if $\psi(x,t)$ is. Therefore, equation (1.1) is U(1)-invariant in the sense of [5], and the Nöther theorem implies the conservation of l^2 norm:

$$\|\psi(t)\| = \|\psi(0)\|.$$

Here and below $\|\cdot\| = \|\cdot\|_{l^2}$.

The main subject of this paper is an analysis of the special role played by *solitary waves* or *nonlinear eigenfunctions*, which are finite energy solutions of the form

$$\psi(x,t) = \psi_{\omega}(x)e^{i\omega t}, \quad \omega \in \mathbb{R}.$$
(1.5)

The frequency ω and the amplitude $\psi_{\omega}(x)$ solve the following *nonlinear eigenvalue problem*:

$$-\omega\psi_{\omega}(x) = -\Delta_L\psi_{\omega}(x) - \delta(x)F(\psi_{\omega}(0)), \quad x \in \mathbb{Z}$$
(1.6)

which follows directly from (1.1) and (1.4) since $\omega \in \mathbb{R}$. The solitary waves constitute a twodimensional solitary manifold in the Hilbert phase space $l^2(\mathbb{Z})$.

We prove the asymptotics of type

$$\psi(\cdot, t) \sim \psi_{\omega_{\pm}} e^{i\omega_{\pm}t} + W(t)\Phi_{\pm}, \quad t \to \pm \infty, \tag{1.7}$$

where W(t) is the dynamical group of the free Schrödinger equation, $\Phi_{\pm} \in l^2(\mathbb{Z})$ are the corresponding asymptotic scattering states, and the remainder converges to zero as $\mathcal{O}(|t|^{-1/2})$

in global norm of $l^2(\mathbb{Z})$. The asymptotics hold for the solutions with initial states close to the *stable part* of the solitary manifold, extending the results of [1, 2, 3, 10, 11, 12] to the equation (1.1).

For the first time, the asymptotics of type (1.7) were established by Soffer and Weinstein [14, 15] (see also [13]) for nonlinear U(1)-invariant continuous Schrödinger equation with small initial states if the nonlinear coupling constant is sufficiently small. The next result was obtained by Buslaev and Perelman [2] who proved that the solitary manifold attracts finite energy solutions of a 1D nonlinear U(1)-invariant translation invariant Schrödinger equation with initial states sufficiently close to the *stable part* of the solitary manifold. For a more lengthy discussion of our motivation, and of previous results in the literature ([3, 11, 12, 13, 14, 15, 16]) we refer the reader to the introduction of [1]. The asymptotics of type (1.7) for nonlinear discrete Schrödinger equation are obtained for the first time in the present paper.

Let us note that we impose conditions which are more general than the standard ones in the following respects: we do not hypothesize any spectral properties of the linearized equation, and do not require any smallness condition on the initial state (only closeness to the solitary manifold). This progress is possible on account of the simplicity of our model which allows an exact analysis of spectral properties of the linearization.

Let us comment on the general strategy of our proofs. We develop the approach [1, 2, 6, 8] for our problem. Firstly, we apply the *symplectic projection* onto the solitary manifold to separate the motion along the solitary manifold and in transversal direction. Secondly, we derive the *modulation equations* for the parameters of the symplectic projection, and linearize the transversal dynamics at the projection of the trajectory. The linearized equation is nonautonomous, and this is one of the fundamental difficulties in the proof. This difficulty is handled by the introduction of an autonomous equation (by freezing the time) with an application of the modulation equations to estimate the resulting additional error terms. A principal role in the rest of the proof is played by the uniform decay of the frozen linearized dynamics projected onto the continuous spectrum, and the method of majorants.

The paper is organized as follows. In §2 we describe all nonzero solitary waves and formulate the main theorem. In §3 we enumerate some properties of the linearized equation. In §4 we establish the time decay for the linearized equation in the continuous spectrum. In §5 the modulation equations for the parameters of the soliton are displayed. The decay of the transverse component is proved in §6 and §7. In §8 we obtain the soliton asymptotics (1.7). In Appendix we study the resolvent of linearized equation.

2 Solitary waves and statement of the main theorem

Our main results describe the large time behavior of the global solutions whose existence is guaranteed by the following theorem

Theorem 2.1. [9, Theorem 3.1]

i) Let conditions (1.2) and (1.4) hold. Then for any $\psi_0 \in l^2 = l^2(\mathbb{Z})$ there exist a unique solution $\psi \in C_b(\mathbb{R}, l^2)$ to the equation (1.1) with initial condition $\psi(x, 0) = \psi_0(x)$. ii) The value of energy functional and the norm of solution is conserved:

$$\mathcal{H}(\psi(t)) = \mathcal{H}(\psi_0), \quad \|\psi(t)\| = \|\psi_0\|, \quad t \in \mathbb{R}.$$
(2.1)

In [9] we give a complete analysis of the set of all solitary waves. There exist two different

sets of nonzero solitary waves. The first set S_+ corresponds to $\omega \in (0, \infty)$ and the second set S_- corresponds to $\omega \in (-\infty, -4)$.

Denote by $k(\omega)$ the positive solution of the equation $\cosh k = |\omega + 2|/2$.

Lemma 2.2. [9, Lemma 4.1]) The sets of all nonzero solitary waves is given by

$$S_{+} = \left\{ \psi_{\omega} e^{i\theta} = C e^{i\theta - k(\omega)|x|} : \ \omega \in (0, \infty), \ C > 0, \ \sinh k(\omega) = a(C^{2})/2 > 0, \ \theta \in [0, 2\pi] \right\}$$
$$S_{-} = \left\{ \psi_{\omega} e^{i\theta} = C(-1)^{|x|} e^{i\theta - k(\omega)|x|} : \ \omega \in (-\infty, -4), \ C > 0, \ \sinh k(\omega) = -a(C^{2})/2 > 0, \ \theta \in [0, 2\pi] \right\}$$

Corollary 2.3. The set S_+ resp. S_- is a smooth manifold with the co-ordinates $\theta \in \mathbb{R} \mod 2\pi$ and C > 0 such that $a(C^2) > 0$ resp. $a(C^2) < 0$.

In the case of polynomial F the condition on C means that C is restricted to lie in a set which is a finite union of one-dimensional intervals. The value C = 0 corresponds to the zero function $\psi_{\omega}(x) = 0$ which is always a solitary wave since F(0) = 0, and for $\omega \in [-4, 0]$ only the zero solitary wave exists.

In ([9]) we proved that the parameters θ, ω locally also are smooth coordinates on \mathcal{S}_{\pm} at the points with $a'(C^2) \neq 0$. We will also need the following result from [9].

Lemma 2.4. For C > 0, a > 0, and $a' \neq (4a + a^3)/(4C^2)$ we have

$$\partial_{\omega} \int |\psi_{\omega}(x)|^2 dx \neq 0.$$
(2.2)

The soliton solution is a trajectory $\psi_{\omega(t)}(x)e^{i\theta(t)}$, where the parameters satisfy the equation $\dot{\theta} = \omega$, $\dot{\omega} = 0$. The solitary waves $e^{i\theta}\psi_{\omega}(x)$ map out in time an orbit of the U(1) symmetry group. This group acts on the phase space $l^2(\mathbb{Z})$ preserving the Hamiltonian \mathcal{H} .

The real form of the solitary wave is $e^{j\theta}\Phi_{\omega}$ where $\Phi_{\omega} = (\psi_{\omega}(x), 0)$, and j is the 2 × 2 matrix

$$j = \begin{pmatrix} 0 & -1 \\ 1 & 0 \end{pmatrix}$$
(2.3)

Linearization at the solitary wave $e^{j\theta}\Phi_{\omega}$ leads to the operator (cf. [1, 3])

$$\mathbf{B} = -\Delta_L + \omega - \delta(x)[a(C^2) + 2a'(C^2)C^2P_1] = \begin{pmatrix} \mathbf{D}_1 & 0\\ 0 & \mathbf{D}_2 \end{pmatrix}, \qquad (2.4)$$

where P_1 is the projector in \mathbb{R}^2 acting as $\begin{pmatrix} \chi_1 \\ \chi_2 \end{pmatrix} \mapsto \begin{pmatrix} \chi_1 \\ 0 \end{pmatrix}$,

$$\mathbf{D}_1 = -\Delta_L + \omega - \delta(x)[a + 2a'C^2], \quad \mathbf{D}_2 = -\Delta_L + \omega - \delta(x)a.$$

Let $\mathbf{C} = j^{-1}\mathbf{B}$. We will show in Appendix A that the continuous spectrum of \mathbf{C} coincides with $\mathcal{C}_{-} \cup \mathcal{C}_{+} = [-i(\omega + 4), -i\omega] \cup [i\omega, i(\omega + 4)]$. The point 0 belongs to the discrete spectrum, and the dimension of its invariant subspace is at least 2. If $a' \neq (4a + a^3)/(2C^2)$ then the invariant subspace associated to the eigenvalue $\lambda = 0$ is of dimension exactly 2. We will analyze only the solitary waves with $a' \notin \{0; (4a + a^3)/(2C^2)\}$. We assume also more specific condition

Definition 2.5. We say the solitary wave $\psi_{\omega}(x)e^{i\theta}$, satisfies the spectral condition $\{SP\}$ if 1) $a' \notin \{0; (4a + a^3)/(2C^2)\}$ 2) there is no eigenvalue except $\lambda = 0$.

In Appendix A we give an example when the condition $\{SP\}$ holds. If condition $\{SP\}$ is true for a fixed value ω_0 , it is also true for values ω in a small interval centered at ω_0 . The condition $\{SP\}$ ensures orbital stability of solitary waves.

