

3.20pt

Overview on geometries of shape spaces, diffeomorphism groups, and spaces of Riemannian metrics

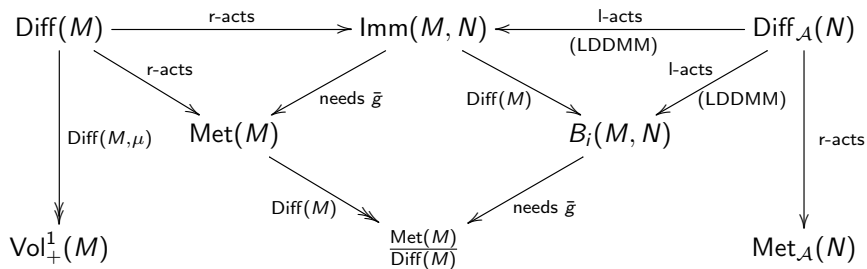
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Based on collaborations with: D. Mumford, M. Bauer,
M. Bruveris, P. Harms

The diagram



$$\text{Met}(M) = \Gamma(S_+^2 T^* N)$$

\bar{g}

$\text{Diff}(M)$

$\text{Diff}_{\mathcal{A}}(N), \mathcal{A} \in \{H^\infty, \mathcal{S}, c\}$

$\text{Imm}(M, N)$

$B_i(M, N) = \text{Imm}/\text{Diff}(M)$

$\text{Vol}_+^1(M) \subset \Gamma(\text{vol}(M))$

space of all Riemann metrics on M

one Riemann metric on N

Lie group of all diffeos on compact mf M

Lie group of diffeos of decay \mathcal{A} to Id_N

mf of all immersions $M \rightarrow N$

shape space

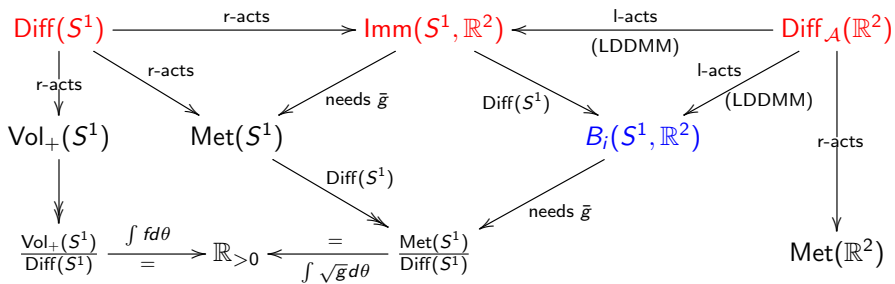
space of positive smooth probability densities

$$\text{Emb}(M, N) \rightarrow \text{Emb}(M, N)/\text{Diff}(M) = B(M, N)$$

is a smooth principal fiber bundle with structure group $\text{Diff}(M)$; $B(M, N)$ is the smooth manifold of submanifolds of N of type M .

The right action of $\text{Diff}(M)$ on $\text{Imm}(M, N)$ is not free; each isotropy group is a finite group [Cervera, Mascaro, Michor, 1991] and thus the quotient $\text{Imm}(M, N)/\text{Diff}(M) = B_i(M, N)$ is an honest orbifold, albeit infinite dimensional.

The right action of $\text{Diff}(M)$ on $\text{Met}(M)$ is not free; each isotropy group is a finite dimensional Lie group (compact for compact M). The quotient $\text{Met}(M)/\text{Diff}(M)$ is a stratified space, the 'true' phase space for Einstein's equation, sometimes called 'superspace', [Ebin] [Ebin, Marsden].