The functional spaces we are going to consider are the weighted Banach spaces $l^p_{\beta} = l^p_{\beta}(\mathbb{Z})$, $p \in [1, \infty), \beta \in \mathbb{R}$ of complex valued functions with the norm

$$\|u\|_{l^p_{\beta}} = \|(1+|x|)^{\beta}u(x)\|_{l^p}.$$
(2.5)

Let us denote by W(t) the dynamical group of the free Schrödinger equation. Our main theorem is the following:

Theorem 2.6. Let conditions (1.2), and (1.4) hold, $\beta \geq 2$ and $\psi(x,t) \in C(\mathbb{R},l^2)$ be the solution to the equation (1.1) with initial value $\psi_0(x) = \psi(x,0) \in l^2 \cap l^1_\beta$ which is close to a solitary wave $\psi_{\omega_0} e^{i\theta_0}$

$$d := \|\psi_0 - \psi_{\omega_0} e^{i\theta_0}\|_{l^2 \cap l^1_\beta} \ll 1.$$
(2.6)

Assume further that the spectral condition $\{SP\}$ holds for the solitary wave with $\omega = \omega_0$. Then for d sufficiently small the solution admits the following asymptotics:

$$\psi(\cdot, t) = \psi_{\omega_{\pm}} e^{i\omega_{\pm}t} + W(t)\Phi_{\pm} + r_{\pm}(t), \quad t \to \pm \infty,$$
(2.7)

where $\Phi_{\pm} \in l^2(\mathbb{Z})$ are the corresponding asymptotic scattering states, and

$$||r_{\pm}(t)|| = \mathcal{O}(|t|^{-1/2}), \quad t \to \pm \infty.$$
 (2.8)

3 Linearized evolution

In this section we summarize the properties of the linearized evolution which will be needed. The proof of these properties one can find in Appendix A and in [1]. The linearized equation reads

$$\dot{\chi}(x,t) = \mathbf{C}\chi(x,t), \qquad \mathbf{C} := j^{-1}\mathbf{B} = \begin{pmatrix} 0 & \mathbf{D}_2 \\ -\mathbf{D}_1 & 0 \end{pmatrix}.$$
(3.1)

Theorem 2.1 generalizes to the equation (3.1): the equation admits unique solution $\chi(x,t) \in C_b(\mathbb{R}, l^2)$ for every initial function $\chi(x, 0) = \chi_0 \in l^2$. Denote by $e^{\mathbf{C}t}$ the dynamical group of equation (3.1) acting in the space l^2 . Then (2.1) implies that

$$||e^{\mathbf{C}t}\chi_0|| = ||\chi_0||, \quad t \in \mathbb{R}.$$
 (3.2)

The resolvent $\mathbf{R}(\lambda) := (\mathbf{C} - \lambda)^{-1}$ is an integral operator with matrix valued integral kernel (see Appendix A)

$$\mathbf{R}(\lambda, x, y) = \Gamma(\lambda, x, y) + P(\lambda, x, y), \qquad (3.3)$$

where

$$\Gamma(\lambda, x, y) = \begin{pmatrix} \frac{1}{4\sin\theta_{+}} & -\frac{1}{4\sin\theta_{-}} \\ \frac{i}{4\sin\theta_{+}} & \frac{i}{4\sin\theta_{-}} \end{pmatrix} \begin{pmatrix} e^{i\theta_{+}|x-y|} - e^{i\theta_{+}(|x|+|y|)} & -i(e^{i\theta_{+}|x-y|} - e^{i\theta_{+}(|x|+|y|)}) \\ e^{i\theta_{-}|x-y|} - e^{i\theta_{-}(|x|+|y|)} & i(e^{i\theta_{-}|x-y|} - e^{i\theta_{-}(|x|+|y|)}) \end{pmatrix}$$
(3.4)

$$P(\lambda, x, y) = \frac{1}{2D} \begin{pmatrix} e^{i\theta_+|x|} & e^{i\theta_-|x|} \\ ie^{i\theta_+|x|} & -ie^{i\theta_-|x|} \end{pmatrix} \begin{pmatrix} i\alpha - 2\sin\theta_- & i\beta \\ -i\beta & -i\alpha + 2\sin\theta_+ \end{pmatrix} \begin{pmatrix} e^{i\theta_+|y|} & -ie^{i\theta_+|y|} \\ e^{i\theta_-|y|} & ie^{i\theta_-|y|} \end{pmatrix}$$
(3.5)

Here $\theta_{\pm}(\lambda)$ is the root of $2\cos\theta_{\pm} = \omega + 2 \pm i\lambda$ defined with cuts in the complex λ plane so that $\theta_{\pm}(\lambda)$ is analytic on $\mathbb{C} \setminus \mathcal{C}_{\pm}$, and $\operatorname{Im} \theta_{\pm}(\lambda) > 0$ for $\lambda \in \mathbb{C} \setminus \mathcal{C}_{\pm}$. The constants α, β and the determinant $D = D(\lambda)$ are given by the formulas

$$\alpha = a + a'C^2, \ \beta = a'C^2, \ D = 2i\alpha(\sin\theta_+ + \sin\theta_-) - 4\sin\theta_+ \sin\theta_- + \alpha^2 - \beta^2.$$

The poles of the resolvent correspond to the roots of the determinant $D(\lambda)$. If spectral condition $\{SP\}$ holds then the determinant has the only root $\lambda = 0$ with the multiplicity 2.

Observe that (1.6) and its derivative in ω give the following identities:

$$\mathbf{D}_2\psi_\omega = 0 \qquad \mathbf{D}_1(\partial_\omega\psi_\omega) = -\psi_\omega. \tag{3.6}$$

These formulae imply that the vectors $j\Phi_{\omega}$ and $\partial_{\omega}\Phi_{\omega}$ lie in the generalized two dimensional null space X^0 of the non-self-adjoint operator **C** defined in (3.1) and

$$\mathbf{C}j\Phi_{\omega} = 0 \qquad \mathbf{C}\partial_{\omega}\Phi_{\omega} = j\Phi_{\omega}. \tag{3.7}$$

The symplectic form Ω for the real vectors ψ and η is defined by

$$\Omega(\psi,\eta) = \langle \psi, j\eta \rangle = \sum_{\mathbb{Z}} (\psi_1 \eta_2 - \psi_2 \eta_1).$$
(3.8)

By Lemma 2.4

$$\Omega(j\Phi_{\omega},\partial_{\omega}\Phi_{\omega}) = -\frac{1}{2}\partial_{\omega}\int |\psi_{\omega}|^2 dx \neq 0.$$
(3.9)

Hence, the symplectic form Ω is nondegenerate on X^0 , i.e. X^0 is a symplectic subspace. Therefore, there exists a symplectic projection operator \mathbf{P}^0 from l^2 onto X^0 represented by the formula

$$\mathbf{P}^{0}\psi = \frac{1}{\langle \Phi_{\omega}, \partial_{\omega}\Phi_{\omega} \rangle} [\langle \psi, j\partial_{\omega}\Phi_{\omega} \rangle j\Phi_{\omega} + \langle \psi, \Phi_{\omega} \rangle \partial_{\omega}\Phi_{\omega}]$$
(3.10)

Denote by $\mathbf{P}^c = 1 - \mathbf{P}^0$ the symplectic projector onto the continuous spectral subspace.

Remark 3.1. On the generalized null space itself $\mathbf{C}^2 = 0$ by (3.7), and so the semigroup $e^{t\mathbf{C}}$ reduces to $1 + \mathbf{C}t$ as usual for the exponential of the nilpotent part of an operator.

4 Time decay in continuous spectrum

Due to Remark 3.1 we see that the solutions $\chi(t) = e^{\mathbf{C}t}\chi_0$ of the linearized equation (3.1) do not decay as $t \to \infty$ if $\mathbf{P}^0\chi_0 \neq 0$. On the other hand, we do expect time decay of $\mathbf{P}^c\chi(t)$, as a consequence of the Laplace representation for $\mathbf{P}^c e^{\mathbf{C}t}$:

$$\mathbf{P}^{c}e^{\mathbf{C}t} = -\frac{1}{2\pi i} \int_{\mathcal{C}_{+}\cup\mathcal{C}_{-}} e^{\lambda t} (\mathbf{R}(\lambda+0) - \mathbf{R}(\lambda-0)) d\lambda.$$
(4.1)

The decay for the oscillatory integral is obtained from the analytic properties of $\mathbf{R}(\lambda)$ for $\lambda \in \mathcal{C}_+ \cup \mathcal{C}_-$.

In Appendix A we will show that $D(\lambda) \neq 0$ for $\lambda \in \mathcal{C}_+ \cup \mathcal{C}_-$. Clearly in order to understand the decay of $\mathbf{P}^c e^{t\mathbf{C}}$, it is crucial to study the behavior of $\mathbf{R}(\lambda, x, y)$ near the branch points $\lambda = \pm i\omega$ and $\lambda = \pm i(\omega + 4)$ (where $\sin \theta_{\pm}$ vanish).

We deduce time decay for the group $\mathbf{P}^c e^{t\mathbf{C}}$ by means of the following version of Lemma 10.2 from [7], which is itself based on Zygmund's lemma [19, p.45].

Let $\mathcal{F} : [a, b] \to \mathbf{B}$ be a C^2 function with values in a Banach space **B**. Let us define the **B**-valued function

$$I(t) = \int_{b}^{a} e^{-it\nu} \mathcal{F}(\nu) \ d\nu.$$

Lemma 4.1. Suppose that $\mathcal{F}(a) = \mathcal{F}(b) = 0$, and $\mathcal{F}'' \in L^1(a + \delta, b - \delta; \mathbf{B})$ for some $\delta > 0$. Moreover,

$$\mathcal{F}''(a+\zeta), \ \mathcal{F}''(b-\zeta) = \mathcal{O}(\zeta^{p-2}), \quad \zeta \downarrow 0$$

in the norm of **B** for some $p \in (0,1)$. Then $I(t) \in C_b(a + \varepsilon, b - \varepsilon; \mathbf{B})$ for any $\varepsilon > 0$, and

 $I(t) = \mathcal{O}(t^{-1-p})$ as $t \to \infty$ in the norm of **B**.

We will apply Lemma 4.1 to the function $\mathcal{F}(\lambda) = \mathbf{R}(\lambda + 0) - \mathbf{R}(\lambda - 0)$ with values in the Banach space $\mathcal{B} = B(l_{\beta}^1, l_{-\beta}^{\infty})$, the space of continuous linear maps $l_{\beta}^1 \to l_{-\beta}^{\infty}$ for any $\beta \geq 2$.

Theorem 4.2. Assume that the spectral condition $\{SP\}$ holds so that $\lambda = 0$ is the only point in the discrete spectrum of the operator $\mathbf{C} = \mathbf{C}(\omega)$. Then for $\beta \geq 2$

$$\|\mathbf{P}^c e^{\mathbf{C}t}\|_{\mathcal{B}} = \mathcal{O}(t^{-3/2}), \quad t \to \infty.$$
(4.2)

First we use the formulas (4.1) and (3.3) to obtain

$$-2\pi i \mathbf{P}^{c} e^{\mathbf{C}t} = \int_{\mathcal{C}_{+}\cup\mathcal{C}_{-}} e^{\lambda t} (\Gamma(\lambda+0) - \Gamma(\lambda-0)) d\lambda + \int_{\mathcal{C}_{+}\cup\mathcal{C}_{-}} e^{\lambda t} (P(\lambda+0) - P(\lambda-0)) d\lambda \quad (4.3)$$

Next we apply Lemma 4.1 to each summand in the RHS of (4.3) separately. Then Theorem 4.2 immediately follows from the two lemmas below.

Lemma 4.3. If the assumption of Theorem 4.2 hold then

$$\int_{\mathcal{C}_+\cup\mathcal{C}_-} e^{\lambda t} (\Gamma(\lambda+0) - \Gamma(\lambda-0)) \ d\lambda = \mathcal{O}(t^{-3/2}), \quad t \to \infty$$
(4.4)

in the norm \mathcal{B} .

Proof We consider only the integral over C_+ since the integral over C_- can be handled in the same way. The points $\lambda = i\omega$ and $\lambda = i(\omega + 4)$ are the branch points for θ_+ , therefore, if $\lambda \in C_+$ then since θ_- is continuous across C_+

$$\Gamma(\lambda+0) - \Gamma(\lambda-0) = \Gamma^+(\lambda+0) - \Gamma^+(\lambda-0),$$

where Γ^+ is the sum of those terms in Γ which involve θ_+ . Let us consider, for example, Γ_{11}^+ . The expression (3.4) implies for y > 0 that

$$\Gamma_{11}^{+}(\lambda, x, y) = \begin{cases} 0, & x \leq 0, \\\\ \frac{e^{i\theta_{+}y}(e^{-i\theta_{+}x} - e^{i\theta_{+}x})}{4\sin\theta_{+}}, & 0 \leq x \leq y, \\\\ \frac{e^{i\theta_{+}x}(e^{-i\theta_{+}y} - e^{i\theta_{+}y})}{4\sin\theta_{+}}, & x \geq y. \end{cases}$$

For $\lambda \in \mathcal{C}_+$, the root θ_+ is real, and $\theta_+(\lambda + 0) = -\theta_+(\lambda - 0)$. Then, for y > 0,

$$\Gamma_{11}^{+}(\lambda+0,x,y) - \Gamma_{11}^{+}(\lambda-0,x,y) = -\Theta(x)\frac{\sin\theta_{+}|x|\sin\theta_{+}|y|}{\sin\theta_{+}},$$
(4.5)

where $\Theta(x) = 1$ for x > 0 and zero otherwise. Recall that

$$\theta_{+} = \theta_{+}(\nu) = \arccos \frac{\omega + 2 - \nu}{2}, \quad \sin \theta_{+} = \frac{1}{2}\sqrt{(-\omega + \nu)(4 + \omega - \nu)}, \quad \nu = -i\lambda.$$

Let us calculate the second derivative of the function $f(\nu) = \frac{\sin \theta_+ |x| \sin \theta_+ |y|}{\sin \theta_+}$:

$$f''(\nu) = \frac{-2(|x|^2 + |y|^2 - 1)\sin\theta_+ |x|\sin\theta_+ |y| + 4|x||y|\cos\theta_+ |x|\cos\theta_+ |y|}{(-\omega + \nu)^{3/2}(4 + \omega - \nu)^{3/2}} - \frac{8(|x|\cos\theta_+ |x|\sin\theta_+ |y| + |y|\sin\theta_+ |x|\cos\theta_+ |y|)\cos\theta_+}{(-\omega + \nu)^2(4 + \omega - \nu)^2} + \frac{16\sin\theta_+ |x|\sin\theta_+ |y|\cos^2\theta_+}{(-\omega + \nu)^{5/2}(4 + \omega - \nu)^{5/2}} + \left[\frac{|x|\cos\theta_+ |x|\sin\theta_+ |y| + |y|\sin\theta_+ |x|\cos\theta_+ |y|}{(-\omega + \nu)^2(4 + \omega - \nu)^2} - \frac{\sin\theta_+ |x|\sin\theta_+ |y|\cos\theta_+}{(-\omega + \nu)^{5/2}(4 + \omega - \nu)^{5/2}}\right](\omega + 2 - \nu)$$

Since

$$\sin \theta_+ |z| \sim |z| \sqrt{\nu - \omega}, \ \nu \to \omega \quad \text{and} \quad \sin \theta_+ |z| \sim |z| \sqrt{4 + \omega - \nu}, \ \nu \to \omega + 4,$$

then

$$|f''(\nu)| \le \frac{C(1+|x|^2)(1+|y|^2)}{(\nu-\omega)^{3/2}}, \ \omega < \nu < \omega + 1,$$

and

$$|f''(\nu)| \le \frac{C(1+|x|^2)(1+|y|^2)}{(4+\omega-\nu)^{3/2}}, \ \omega+3 < \nu < \omega+4,$$

For y < 0 an identical calculation leads to the same bound. Therefore the operator valued function $\mathcal{F}(\nu) = \Gamma_{11}^+(\lambda + 0) - \Gamma_{11}^+(\lambda - 0)$ satisfies the conditions of Lemma 4.1 with $a = \omega$, $b = 4 + \omega$, p = 1/2 and $\mathbf{B} = \mathcal{B}$.

Next we consider the second summand in the RHS of (4.3).

Lemma 4.4. In the situation of Theorem 4.2

$$\int_{\mathcal{C}_+\cup\mathcal{C}_-} e^{\lambda t} (P(\lambda+0) - P(\lambda-0)) \ d\lambda = \mathcal{O}(t^{-3/2}), \tag{4.6}$$

in the norm \mathcal{B} .

Proof We consider only the integral over C_+ and one component of the matrix P, for example, P_{11} :

$$P_{11}(\lambda, x, y) = \frac{(i\alpha - 2\sin\theta_{-})e^{i\theta_{+}(|x| + |y|)} + (2\sin\theta_{-} - i\alpha)e^{i\theta_{-}(|x| + |y|)} + i\beta(e^{i\theta_{-}|y| + i\theta_{+}|x|} - e^{i\theta_{+}|y| + i\theta_{-}|x|})}{2i\alpha(\sin\theta_{+} + \sin\theta_{-}) - 4\sin\theta_{+}\sin\theta_{-} + \alpha^{2} - \beta^{2}}$$

Denote $\zeta = -\omega - i\lambda$, then $\sin \theta_+ = \sqrt{\zeta}\sqrt{4-\zeta}$, $\sin \theta_- = \sqrt{-2\omega-\zeta}\sqrt{4+2\omega+\zeta}$. The Taylor expansion in $\sqrt{\zeta}$ as $\zeta \to 0$, Im $\zeta \ge 0$ implies

$$P_{11}(i\omega + i\zeta, x, y) = P_0 + P_1(x, y)\zeta^{1/2} + P_2(x, y)\mathcal{O}(\zeta),$$

where $|P_j(x,y)| \leq C_j(1+|x|^j)(1+|y|^j)$, j=1,2. Therefore, if $\lambda = i\omega + i\zeta \in \mathcal{C}_+$ then

$$\mathcal{F}(\omega+\zeta) = P_{11}(i\omega+i\zeta+0) - P_{11}(i\omega+i\zeta-0) = \mathcal{O}(\zeta^{1/2}), \quad \zeta \to 0$$

in the norm of \mathcal{B} . Similarly, differentiating two times the function $P_{11}(\lambda, x, y)$ in λ , we obtain that

$$\mathcal{F}''(\omega+\zeta) = -P''_{11}(i\omega+i\zeta+0) + P''_{11}(i\omega+i\zeta-0) = \mathcal{O}(\zeta^{-3/2}), \quad \zeta \to 0$$

in the norm of \mathcal{B} . In the same way

$$\mathcal{F}''(4+\omega-\zeta) = -P_{11}''(i(4+\omega-\zeta)+0) + P_{11}''(i(4+\omega-\zeta)-0) = \mathcal{O}(\zeta^{-3/2}), \quad \zeta \to 0$$

Therefore, the function $\mathcal{F}(\nu)$, $\nu = -i\lambda$ satisfies the conditions of Lemma 4.1 with p = 1/2 and $\mathbf{B} = \mathcal{B}$.

5 Modulation equations

In this section we present the modulation equations which allow a construction of solutions $\psi(x,t)$ of equation (1.1) close at each time t to a soliton i.e. to one of the functions $\psi_{\omega}(x)$ in the set $S_+ \cup S_-$ described in section 2 with time varying ("modulating") parameters (ω, θ) = ($\omega(t), \theta(t)$). Let us rewrite (1.1) in the real form

$$j\dot{\psi}(x,t) = -\psi''(x,t) - \delta(x)\mathbf{F}(\psi(0,t)), \qquad (5.1)$$

as an equation for $\psi(x,t) \in \mathbb{R}^2$ with $\mathbf{F}(\psi) \in \mathbb{R}^2$ which is the real vector version of $F(\psi) \in \mathbb{C}$. Then $\psi(x,t) = e^{j\theta(t)} \Phi_{\omega(t)}(x)$ is a solution of (5.1) if and only if $\dot{\theta} = \omega$ and $\dot{\omega} = 0$.

We look for a solution to (5.1) in the form

$$\psi(x,t) = e^{j\theta(t)} \left(\Phi_{\omega(t)}(x) + \chi(x,t) \right) = e^{j\theta(t)} \Psi(x,t), \quad \Psi(x,t) = \Phi_{\omega(t)}(x) + \chi(x,t).$$
(5.2)

Since this is a solution of (5.1) as long as $\chi \equiv 0$ and $\dot{\theta} = \omega$ and $\dot{\omega} = 0$ it is natural to look for solutions in which χ is small and

$$\theta(t) = \int_0^t \omega(s)ds + \gamma(t)$$

with γ treated perturbatively. Observe that so far this representation is underdetermined since for any $(\omega(t), \theta(t))$ it just amounts to a definition of χ ; it is made unique by restricting $\chi(t)$ to lie in the image of the projection operator onto the continuous spectrum $\mathbf{P}_t^c = \mathbf{P}^c(\omega(t))$ or equivalently that

$$\mathbf{P}_t^0 \chi(t) = 0, \quad \mathbf{P}_t^0 = \mathbf{P}^0(\omega(t)) = I - \mathbf{P}^c(\omega(t))$$
(5.3)

Now we give a system of *modulation equations* for $\omega(t)$, $\gamma(t)$ which ensure the conditions (5.3) are preserved by the time evolution.