$\text{Diff}(S^1)$

$\text{Diff}_{\mathcal{A}}(\mathbb{R}^2)$, $\mathcal{A} \in \{\mathcal{B}, H^\infty, \mathcal{S}, c\}$

$\text{Imm}(S^1, \mathbb{R}^2)$

$B_i(S^1, \mathbb{R}^2) = \text{Imm}/\text{Diff}(S^1)$

$\text{Vol}_+(S^1) = \{f d\theta : f \in C^\infty(S^1, \mathbb{R}_{>0})\}$

$\text{Met}(S^1) = \{g d\theta^2 : g \in C^\infty(S^1, \mathbb{R}_{>0})\}$

Lie group of all diffeos on compact mf S^1

Lie group of diffeos of decay \mathcal{A} to $\text{Id}_{\mathbb{R}^2}$

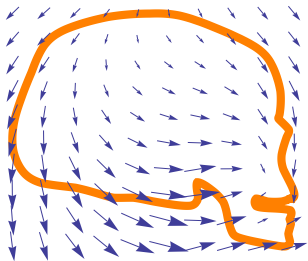
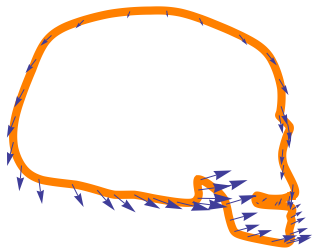
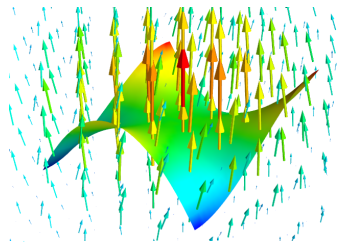
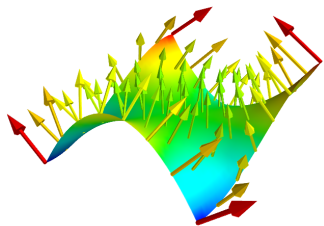
mf of all immersions $S^1 \rightarrow \mathbb{R}^2$

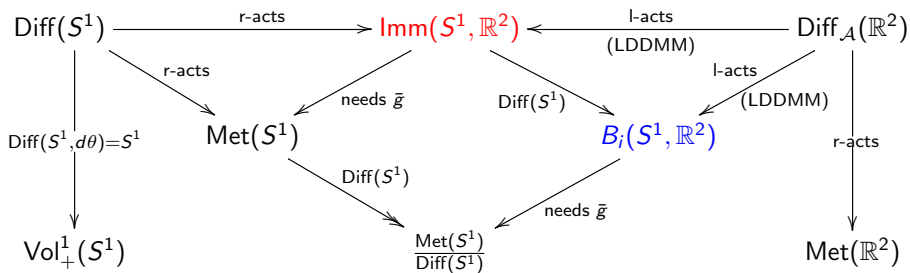
shape space

space of positive smooth probability densities

space of metrics on S^1

Inner versus Outer





The manifold of immersions

Let M be either S^1 or $[0, 2\pi]$.

$$\text{Imm}(M, \mathbb{R}^2) := \{c \in C^\infty(M, \mathbb{R}^2) : c'(\theta) \neq 0\} \subset C^\infty(M, \mathbb{R}^2).$$

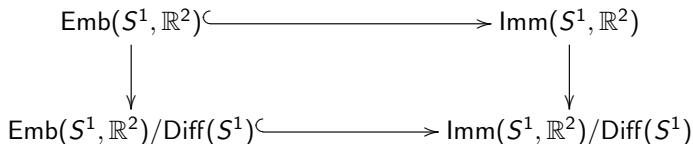
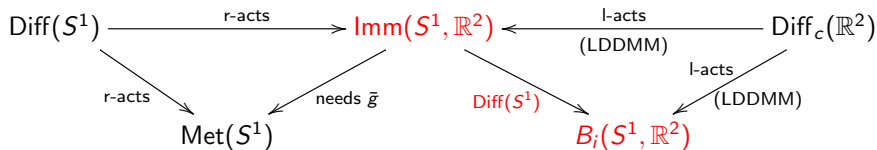
The tangent space of $\text{Imm}(M, \mathbb{R}^2)$ at a curve c is the set of all vector fields along c :

$$T_c \text{Imm}(M, \mathbb{R}^2) = \left\{ h : \begin{array}{ccc} & & T\mathbb{R}^2 \\ & \nearrow h & \downarrow \pi \\ M & \xrightarrow{c} & \mathbb{R}^2 \end{array} \right\} \cong \{h \in C^\infty(M, \mathbb{R}^2)\}$$