Lemma 5.1. (i) Assume given a solution of (5.1) with regularity as described in Theorem 2.1, which can be written in the form (5.2) -(5.3) with continuously differentiable $\omega(t)$, $\theta(t)$. Then

$$\dot{\chi} = \mathbf{C}\chi - \dot{\omega}\partial_{\omega}\Phi_{\omega} + \dot{\gamma}j^{-1}(\Phi_{\omega} + \chi) + \mathbf{Q}$$
(5.4)

where $\mathbf{Q}(\chi,\omega) = -\delta(x)j^{-1} (\mathbf{F}(\Phi_{\omega} + \chi) - \mathbf{F}(\Phi_{\omega}) - \mathbf{F}'(\Phi_{\omega})\chi)$, and

$$\dot{\omega} = \frac{\langle \mathbf{P}^{0} \mathbf{Q}, \Psi \rangle}{\langle \partial_{\omega} \Phi_{\omega} - \partial_{\omega} \mathbf{P}^{0} \chi, \Psi \rangle}$$
(5.5)

$$\dot{\gamma} = \frac{\langle j \mathbf{P}^0(\partial_\omega \Phi_\omega - \partial_\omega \mathbf{P}^0 \chi), \mathbf{P}^0 \mathbf{Q} \rangle}{\langle \partial_\omega \Phi_\omega - \partial_\omega \mathbf{P}^0 \chi, \Psi \rangle}, \qquad (5.6)$$

where $\mathbf{P}^0 = \mathbf{P}^0(\omega(t))$ is the projection operator defined in (3.10) and $\partial_{\omega}\mathbf{P}^0 = \partial_{\omega}\mathbf{P}^0(\omega)$ evaluated at $\omega = \omega(t)$.

(ii) Conversely given ψ a solution of (5.1) as in Theorem 2.1 and continuously differentiable functions $\omega(t)$, $\theta(t)$ which satisfy (5.5)-(5.6) then χ defined by (5.2) satisfies (5.4) and the condition (5.3) holds at all times if it holds initially.

Proof This can be proved as in [3, Prop.2.2].

It remains to show, for appropriate initial data close to a soliton, that there exist solutions to (5.5)-(5.6), at least locally. To achieve this observe that if the spectral condition $\{SP\}$ holds then by Lemma 2.4 the denominator appearing on the right hand side of (5.5) and (5.6) does not vanish for small $\|\chi\|_{l^3_{\alpha}}$. This is because

$$\langle \partial_{\omega}\psi_{\omega},\psi_{\omega}\rangle = \frac{1}{2}\partial_{\omega}\int |\psi_{\omega}|^2 dx \neq 0$$
(5.7)

as discussed in section 2. This has the consequence that the orthogonality conditions really can be satisfied for small χ because they are equivalent to a locally well posed set of ordinary differential equations for $t \to (\theta(t), \omega(t))$. This implies the following corollary:

Corollary 5.2. (i) In the situation of (i) in the previous lemma assume that (5.7) holds. If $\|\chi\|_{l^p_{\beta}}$ is sufficiently small for some p, β the right hand sides of (5.5) and (5.6) are smooth in θ, ω and there exists continuous $\mathcal{R} = \mathcal{R}(\omega, \chi)$ such that

$$|\dot{\gamma}(t)| \le \mathcal{R}|\chi(0,t)|^2, \qquad |\dot{\omega}(t)| \le \mathcal{R}|\chi(0,t)|^2.$$

(ii) Assume given ψ , a solution of (5.1) as in Theorem 2.1. If ω_0 satisfies (5.7) and $\chi(x,0) = e^{-j\theta_0}\psi(x,0) - \Phi_{\omega_0}(x)$ is small in some l^p_β norm and satisfies (5.3) there is a time interval on which there exist C^1 functions $t \mapsto (\omega(t), \gamma(t))$ which satisfy (5.5)-(5.6).

6 Time decay for the transversal dynamics

Let us represent the initial data ψ_0 in a convenient form for application of the modulation equations: the next Lemma will allow us to assume that (5.3) holds initially without loss of generality.

Lemma 6.1. In the situation of Theorem 2.6 there exists a solitary wave $\psi_{\tilde{\omega}_0}$ satisfying the spectral condition $\{SP\}$ such that in vector form

$$\psi_0(x) = e^{j\theta_0}(\Phi_{\tilde{\omega}_0}(x) + \chi_0(x)), \quad \Phi_{\tilde{\omega}_0} = (\psi_{\tilde{\omega}_0}, 0),$$

and for $\chi_0(x)$ we have

$$\mathbf{P}^0(\tilde{\omega}_0)(\chi_0) = 0, \tag{6.1}$$

and

$$\|\chi_0\|_{l^1_\beta \cap l^2} = \tilde{d} = O(d) \quad as \ d \to 0.$$

Proof This can be proved as in [1, Lemma 10.1] by a standard application of the implicit function theorem.

In Section 8 we will show that our main Theorem 2.6 can be derived from the following time decay of the transversal component $\chi(t)$:

Theorem 6.2. Let all the assumptions of Theorem 2.6 hold. For d sufficiently small there exist C^1 functions $t \mapsto (\omega(t), \gamma(t))$ defined for $t \ge 0$ such that the solution $\psi(x, t)$ of (5.1) can be written as in (5.2-5.3) with (5.5-5.6) satisfied, and there exists a number $\overline{M} > 0$, depending only on the initial data, such that

$$M(T) = \sup_{0 \le t \le T} \left[(1+t)^{3/2} \|\chi(t)\|_{l^{\infty}_{-\beta}} + (1+t)^3 \left(|\dot{\gamma}| + |\dot{\omega}| \right) \| \le \overline{M},$$
(6.2)

uniformly in T > 0, and $\overline{M} = O(d)$ as $d \to 0$.

Remarks 6.3. (0) This theorem will be deduced from Proposition 7.1 in the next section.

(i) Theorem 2.1 implies that the norms in the definition of M are continuous functions of time (and so M is also).

(ii) The result holds also for negative time with appropriate changes since $\psi(x,t)$ solves (1.1) if and only if $\overline{\psi}(x,-t)$ does.

(iii) The result implies in particular that $t^3|\dot{\theta} - \omega| + t^3|\dot{\omega}| \leq C$, hence $\omega(t)$ and $\theta(t) - t\omega_+$ should converge as $t \to \infty$ while $\psi(x, t) - e^{j\theta(t)}\Phi_{\omega(t)}(x)$ have limit zero in $l^{\infty}_{-\beta}(\mathbb{R})$.

7 Proof of transversal decay

7.1 Inductive argument (proof of Theorem 6.2)

Let us write the initial data in the form

$$\psi_0(x) = e^{j\theta_0}(\Phi_{\omega_0}(x) + \chi_0(x)). \tag{7.1}$$

with $d = \|\chi_0\|_{l^1_{\beta} \cap H^1}$ sufficiently small. By Lemma 6.1 we can assume that $\mathbf{P}^0(\omega_0)(\chi_0) = 0$ without loss of generality. Then the local existence asserted in Corollary 5.2 implies the existence of an interval $[0, t_1]$ on which are defined C^1 functions $t \mapsto (\omega(t), \gamma(t))$ satisfying (5.5)-(5.6) and such that $M(t_1) = \rho$ for some $t_1 > 0$ and $\rho > 0$. By continuity we can make ρ as small as we like by making d and t_1 small. The following Proposition is proved in section 7.4 below.

Proposition 7.1. In the situation of Theorem 6.2 let $M(t_1) \leq \rho$ for some $t_1 > 0$ and $\rho > 0$. Then there exist numbers d_1 and ρ_1 , independent of t_1 , such that

$$M(t_1) \le \rho/2 \tag{7.2}$$

if $d = \|\chi_0\|_{L^1_\beta \cap H^1} < d_1$ and $\rho < \rho_1$.

Assuming the truth of Proposition 7.1 for now Theorem 6.2 will follow from the next argument:

Consider the set \mathcal{T} of $t_1 \geq 0$ such that $(\omega(t), \gamma(t))$ are defined on $[0, t_1]$ and $M(t_1) \leq \rho$. This set is relatively closed by continuity. On the other hand, (7.2) and Corollary 5.2 with sufficiently small ρ and d imply that this set is also relatively open, and hence $\sup \mathcal{T} = +\infty$, completing the proof of Theorem 6.2.