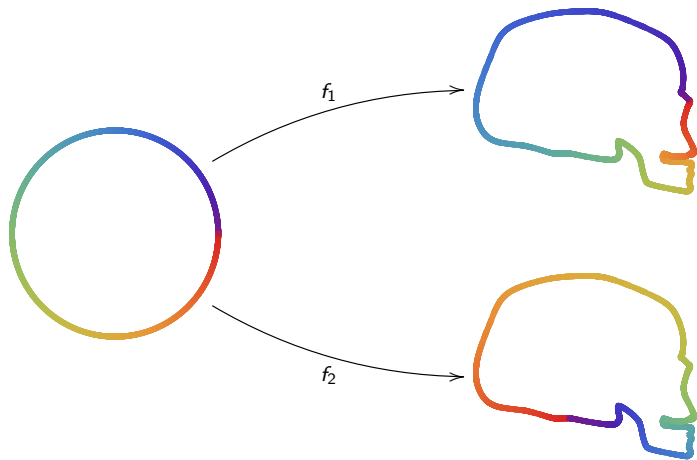
Some Notation:

$$v(\theta) = \frac{c'(\theta)}{|c'(\theta)|}, \quad n(\theta) = iv(\theta), \quad ds = |c'(\theta)|d\theta, \quad Ds = \frac{1}{|c'(\theta)|}d\theta$$

Need for invariance



Different parameterizations



$$f_1, f_2 : S^1 \rightarrow \mathbb{R}^2, \quad f_1 = f_2 \circ \varphi, \quad \varphi \in \text{Diff}(S^1)$$

Inducing a metric on shape space

$$\begin{array}{c} \text{Imm}(M, \mathbb{R}^2) \\ \downarrow \pi \\ B_i := \text{Imm}(M, \mathbb{R}^2) / \text{Diff}(M) \end{array}$$

Every $\text{Diff}(M)$ -invariant metric "above" induces a unique metric "below" such that π is a Riemannian submersion.

The vertical and horizontal bundle

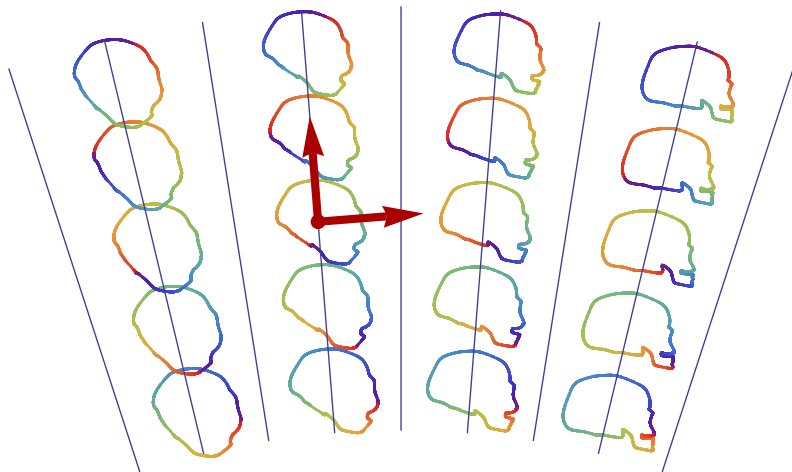
- ▶ $T \text{Imm} = \text{Vert} \oplus \text{Hor}$.
- ▶ The vertical bundle is

$$\text{Vert} := \ker T\pi \subset T \text{Imm}.$$

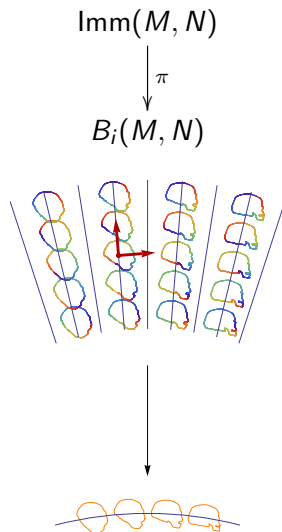
- ▶ The horizontal bundle is

$$\text{Hor} := (\ker T\pi)^{\perp, G} \subset T \text{Imm}.$$

The vertical and horizontal bundle



Definition of a Riemannian metric



1. Define a $\text{Diff}(M)$ -invariant metric G on Imm .
2. Then $T\pi$ restricted to the horizontal space yields an isomorphism

$$(\ker T_f \pi)^{\perp, G} \cong T_{\pi(f)} B_i.$$

3. Define a metric on B_i such that

$$(\ker T_f \pi)^{\perp, G} \cong T_{\pi(f)} B_i$$

is an isometry.

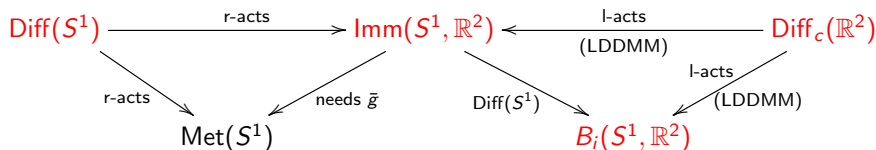
$$\begin{array}{c} \text{Imm}(M, \mathbb{R}^2) \\ \downarrow \pi \\ B_i := \text{Imm}(M, \mathbb{R}^2) / \text{Diff}(M) \end{array}$$

- ▶ Horizontal geodesics on $\text{Imm}(M, \mathbb{R}^2)$ project down to geodesics in shape space.
- ▶ O'Neill's formula connects sectional curvature on $\text{Imm}(M, \mathbb{R}^2)$ and on B_i .

L^2 metric

$$G_c^0(h, k) = \int_M \langle h(\theta), k(\theta) \rangle ds.$$

Problem: The induced geodesic distance vanishes.



[MichorMumford2005a,2005b], [BauerBruverisHarmsMichor2011,2012]

Weak Riem. metrics on $\text{Emb}(M, N) \subset \text{Imm}(M, N)$.

Metrics on the space of immersions of the form:

$$G_f^P(h, k) = \int_M \bar{g}(P^f h, k) \text{vol}(f^* \bar{g})$$

where \bar{g} is some fixed metric on N , $g = f^* \bar{g}$ is the induced metric on M , $h, k \in \Gamma(f^* TN)$ are tangent vectors at f to $\text{Imm}(M, N)$, and P^f is a positive, selfadjoint, bijective (scalar) pseudo differential operator of order $2p$ depending smoothly on f . Good example: $P^f = 1 + A(\Delta^g)^p$, where Δ^g is the Bochner-Laplacian on M induced by the metric $g = f^* \bar{g}$. Also P has to be $\text{Diff}(M)$ -invariant: $\varphi^* \circ P_f = P_{f \circ \varphi} \circ \varphi^*$.

Elastic metrics on plane curves

Here $M = S^1$ or $[0, 1\pi]$, $N = \mathbb{R}^2$. The elastic metrics on $\text{Imm}(M, \mathbb{R}^2)$ is

$$G_c^{a,b}(h, k) = \int_0^{2\pi} a^2 \langle D_s h, n \rangle \langle D_s k, n \rangle + b^2 \langle D_s h, v \rangle \langle D_s k, v \rangle ds,$$

with

$$\begin{aligned} P_c^{a,b}(h) = & -a^2 \langle D_s^2 h, n \rangle n - b^2 \langle D_s^2 h, v \rangle v \\ & + (a^2 - b^2) \kappa (\langle D_s h, v \rangle n + \langle D_s h, n \rangle v) \\ & + (\delta_{2\pi} - \delta_0) (a^2 \langle n, D_s h \rangle n + b^2 \langle v, D_s h \rangle v). \end{aligned}$$

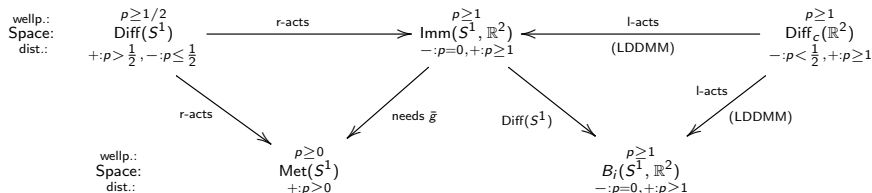
Sobolev type metrics

Advantages of Sobolev type metrics:

1. Positive geodesic distance
2. Geodesic equations are well posed
3. Generalization to higher dimension

Problems:

1. Analytic solutions to the geodesic equation?
2. Curvature of shape space with respect to these metrics?
3. Numerics are in general computational expensive



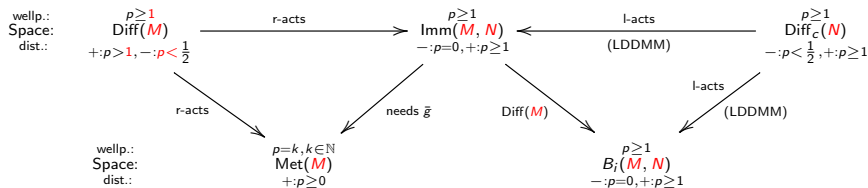
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Geodesic equation.

The geodesic equation for a Sobolev-type metric G^P on immersions is given by

$$\begin{aligned}\nabla_{\partial_t} f_t &= \frac{1}{2} P^{-1} \left(\text{Adj}(\nabla P)(f_t, f_t)^\perp - 2 Tf \cdot \bar{g}(Pf_t, \nabla f_t)^\sharp \right. \\ &\quad \left. - \bar{g}(Pf_t, f_t) \cdot \text{Tr}^g(S) \right) \\ &\quad - P^{-1} \left((\nabla_{f_t} P) f_t + \text{Tr}^g(\bar{g}(\nabla f_t, Tf)) Pf_t \right).\end{aligned}$$

The geodesic equation written in terms of the momentum for a Sobolev-type metric G^P on Imm is given by:

$$\begin{cases} p = Pf_t \otimes \text{vol}(g) \\ \nabla_{\partial_t} p = \frac{1}{2} \left(\text{Adj}(\nabla P)(f_t, f_t)^\perp - 2 Tf \cdot \bar{g}(Pf_t, \nabla f_t)^\sharp \right. \\ \quad \left. - \bar{g}(Pf_t, f_t) \text{Tr}^g(S) \right) \otimes \text{vol}(g) \end{cases}$$

Wellposedness

Assumption 1: $P, \nabla P$ and $\text{Adj}(\nabla P)^\perp$ are smooth sections of the bundles

$L(T\text{Imm}; T\text{Imm})$



Imm

$L^2(T\text{Imm}; T\text{Imm})$



Imm

$L^2(T\text{Imm}; T\text{Imm})$



$\text{Imm},$

respectively. Viewed locally in trivializ. of these bundles, $P_f h, (\nabla P)_f(h, k), (\text{Adj}(\nabla P)_f(h, k))^\perp$ are pseudo-differential operators of order $2p$ in h, k separately. As mappings in f they are non-linear, and we assume they are a composition of operators of the following type:

- (a) Local operators of order $l \leq 2p$, i.e., nonlinear differential operators $A(f)(x) = A(x, \hat{\nabla}^l f(x), \hat{\nabla}^{l-1} f(x), \dots, \hat{\nabla} f(x), f(x))$
- (b) Linear pseudo-differential operators of degrees l_i , such that the total (top) order of the composition is $\leq 2p$.

Assumption 2: For each $f \in \text{Imm}(M, N)$, the operator P_f is an elliptic pseudo-differential operator of order $2p$ for $p > 0$ which is positive and symmetric with respect to the H^0 -metric on Imm , i.e.

$$\int_M \bar{g}(P_f h, k) \text{vol}(g) = \int_M \bar{g}(h, P_f k) \text{vol}(g) \quad \text{for } h, k \in T_f \text{Imm}.$$

Theorem [Bauer, Harms, M, 2011] *Let $p \geq 1$ and $k > \dim(M)/2 + 1$, and let P satisfy the assumptions.*