7.2 Frozen linearized equation

A crucial part of the proof of Proposition 7.1 is the estimation of the first term in M, for which purpose it is necessary to make use of the dispersive properties obtained in sections 3 and 4. Rather than study directly (5.4), whose linear part is non-autonomous, it is convenient (following [2, 3]) to introduce a small modification of (5.2), which leads to an autonomous linearized equation. This new ansatz for the solution is

$$\psi(x,t) = e^{j\theta} (\Phi_{\omega}(x) + e^{-j(\theta - \tilde{\theta})} \eta), \quad \text{where } \tilde{\theta}(t) = \omega_1 t + \theta_0, \ \theta_0 = \theta_0 \text{ and } \omega_1 = \omega(t_1)$$
(7.3)

so that, $\eta = e^{j(\theta - \tilde{\theta})} \chi$ and $\chi = e^{-j(\theta - \tilde{\theta})} \eta$. Since

$$\dot{\chi} = e^{-j(\theta - \tilde{\theta})} \Big(\dot{\eta} - j(\omega + \dot{\gamma} - \omega_1) \eta \Big)$$

equation (5.4) implies

$$\dot{\eta} = j^{-1}(\omega_1 - \omega)\eta + e^{j(\theta - \tilde{\theta})}\mathbf{C}\left(e^{-j(\theta - \tilde{\theta})}\eta\right) + e^{j(\theta - \tilde{\theta})}\left(j^{-1}\dot{\gamma}\Phi_\omega - \dot{\omega}\partial_\omega\Phi_\omega + \mathbf{Q}[e^{-j(\theta - \tilde{\theta})}\eta]\right).$$
(7.4)

The matrices **C** and $e^{j\phi}$, where $\phi = \theta - \tilde{\theta}$, do not commute:

$$\mathbf{C}e^{j\phi} - e^{j\phi}\mathbf{C} = \delta(x)b\sin\phi\ \sigma, \text{ where } \sigma = \begin{pmatrix} 1 & 0\\ 0 & -1 \end{pmatrix}, \ b = 2a'C^2.$$
(7.5)

Using (7.5) we rewrite equation (7.4) as

$$\dot{\eta} = j^{-1}(\omega_1 - \omega)\eta + \mathbf{C}\eta + e^{j(\theta - \tilde{\theta})} \Big(-\delta(x)b\sin(\theta - \tilde{\theta})\sigma\eta + j^{-1}\dot{\gamma}\Phi_\omega - \dot{\omega}\partial_\omega\Phi_\omega + \mathbf{Q}[e^{-j(\theta - \tilde{\theta})}\eta] \Big).$$

To obtain a perturbed *autonomous* equation we rewrite the first two terms on the RHS by freezing the coefficients at $t = t_1$. Note that

$$j^{-1}(\omega_1 - \omega) + \mathbf{C} = \mathbf{C}_1 - j^{-1}\delta(x)(V - V_1),$$

where $V = a + bP_1$, $V_1 = V(t_1)$, and $C_1 = C(t_1)$. The equation for η now reads

$$\dot{\eta} = \mathbf{C}_1 \eta - j^{-1} \delta(x) (V - V_1) \eta + e^{j(\theta - \tilde{\theta})} \left(-\delta(x) b \sin(\theta - \tilde{\theta}) \sigma \eta + j^{-1} \dot{\gamma} \Phi - \dot{\omega} \partial_\omega \Phi_\omega + \mathbf{Q} [e^{-j(\theta - \tilde{\theta})} \eta] \right)$$
(7.6)

The first term is now independent of t; the idea is that if there is sufficiently rapid convergence of $\omega(t)$ as $t \to \infty$ the other remaining terms are small uniformly with respect to t_1 . Finally the equation (7.6) can be written in the following frozen form

$$\dot{\eta} = \mathbf{C_1}\eta + \mathbf{f_1} \tag{7.7}$$

where

$$\mathbf{f_1} = -j^{-1}\delta(x)(V - V_1)\eta + e^{j(\theta - \tilde{\theta})} \left(-\delta(x)b\sin(\theta - \tilde{\theta})\sigma\eta + j^{-1}\dot{\gamma}\Phi - \dot{\omega}\partial_{\omega}\Phi_{\omega} + \mathbf{Q}[e^{-j(\theta - \tilde{\theta})}\eta] \right)$$
(7.8)

Remark 7.2. The advantage of (7.7) over (5.4) is that it can be treated as a perturbed autonomous linear equation, so that the estimates from section 3 can be used directly. The additional terms in $\mathbf{f_1}$ can be estimated as small uniformly in t_1 : see lemma 7.3 below. This is the reason for introduction of the ansatz (7.3).

Lemma 7.3. In the situation of Proposition 7.1 there exists c > 0, independent of t_1 , such that for $0 \le t \le t_1$

$$|a(t) - a_1| + |b(t) - b_1| + |\theta(t) - \tilde{\theta}(t)| \le c\rho,$$

where

$$\rho := \sup_{0 \le t \le t_1} (1 + t^3) (|\dot{\gamma}(t)| + |\dot{\omega}(t)|) \le M(t_1).$$
(7.9)

Proof By (7.9), we have

$$|a(t) - a(t_1)| = |\int_{t}^{t_1} \dot{a}(\tau)d\tau| \le c \Big(\sup_{0 \le \tau \le t_1} (1 + \tau^2) |\dot{\omega}(\tau)| \Big) \int_{t}^{t_1} \frac{d\tau}{1 + \tau^2} \le c\rho,$$

since $|\dot{a}(\tau)| \leq c|\dot{\omega}(\tau)|$. The difference $|b(t) - b(t_1)|$ can be estimated similarly. Next

$$\theta(t) - \tilde{\theta}(t) = \int_0^t \omega(\tau) d\tau + \gamma(t) - \omega(t_1)t - \gamma(0) = \int_0^t (\omega(\tau) - \omega(t_1)) d\tau + \int_0^t \dot{\gamma}(\tau) d\tau$$
$$= -\int_0^t \int_\tau^{t_1} \dot{\omega}(s) ds d\tau + \int_0^t \dot{\gamma}(\tau) d\tau.$$
(7.10)

By (7.9) the first summand in RHS of (7.10) can be estimated as

$$\begin{split} \int_0^t \int_{t_1}^\tau |\dot{\omega}(s)| ds \, d\tau &\leq \int_0^t \int_{\tau}^{t_1} (1+s)^{2+\varepsilon} |\dot{\omega}(s)| \frac{1}{(1+s)^{2+\varepsilon}} ds \, d\tau \\ &\leq c \sup_{0 \leq s \leq t_1} (1+s)^{2+\varepsilon} |\dot{\omega}(s)| \int_0^t \int_{\tau}^{t_1} \frac{1}{(1+s)^{2+\varepsilon}} ds \, d\tau \leq c\rho \end{split}$$

since the last integral is bounded for $t \in [0, t_1]$. Finally, for the second summand on the RHS of (7.10) inequality (7.9) implies

$$|\int_{0}^{t} \dot{\gamma}(\tau) d\tau| \le c \sup_{0 \le \tau \le t_{1}} (1 + \tau^{2}) |\dot{\gamma}(\tau)| \int_{t}^{t_{1}} \frac{d\tau}{1 + \tau^{2}} \le c\rho$$

7.3 Projection onto discrete and continuous spectral spaces

From sections 3 and 4 we have information concerning $U(t) = e^{\mathbf{C}_1 t}$, in particular decay on the subspace orthogonal to the (two dimensional) generalized null space. It is therefore necessary to introduce a further decomposition to take advantage of this. Recall, by comparing (5.2) and (7.3) that

$$\eta = e^{j(\theta-\theta)}\chi$$
 and $\mathbf{P}_t^0\chi(t) = 0.$ (7.11)

Introduce the symplectic projections $\mathbf{P}_1^0 = \mathbf{P}_{t_1}^0$ and $\mathbf{P}_1^c = \mathbf{P}_{t_1}^c$ onto the discrete and continuous spectral subspaces defined by the operator \mathbf{C}_1 and write, at each time $t \in [0, t_1]$:

$$\eta(t) = g(t) + h(t)$$
(7.12)

with $g(t) = \mathbf{P}_1^0 \eta(t)$ and $h(t) = \mathbf{P}_1^c \eta(t)$. The following lemma shows that it is only necessary to estimate h(t).

Lemma 7.4. In the situation of Proposition 7.1, assume

$$\sup_{0 \le t \le t_1} \left(|\omega(t) - \omega_1| + |\theta(t) - \theta_1(t)| \right) = \Delta$$

is sufficiently small. Then for $0 \le t \le t_1$ there exists $c(\Delta, \omega_1)$ such that

$$c(\Delta,\omega_1)^{-1} \|h\|_{l^{\infty}_{-\beta} \cap l^2} \le \|\eta\|_{l^{\infty}_{-\beta} \cap l^2} \le c(\Delta,\omega_1) \|h\|_{l^{\infty}_{-\beta} \cap l^2}.$$
(7.13)

Proof This can be proved as in [1, Lemma 11.5]

7.4 Proof of Proposition 7.1

To prove Proposition 7.1 we explain how to estimate both terms in M, (6.2), to be $\leq \rho/4$, uniformly in t_1 .

Estimation of the second term in M. As in Corollary 5.2 we have

$$|\dot{\gamma}(t)| + |\dot{\omega}(t)| \le c_0 |\chi(0,t)|^2 \le c_0 \frac{M(t)^2}{(1+|t|)^3}, \quad t \le t_1,$$

since $|\chi(0,t)| \leq ||\chi(t)||_{l_{-\beta}^{\infty}}$. Finally let $\rho_1 < 1/(4c_0)$ to complete the estimate for the second term in M as $\leq \rho/4$.

Estimation of the first term in M. By Lemma 7.4 it is enough to estimate h. Let us apply the projection \mathbf{P}_1^c to both sides of (7.7). Then the equation for h reads

$$\dot{h} = \mathbf{C_1}h + \mathbf{P_1^c}\mathbf{f_1} \tag{7.14}$$

Now to estimate h we use the Duhamel representation:

$$h(t) = U(t)h(0) + \int_0^t U(t-s)\mathbf{P}_1^c \mathbf{f_1}(s)ds, \quad t \le t_1.$$
(7.15)

with $U(t) = e^{\mathbf{C}_1 t}$ the one parameter group just introduced. Recall that $\mathbf{P}_1^0 h(t) = 0$ for $t \in [0, t_1]$. Therefore

$$\|U(t)h(0)\|_{l^{\infty}_{-\beta}} \le c(1+t)^{-3/2} \|h(0)\|_{l^{1}_{\beta} \cap l^{2}} \le c(1+t)^{-3/2} \|\eta(0)\|_{l^{1}_{\beta} \cap l^{2}}.$$
(7.16)

by Theorem 4.2 and inequalities (3.2) and (7.13). Let us estimate the integrand on the righthand side of (7.15). We use the representation (7.8) for $\mathbf{f_1}$ and apply Theorem 4.2, Corollary 5.2 and Lemma 7.3 to obtain that

$$\begin{aligned} \|U(t-s)\mathbf{P}_{1}^{c}\mathbf{f}_{1}\|_{l_{-\beta}^{\infty}} &\leq c(1+t-s)^{-3/2} \|\mathbf{P}_{1}^{c}(\mathbf{f}_{1}(t))\|_{l_{\beta}^{1}} \\ &\leq c(1+t-s)^{-3/2} \left(|\eta(0,t)|^{2} + \rho|\eta(0,t)| \right) \\ &\leq c(1+t-s)^{-3/2} \left(\|\eta(t)\|_{l_{-\beta}^{\infty}}^{2} + \rho\|\eta(t)\|_{l_{-\beta}^{\infty}}^{2} \right), \quad t \leq t_{1}. \end{aligned}$$
(7.17)