Then the geodesic equation has unique local solutions in the Sobolev manifold Imm^{k+2p} of H^{k+2p} -immersions. The solutions depend smoothly on t and on the initial conditions $f(0, \cdot)$ and $f_t(0, \cdot)$. The domain of existence (in t) is uniform in k and thus this also holds in $\text{Imm}(M, N)$. Moreover, in each Sobolev completion Imm^{k+2p} , the Riemannian exponential mapping \exp^P exists and is smooth on a neighborhood of the zero section in the tangent bundle, and (π, \exp^P) is a diffeomorphism from a (smaller) neighbourhood of the zero section to a neighborhood of the diagonal in $\text{Imm}^{k+2p} \times \text{Imm}^{k+2p}$. All these neighborhoods are uniform in $k > \dim(M)/2 + 1$ and can be chosen H^{k_0+2p} -open, for $k_0 > \dim(M)/2 + 1$. Thus both properties of the exponential mapping continue to hold in $\text{Imm}(M, N)$.

Sobolev completions of $\Gamma(E)$, where $E \rightarrow M$ is a VB

Fix (background) Riemannian metric \hat{g} on M and its covariant derivative ∇^M . Equip E with a (background) fiber Riemannian metric \hat{g}^E and a compatible covariant derivative $\hat{\nabla}^E$. Then *Sobolev space* $H^k(E)$ is the completion of $\Gamma(E)$ for the Sobolev norm

$$\|h\|_k^2 = \sum_{j=0}^k \int_M (\hat{g}^E \otimes \hat{g}_j^0)((\hat{\nabla}^E)^j h, (\hat{\nabla}^E)^j h) \text{vol}(\hat{g}).$$

This Sobolev space is independent of choices of \hat{g} , ∇^M , \hat{g}^E and $\hat{\nabla}^E$ since M is compact: The resulting norms are equivalent.

Sobolev lemma: *If $k > \dim(M)/2$ then the identity on $\Gamma(E)$ extends to an injective bounded linear map $H^{k+p}(E) \rightarrow C^p(E)$ where $C^p(E)$ carries the supremum norm of all derivatives up to order p .*

Module property of Sobolev spaces: *If $k > \dim(M)/2$ then pointwise evaluation $H^k(L(E, E)) \times H^k(E) \rightarrow H^k(E)$ is bounded bilinear. Likewise all other pointwise contraction operations are multilinear bounded operations.*

Proof of well-posedness

By assumption 1 the mapping $P_f h$ is of order $2p$ in f and in h where f is the footpoint of h . Therefore $f \mapsto P_f$ extends to a smooth section of the smooth Sobolev bundle

$$L(T\text{Imm}^{k+2p}; T\text{Imm}^k \mid \text{Imm}^{k+2p}) \rightarrow \text{Imm}^{k+2p},$$

where $T\text{Imm}^k \mid \text{Imm}^{k+2p}$ denotes the space of all H^k tangent vectors with foot point a H^{k+2p} immersion, i.e., the restriction of the bundle $T\text{Imm}^k \rightarrow \text{Imm}^k$ to $\text{Imm}^{k+2p} \subset \text{Imm}^k$.

This means that P_f is a bounded linear operator

$$P_f \in L(H^{k+2p}(f^*TN), H^k(f^*TN)) \quad \text{for } f \in \text{Imm}^{k+2p}.$$

It is injective since it is positive. As an elliptic operator, it is an unbounded operator on the Hilbert completion of $T_f\text{Imm}$ with respect to the H^0 -metric, and a Fredholm operator $H^{k+2p} \rightarrow H^k$ for each k . It is selfadjoint elliptic, so the index = 0. Since it is injective, it is thus also surjective.

By the implicit function theorem on Banach spaces, $f \mapsto P_f^{-1}$ is then a smooth section of the smooth Sobolev bundle

$$L(T\text{Imm}^k | \text{Imm}^{k+2p}; T\text{Imm}^{k+2p}) \rightarrow \text{Imm}^{k+2p}$$

As an inverse of an elliptic pseudodifferential operator, P_f^{-1} is also an elliptic pseudo-differential operator of order $-2p$.