Now (7.13), (7.15), (7.16) and (7.17) imply

$$\|\eta(t)\|_{l^{\infty}_{-\beta}} \le c(1+t)^{-3/2} \|\eta(0)\|_{l^{1}_{\beta}\cap l^{2}} + c_{1} \int_{0}^{t} \frac{ds}{(1+t-s)^{3/2}} \left(\|\eta(s)\|_{l^{\infty}_{-\beta}}^{2} + \rho\|\eta(s)\|_{l^{\infty}_{-\beta}}\right)$$

Multiply by $(1+t)^{3/2}$ to deduce

$$(1+t)^{3/2} \|\eta(t)\|_{l^{\infty}_{-\beta}} \le cd + c_1 \int_0^t \frac{(1+t)^{3/2}(1+s)^{-3}}{(1+t-s)^{3/2}} (1+s)^3 \|\eta(s)\|_{l^{\infty}_{-\beta}}^2 ds$$

$$+ c_1 \rho \int_0^t \frac{(1+t)^{3/2}(1+s)^{-3/2}}{(1+t-s)^{3/2}} (1+s)^{3/2} \|\eta(s)\|_{l^{\infty}_{-\beta}} ds$$
(7.18)

since $\|\eta(0)\|_{l^1_{\beta} \cap l^2} \leq d$. Introduce the majorant

$$m(t) := \sup_{[0,t]} (1+s)^{3/2} \|\eta(s)\|_{l^{\infty}_{-\beta}}, \quad t \le t_1$$

and hence

$$m(t) \le cd + c_1 m^2(t) \int_0^t \frac{(1+t)^{3/2} (1+s)^{-3}}{(1+t-s)^{3/2}} \, ds + \rho c_1 m(t) \int_0^t \frac{(1+t)^{3/2} (1+s)^{-3/2}}{(1+t-s)^{3/2}} \, ds. \tag{7.19}$$

It easy to see (by splitting up the integrals into s < t/2 and $s \ge t/2$) that both these integrals are bounded independent of t. Thus (7.19) implies that there exist c, c_2, c_3 , independent of t_1 , such that

$$m(t) \le cd + \rho c_2 m(t) + c_3 m^2(t), \quad t \le t_1.$$

Recall that $m(t_1) \leq \rho \leq \rho_1$ by assumption. Therefore this inequality implies that m(t) is bounded for $t \leq t_1$, and moreover,

$$m(t) \le c_4 d, \quad t \le t_1$$

if d and ρ are sufficiently small. The constant c_4 does not depend on t_1 . We choose d in (2.6) small enough that $d < \rho/(4c_4)$. Therefore,

$$\sup_{[0,t_1]} (1+t)^{3/2} \|\eta(t)\|_{l^{\infty}_{-\beta}} < \rho/4$$

if d and ρ are sufficiently small. This bounds the first term as $\langle \rho/4 \rangle$ by (7.11) and hence $M(t_1) < \rho/2$, completing the proof of Proposition 7.1.

8 Soliton asymptotics

Here we prove our main Theorem 2.6 using the bounds (6.2). For the solution $\psi(x,t)$ to (1.1) let us define the accompanying soliton as $s(x,t) = \psi_{\omega(t)}(x)e^{i\theta(t)}$, where $\dot{\theta}(t) = \omega(t) + \dot{\gamma}(t)$. Then for the difference $z(x,t) = \psi(x,t) - s(x,t)$ we obtain easily from equations (1.1) and (1.6)

$$i\dot{z}(x,t) = -z''(x,t) + \dot{\gamma}s(x,t) - i\dot{\omega}\partial_{\omega}s(x,t) - \delta(x)\Big(F(\psi(0,t)) - F(s(0,t))\Big).$$
(8.1)

Then

$$z(t) = W(t)z(0) + \int_{0}^{t} W(t-\tau)f(\cdot,\tau)d\tau,$$
(8.2)

where $f(x,t) = \dot{\gamma}s(x,t) - i\dot{\omega}\partial_{\omega}s(x,t) - \delta(x)\Big(F(\psi(0,t)) - F(s(0,t))\Big)$, and W(t) is the dynamical group of the free Schrödinger equation. Since $\gamma(t) - \gamma_+$, $\omega(t) - \omega_+ = \mathcal{O}(t^{-2})$, and therefore $\theta(t) - \omega_+ t - \gamma_+ = \mathcal{O}(t^{-1})$ for $t \to \infty$, to establish the asymptotic behavior (2.7) it suffices to prove that

$$z(t) = W(t)\Phi_{+} + r_{+}(t)$$
(8.3)

with some $\Phi_+ \in l^2(\mathbb{Z})$ and $||r_+(t)|| = \mathcal{O}(t^{-1/2})$. Let us rewrite (8.2) as

$$z(t) = W(t) \left(z(0) + \int_{0}^{\infty} W(-\tau) f(\cdot, \tau) d\tau \right) - \int_{0}^{t} W(t-\tau) f(\cdot, \tau) d\tau = W(t) \Phi_{+} + r_{+}(t).$$
(8.4)

Let us recall that by (6.2)

$$|\dot{\omega}(t)| \le c(1+t)^{-3}, \ |\dot{\gamma}(t)| \le c(1+t)^{-3}, \ |F(\psi(0,t)) - F(s(0,t))| \le c|\chi(0,t)| \le c(1+t)^{-3/2}.$$

Hence, the unitarity in l^2 of the group W(t) implies that $\Phi_+ = z(0) + \int_0^\infty W(-\tau)f(\cdot,\tau)d\tau \in l^2$, and $||r_+(t)|| = \mathcal{O}(t^{-1/2}), t \to \infty$.

A The resolvent

A.1 Calculation of the matrix kernel

Here we will construct matrix kernel of the resolvent $\mathbf{R}(\lambda)$ explicitly

$$\mathbf{R}(\lambda, x, y) = \begin{pmatrix} R_{11}(\lambda, x, y) & R_{12}(\lambda, x, y) \\ R_{21}(\lambda, x, y) & R_{22}(\lambda, x, y) \end{pmatrix}$$
(A. 1)

which is the solution to the equation

$$(\mathbf{C} - \lambda)\mathbf{R}(\lambda, x, y) = \delta(x - y) \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}.$$
 (A. 2)

Calculation of first column For the first column $R_I(\lambda, x, y) := \begin{pmatrix} R_{11}(\lambda, x, y) \\ R_{21}(\lambda, x, y) \end{pmatrix}$ of the matrix $\mathbf{R}(\lambda, x, y)$ we obtain

$$(\mathbf{C} - \lambda)R_I(\lambda, x, y) = \delta(x - y) \begin{pmatrix} 1\\ 0 \end{pmatrix}.$$
 (A. 3)

If $x \neq 0$ and $x \neq y$, (A. 3) takes the form

$$\begin{pmatrix} -\lambda & \mathbf{D}_2 \\ -\mathbf{D}_1 & -\lambda \end{pmatrix} R_I(\lambda, x, y) = \begin{pmatrix} -\lambda & -\Delta_L - \omega \\ \Delta_L + \omega & -\lambda \end{pmatrix} R_I(\lambda, x, y) = 0, \quad x \neq 0, \quad x \neq y.$$
(A. 4)

The general solution is a linear combination of exponential solutions of type $e^{i\theta x}v$. Substituting into (A. 4), we get

$$\begin{pmatrix} -\lambda & 2-2\cos\theta + \omega \\ -2+2\cos\theta - \omega & -\lambda \end{pmatrix} v = 0.$$
 (A. 5)

For nonzero vectors v, the determinant of the matrix vanishes,

$$\lambda^2 + (2 - 2\cos\theta + \omega)^2 = 0.$$

Finally, we obtain four roots $\pm \theta_{\pm}(\lambda)$ in $D := -\pi \leq \operatorname{Re} \theta \leq \pi$ with

$$2 - 2\cos\theta_{\pm}(\lambda) = -\omega \mp i\lambda. \tag{A. 6}$$

We choose the cuts in the complex plane λ :

the cut $\mathcal{C}_+ := [i\omega, i(\omega + 4)]$ for $\theta_+(\lambda)$ and the cut $\mathcal{C}_- := [-i(\omega + 4), -i\omega]$ for $\theta_-(\lambda)$ and

Im
$$\theta_{\pm}(\lambda) > 0, \qquad \lambda \in \mathbb{C} \setminus \mathcal{C}_{\pm}.$$
 (A. 7)

It remains to derive the vector $v = (v_1, v_2)$ which is solution to (A. 5):

$$v_2 = -\frac{2 - 2\cos\theta_{\pm} + \omega}{\lambda}v_1 = \frac{\pm i\lambda}{\lambda}v_1 = \pm iv_1$$

Therefore, we have two corresponding vectors $v_{\pm} = \begin{pmatrix} 1 \\ \pm i \end{pmatrix}$ and we get four linearly independent exponential solutions $v_{\pm}e^{\pm i\theta_{\pm}x}$ and $v_{\pm}e^{\pm i\theta_{\pm}x}$.

Now we can solve the equation (A. 3). First we rewrite it using the representation (3.1) for the operator \mathbf{C} ,

$$\begin{pmatrix} -\lambda & -\Delta_L + \omega \\ \Delta_L - \omega & -\lambda \end{pmatrix} \begin{pmatrix} R_{11}(\lambda, x, y) \\ R_{21}(\lambda, x, y) \end{pmatrix} = \delta(x-y) \begin{pmatrix} 1 \\ 0 \end{pmatrix} + \delta(x) \begin{pmatrix} 0 & a \\ -a-b & 0 \end{pmatrix} \begin{pmatrix} R_{11}(\lambda, 0, y) \\ R_{21}(\lambda, 0, y) \end{pmatrix}$$
(A. 8)

Let us consider y > 0 for the concreteness. Then the RHS vanishes in the open intervals $(-\infty, 0), (0, y)$ and (y, ∞) . Hence, for the parameter λ outside the cuts C_{\pm} , the solution admits the representation

$$R_{I}(\lambda, x, y) = \begin{cases} A_{+}e^{-i\theta_{+}x}v_{+} + A_{-}e^{-i\theta_{-}x}v_{-}, & x < 0, \\ B_{+}^{-}e^{-i\theta_{+}x}v_{+} + B_{-}^{-}e^{-i\theta_{-}x}v_{-} + B_{+}^{+}e^{i\theta_{+}x}v_{+} + B_{-}^{+}e^{i\theta_{-}x}v_{-}, & 0 < x < y, \\ C_{+}e^{i\theta_{+}x}v_{+} + C_{-}e^{i\theta_{-}x}v_{-}, & x > y \end{cases}$$
(A. 9)

since by (A. 7), the exponent $e^{-i\theta_{\pm}x}$ decays for $x \to -\infty$, and similarly, $e^{i\theta_{\pm}x}$ decays for $x \to \infty$. Next we need eight equations to calculate the eight constants A_+, \ldots, C_- . We have two continuity equations and two jump conditions for the derivatives at the points x = 0 and x = y. These four vector equations give just eight scalar equations for the calculation. **Continuity at** x = y: $R_I(y - 0, y) = R_I(y + 0, y)$, i.e.

$$B_{-}^{-}v_{+}/e_{+} + B_{-}^{-}v_{-}/e_{-} + B_{+}^{+}v_{+}e_{+} + B_{-}^{+}v_{-}e_{-} = C_{+}v_{+}e_{+} + C_{-}v_{-}e_{-},$$

where $e_{\pm} := e^{i\theta_{\pm}y}$. It is equivalent to

$$\begin{cases} B_{+}^{-}/e_{+} + B_{+}^{+}e_{+} = C_{+}e_{+}, \\ B_{-}^{-}/e_{-} + B_{-}^{+}e_{-} = C_{-}e_{-}. \end{cases}$$
(A. 10)

Continuity at x = 0: $R_I(-0, y) = R_I(+0, y)$, i.e.

$$A_{+}v_{+} + A_{-}v_{-} = B_{+}^{-}v_{+} + B_{-}^{-}v_{-} + B_{+}^{+}v_{+} + B_{-}^{+}v_{-}$$

that is equivalent to

$$\begin{cases}
A_{+} = B_{+}^{-} + B_{+}^{+}, \\
A_{-} = B_{-}^{-} + B_{-}^{+}.
\end{cases}$$
(A. 11)

"Jump" at x = y: Noting that

$$\begin{pmatrix} 1\\0 \end{pmatrix} = \frac{v_+ + v_-}{2}.$$
 (A. 12)

At x = y equation (A. 8) reads

$$\begin{cases} -\lambda C_{+}e_{+} - iB_{+}^{-}e^{i\theta_{+}}/e_{+} - iB_{+}^{+}e^{-i\theta_{+}}e_{+} - iC_{+}e_{+}e^{i\theta_{+}} + (2+\omega)iC_{+}e_{+} = 1/2, \\ -\lambda C_{-}e_{-} + iB_{-}^{-}e^{i\theta_{-}}/e_{-} + iB_{-}^{+}e^{-i\theta_{-}}e_{-} + iC_{-}e_{-}e^{i\theta_{-}} - (2+\omega)iC_{-}e_{-} = 1/2. \end{cases}$$
(A. 13)

Also we need equation (A. 8) at x = y + 1:

$$\begin{cases} -\lambda C_{+}e^{i\theta_{+}(y+1)} - iC_{+}e^{i\theta_{+}y} - iC_{+}e^{i\theta_{+}(y+2)} + (2+\omega)iC_{+}e^{i\theta_{+}(y+1)} = 0, \\ -\lambda C_{-}e^{i\theta_{-}(y+1)} + iC_{-}e^{i\theta_{-}y} + iC_{-}e^{i\theta_{-}(y+2)} - (2+\omega)iC_{-}e^{i\theta_{-}(y+1)} = 0. \end{cases}$$

Hence

$$\begin{cases} -\lambda C_{+} - iC_{+}e^{i\theta_{+}} + (2+\omega)iC_{+} = iC_{+}e^{-i\theta_{+}}, \\ -\lambda C_{-} + iC_{-}e^{i\theta_{-}} - (2+\omega)iC_{-} = -iC_{-}e^{-i\theta_{-}}. \end{cases}$$
(A. 14)

Combining (A. 13) and (A. 14), we get

$$\begin{cases} -iB_{+}^{-}e^{i\theta_{+}}/e_{+} - iB_{+}^{+}e^{-i\theta_{+}}e_{+} + iC_{+}e_{+}e^{-i\theta_{+}} = 1/2, \\ iB_{-}^{-}e^{i\theta_{-}}/e_{-} + iB_{-}^{+}e^{-i\theta_{-}}e_{-} - iC_{-}e_{-}e^{-i\theta_{-}} = 1/2. \end{cases}$$

After substituting of C_{\pm} from (A. 10), the constants B_{\pm}^{+} cancel and we get

$$B_{+}^{-}\frac{i}{e_{+}}(-e^{i\theta_{+}} + e^{-i\theta_{+}}) = 1/2, \quad B_{-}^{-}\frac{i}{e_{-}}(e^{i\theta_{-}} - e^{-i\theta_{-}}) = 1/2$$

and then

$$B_{+}^{-} = \frac{e_{+}}{4\sin\theta_{+}}, \qquad \qquad B_{-}^{-} = -\frac{e_{-}}{4\sin\theta_{-}}.$$
 (A. 15)

"Jump" at x = 0: Noting that

$$\begin{pmatrix} 0 & a \\ -a-b & 0 \end{pmatrix} v_{+} = \begin{pmatrix} ia \\ -a-b \end{pmatrix} = iv_{+}(a+\frac{b}{2}) - iv_{-}\frac{b}{2} = iv_{+}\alpha - iv_{-}\beta,$$
$$\begin{pmatrix} 0 & a \\ -a-b & 0 \end{pmatrix} v_{-} = \begin{pmatrix} -ia \\ -a-b \end{pmatrix} = iv_{+}\frac{b}{2} - iv_{-}(a+\frac{b}{2}) = iv_{+}\beta - iv_{-}\alpha,$$

where $\alpha = a + \frac{b}{2}$, $\beta = \frac{b}{2}$. Hence,

$$\begin{pmatrix} 0 & a \\ -a-b & 0 \end{pmatrix} (A_{+}v_{+} + A_{-}v_{-}) = iv_{+}(A_{+}\alpha + A_{-}\beta) - iv_{-}(A_{+}\beta + A_{-}\alpha)$$

At x = 0 equation (A. 8) reads

$$\begin{cases} -\lambda A_{+} - iA_{+}e^{i\theta_{+}} - iB_{+}^{-}e^{-i\theta_{+}} - iB_{+}^{+}e^{i\theta_{+}} + (2+\omega)iA_{+} = i(A_{+}\alpha + A_{-}\beta), \\ -\lambda A_{-} + iA_{-}e^{i\theta_{-}} + iB_{-}^{-}e^{-i\theta_{+}} + iB_{-}^{+}e^{i\theta_{-}} - (2+\omega)iA_{-} = -i(A_{+}\beta + A_{-}\alpha) \end{cases}$$
(A. 16)

Also we need equation (A. 8) at x = y + 1:

$$\begin{cases} -\lambda A_{+}e^{i\theta_{+}} - iA_{+} - iA_{+}e^{2i\theta_{+}} + (2+\omega)iA_{+}e^{i\theta_{+}} = 0, \\ -\lambda A_{-}e^{i\theta_{-}} + iA_{-} + iA_{-}e^{2i\theta_{-}} - (2+\omega)iA_{-}e^{i\theta_{-}} = 0. \end{cases}$$

Therefore

$$\begin{cases} -\lambda A_{+} - iA_{+}e^{-i\theta_{+}} - iA_{+}e^{i\theta_{+}} + (2+\omega)iA_{+} = 0, \\ -\lambda A_{-} + iA_{-}e^{-i\theta_{-}} + iA_{-}e^{i\theta_{-}} - (2+\omega)iA_{-} = 0. \end{cases}$$
(A. 17)

Substituting (A. 17) into (A. 16) we get

$$\begin{cases} -iB_{+}^{-}e^{-i\theta_{+}} - iB_{+}^{+}e^{i\theta_{+}} + iA_{+}e^{-i\theta_{+}} = i(A_{+}\alpha + A_{-}\beta), \\ iB_{-}^{-}e^{-i\theta_{+}} + iB_{-}^{+}e^{i\theta_{-}} - iA_{-}e^{-i\theta_{-}} = -i(A_{+}\beta + A_{-}\alpha) \end{cases}$$

Substituting here (A. 11), we get after cancellations,

$$\begin{cases} (e^{i\theta_{+}} - e^{-i\theta_{+}} + \alpha)B_{+}^{+} + \beta B_{-}^{+} = -\alpha B_{+}^{-} - \beta B_{-}^{-} \\ \beta B_{+}^{+} + (e^{i\theta_{-}} - e^{-i\theta_{-}} + \alpha)B_{-}^{+} = -\beta B_{+}^{-} - \alpha B_{-}^{-} \end{cases}$$

Hence, the solution is given by

$$\begin{pmatrix} B_{+}^{+} \\ B_{-}^{+} \end{pmatrix} = -\frac{1}{D} \begin{pmatrix} 2i\sin\theta_{-} + \alpha & -\beta \\ -\beta & 2i\sin\theta_{+} + \alpha \end{pmatrix} \begin{pmatrix} \alpha & \beta \\ \beta & \alpha \end{pmatrix} \begin{pmatrix} B_{+}^{-} \\ B_{-}^{-} \end{pmatrix}, \quad (A. 18)$$

where D is the determinant

$$D := (2i\sin\theta_+ + \alpha)(2i\sin\theta_- + \alpha) - \beta^2, \qquad (A. 19)$$

and B_{+}^{-}, B_{-}^{-} are given by (A. 15). The formulas (A. 15) and (A. 18) imply

$$B_{+}^{+} = \frac{1}{2D} \left(-\frac{2i\alpha\sin\theta_{-} + \alpha^{2} - \beta^{2}}{2\sin\theta_{+}} e_{+} + i\beta e_{-} \right), \quad B_{-}^{+} = \frac{1}{2D} \left(-i\beta e_{+} + \frac{2i\alpha\sin\theta_{+} + \alpha^{2} - \beta^{2}}{2\sin\theta_{-}} e_{-} \right)$$
(A. 20)

Using the identities

$$2i\alpha\sin\theta_{-} + \alpha^{2} - \beta^{2} = D - 2i\alpha\sin\theta_{+} + 4\sin\theta_{+}\sin\theta_{-},$$

$$2i\alpha\sin\theta_{+} + \alpha^{2} - \beta^{2} = D - 2i\alpha\sin\theta_{-} + 4\sin\theta_{+}\sin\theta_{-},$$

let us rewrite (A. 20) as

$$B_{+}^{+} = -\frac{e_{+}}{4\sin\theta_{+}} + \frac{1}{2D} \Big((i\alpha - 2\sin\theta_{-})e_{+} + i\beta e_{-} \Big), \quad B_{-}^{+} = \frac{e_{-}}{4\sin\theta_{-}} - \frac{1}{2D} \Big(i\beta e_{+} + (i\alpha - 2\sin\theta_{+})e_{-} \Big).$$
(A. 21)

Finally, the formulas (A. 9)–(A. 11), (A. 15) and (A. 21) give the first column $R_I(\lambda, x, y)$ of the resolvent for y > 0:

$$R_I(\lambda, x, y) = \Gamma_I(\lambda, x, y) + P_I(\lambda, x, y), \qquad (A. 22)$$

where

$$\Gamma_I(\lambda, x, y) = \frac{1}{4\sin\theta_+} (e^{i\theta_+|x-y|} - e^{i\theta_+(|x|+|y|)})v_+ - \frac{1}{4\sin\theta_-} (e^{i\theta_-|x-y|} - e^{i\theta_-(|x|+|y|)})v_-, \quad (A. 23)$$

and

$$P_{I}(\lambda, x, y) = \frac{1}{2D} \Big[\Big((i\alpha - 2\sin\theta_{-})e^{i\theta_{+}(|x|+|y|)} + i\beta e^{i(\theta_{+}|x|+\theta_{-}|y|)} \Big) v_{+}$$

$$- \Big(i\beta e^{i(\theta_{-}|x|+\theta_{+}|y|)} + (i\alpha - 2\sin\theta_{+})e^{i\theta_{-}(|x|+|y|)} \Big) v_{-} \Big]$$
(A. 24)

Calculation of second column The second column is given by similar formulas with the vector $\begin{pmatrix} 0\\1 \end{pmatrix}$ instead of $\begin{pmatrix} 1\\0 \end{pmatrix}$ in (A. 8). Respectively, (A. 12) is changed by $\begin{pmatrix} 0\\1 \end{pmatrix} = i \frac{v_- - v_+}{2}.$

Hence, we have now change 1/2 by -i/2 in the first equation of (A. 10) and 1/2 by i/2 in the second one. Respectively, (A. 15) for the second column reads

$$B_{+}^{-} = -\frac{ie_{+}}{4\sin\theta_{+}}, \qquad \qquad B_{-}^{-} = -\frac{ie_{-}}{4\sin\theta_{-}}$$

Then the second column $R_{II}(\lambda, x, y)$ of the resolvent reads:

$$R_{II}(\lambda, x, y) = \Gamma_{II}(\lambda, x, y) + P_{II}(\lambda, x, y), \qquad (A. 25)$$

where

$$\Gamma_{II}(\lambda, x, y) = -\frac{i}{4\sin\theta_+} (e^{i\theta_+|x-y|} - e^{i\theta_+(|x|+|y|)})v_+ - \frac{i}{4\sin\theta_-} (e^{i\theta_-|x-y|} - e^{i\theta_-(|x|+|y|)})v_-, \quad (A. 26)$$

and

$$P_{II}(\lambda, x, y) = \frac{i}{2D} \Big[\Big(-(i\alpha - 2\sin\theta_{-})e^{i\theta_{+}(|x|+|y|)} + i\beta e^{i(\theta_{+}|x|+\theta_{-}|y|)} \Big) v_{+} + \Big(i\beta e^{i(\theta_{-}|x|+\theta_{+}|y|)} - (i\alpha - 2\sin\theta_{+})e^{i\theta_{-}(|x|+|y|)} \Big) v_{-} \Big]$$
(A. 27)

Note, that if y < 0 we get the same formulas.

A.2 The poles of the resolvent

The poles of the resolvent correspond to the roots of the determinant (A. 19),

$$D(\lambda) := \alpha^2 + 2i\alpha(\sin\theta_+ + \sin\theta_-) - 4\sin\theta_+ \sin\theta_- - \beta^2 = 0.$$
 (A. 28)

with θ_{\pm} as in (A. 6)-(A. 7). Thus $D(\lambda)$ is an analytic function on $\mathbb{C} \setminus \mathcal{C}_{-} \cup \mathcal{C}_{+}$. Since there are two possible values for the square roots in θ_{\pm} there is a corresponding four-sheeted function $\tilde{D}(\lambda)$ analytic on a four sheeted cover of \mathbb{C} which is branched over \mathcal{C}_{-} and \mathcal{C}_{+} . We call the sheet defined by (A. 7) the *physical sheet*.

We will reduce the equation (A. 28) to the solution of two successive quadratic equations. These can be solved explicitly but the process involves squaring and thus actually produces zeros of the function $\tilde{D}(\lambda)$ rather than of $D(\lambda)$. Therefore we will then have to check whether or not the roots do actually lie on the physical sheet.

Proposition A.1. If $a' = (4a + a^3)/4C^2$ then $\lambda = 0$ is a root of the determinant $D(\lambda)$ with multiplicity 4, otherwise $\lambda = 0$ is a root of the determinant $D(\lambda)$ with multiplicity 2.

Proof First let us check that $\lambda = 0$ is a root of $D(\lambda)$. Let us represent ω by means of $a = a(C^2)$. By results of §2

$$\cosh k = \frac{|\omega+2|}{2}, \quad \sinh k = \frac{|a|}{2}$$

Therefore

$$(\omega + 2)^2 = 4 + a^2.$$

$$D(0) = \alpha^2 - \beta^2 + 2i\alpha ia + a^2 = (a + b/2)^2 - b^2/4 - 2(a + b/2)a + a^2 = 0$$
(A. 29)

since

$$\sin \theta_{\pm} = \sqrt{1 - (\omega + 2)^2/4} = \sqrt{1 - (4 + a^2)/4} = \sqrt{-a^2/4} = ia/2.$$

Now let us compute $D'(\lambda)$:

$$D'(\lambda) = i\alpha \left(\frac{-i(\omega+2+i\lambda)}{\sqrt{4-(\omega+2+i\lambda)^2}} + \frac{i(\omega+2-i\lambda)}{\sqrt{4-(\omega+2-i\lambda)^2}}\right) + \frac{i(\omega+2+i\lambda)\sqrt{4-(\omega+2-i\lambda)^2}}{\sqrt{4-(\omega+2+i\lambda)^2}} - \frac{i(\omega+2-i\lambda)\sqrt{4-(\omega+2+i\lambda)^2}}{\sqrt{4-(\omega+2-i\lambda)^2}}.$$

Hence D'(0) = 0 and $\lambda = 0$ is the root of $D(\lambda)$ of multiplicity at least 2. Further calculation shows that the Taylor series for D near zero takes the form:

$$D(\lambda) = \frac{8a + 2a^3 - 4b}{a^3}\lambda^2 + O(\lambda^4).$$
 (A. 30)

Therefore $\lambda = 0$ is the root of $D(\lambda)$ of multiplicity 4 if and only if $b = (4a + a^3)/2$, i.e. $a' = (4a + a^3)/4C^2$.

Now we prove that there exist a values of $a'C^2 = f(a)$ such that the only root of $D(\lambda)$ is $\lambda = 0$ with multiplicity 2.

Proposition A.2. If $a' = -a/C^2$, then the only root of $D(\lambda)$ is $\lambda = 0$ with multiplicity 2.

Proof One has b = -2a, $\alpha = a + \frac{b}{2} = 0$ and then equation (A. 28) implies

$$\sin \theta_{+} \sin \theta_{-} = -\beta^{2}/4 = -a^{2}/4 < 0.$$
 (A. 31)

From the other hand, by (A. 29) we get

$$\sin^{2} \theta_{+} \sin^{2} \theta_{-} = \left(1 - \frac{(\omega + 2 + i\lambda)^{2}}{4}\right) \left(1 - \frac{(\omega + 2 - i\lambda)^{2}}{4}\right)$$
(A. 32)
$$= \left(1 - \frac{(\omega + 2)^{2}}{4} + \frac{\lambda^{2}}{4}\right)^{2} + \frac{(\omega + 2)^{2}\lambda^{2}}{4} = \left(-\frac{a^{2}}{4} + \frac{\lambda^{2}}{4}\right)^{2} + \lambda^{2} + \frac{a^{2}\lambda^{2}}{4}$$

Hence, (A. 31) and (A. 32) imply

$$\frac{a^4}{16} = \left(-\frac{a^2}{4} + \frac{\lambda^2}{4}\right)^2 + \lambda^2 + \frac{a^2\lambda^2}{4}$$

Hence

$$\lambda^2(\lambda^2 + 2a^2 + 16) = 0$$

It remains to check that the roots $\lambda = \pm i\sqrt{2a^2 + 16}$ don't lie on the physical branch. Let $\theta_+ = x_+ + iy_+$, $\theta_- = x_- + iy_-$ with $y_{\pm} > 0$. Then

$$\cos \theta_{+} = \cos x_{+} \cosh y_{+} - i \sin x_{+} \sinh y_{+} = \frac{\omega + 2 + \sqrt{2a^{2} + 16}}{2} = \frac{\sqrt{a^{2} + 4} + \sqrt{2a^{2} + 16}}{2} > 0,$$
$$\cos \theta_{-} = \cos x_{-} \cosh y_{-} - i \sin x_{-} \sinh y_{-} = \frac{\omega + 2 - \sqrt{2a^{2} + 16}}{2} = \frac{\sqrt{a^{2} + 4} - \sqrt{2a^{2} + 16}}{2} < 0.$$
Hence, $x_{+} = 0, x_{-} = \pi$ and

$$\sin \theta_{+} = \sin(iy_{+}) = i \sinh y_{+}, \quad \sin \theta_{-} = \sin(\pi + iy_{-}) = -i \sinh y_{-}$$

Finally we obtain that $\sin \theta_+ \sin \theta_- = \sinh y_+ \sinh y_- > 0$, which contradict (A. 31).

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