By assumption 1 again, $(\nabla P)_f(m, h)$ and $(\text{Adj}(\nabla P)_f(m, h))^\perp$ are of order $2p$ in f, m, h (locally). Therefore $f \mapsto P_f$ and $f \mapsto \text{Adj}(\nabla P)^\perp$ extend to smooth sections of the Sobolev bundle

$$L^2(T\text{Imm}^{k+2p}; T\text{Imm}^k | \text{Imm}^{k+2p}) \rightarrow \text{Imm}^{k+2p}$$

Using the module property of Sobolev spaces, one obtains that the "Christoffel symbols"

$$\begin{aligned} \Gamma_f(h, h) = & \frac{1}{2} P^{-1} \left(\text{Adj}(\nabla P)(h, h)^\perp - 2 \cdot Tf \cdot \bar{g}(Ph, \nabla h)^\sharp \right. \\ & \left. - \bar{g}(Ph, h) \cdot \text{Tr}^g(S) - (\nabla_h P)h - \text{Tr}^g(\bar{g}(\nabla h, Tf))Ph \right) \end{aligned}$$

extend to a smooth (C^∞) section of the smooth Sobolev bundle

$$L_{\text{sym}}^2(T\text{Imm}^{k+2p}; T\text{Imm}^{k+2p}) \rightarrow \text{Imm}^{k+2p}$$

Thus $h \mapsto \Gamma_f(h, h)$ is a smooth quadratic mapping $TImm \rightarrow TImm$ which extends to smooth quadratic mappings $TImm^{k+2p} \rightarrow TImm^{k+2p}$ for each $k \geq \frac{\dim(2)}{2} + 1$. The geodesic equation $\boxed{\nabla_{\partial_t}^{\bar{g}} f_t = \Gamma_f(f_t, f_t)}$ can be reformulated using the linear connection $C^{\bar{g}} : TN \times_N TN \rightarrow TTN$ (horizontal lift mapping) of $\nabla^{\bar{g}}$:

$$\partial_t f_t = C\left(\frac{1}{2}H_f(f_t, f_t) - K_f(f_t, f_t), f_t\right).$$

The right-hand side is a smooth vector field on $TImm^{k+2p}$, the geodesic spray. Note that the restriction to $TImm^{k+1+2p}$ of the geodesic spray on $TImm^{k+2p}$ equals the geodesic spray there. By the theory of smooth ODE's on Banach spaces, the flow of this vector field exists in $TImm^{k+2p}$ and is smooth in time and in the initial condition, for all $k \geq \frac{\dim(2)}{2} + 1$. It remains to show that the domain of existence is independent of k . I omit this. QED

The elastic metric

$$G_c^{a,b}(h, k) = \int_0^{2\pi} a^2 \langle D_s h, n \rangle \langle D_s k, n \rangle + b^2 \langle D_s h, v \rangle \langle D_s k, v \rangle ds,$$

$$\begin{aligned} c_t &= u \in C^\infty(\mathbb{R}_{>0} \times M, \mathbb{R}^2) \\ L(u_t) &= L\left(\frac{1}{2}H_c(u, u) - K_c(u, u)\right) \\ &= \frac{1}{2}(\delta_0 - \delta_{2\pi})\left(\langle D_s u, D_s u \rangle v + \frac{3}{4}\langle v, D_s u \rangle^2 v \right. \\ &\quad \left. - 2\langle D_s u, v \rangle D_s u - \frac{3}{2}\langle n, D_s u \rangle^2 v\right) \\ &\quad + D_s\left(\langle D_s u, D_s u \rangle v + \frac{3}{4}\langle v, D_s u \rangle^2 v \right. \\ &\quad \left. - 2\langle D_s u, v \rangle D_s u - \frac{3}{2}\langle n, D_s u \rangle^2 v\right) \end{aligned}$$

Note: Only a metric on Imm/transl.

Representation of the elastic metrics

Aim: Represent the class of elastic metrics as the pullback metric of a flat metric on $C^\infty(M, \mathbb{R}^2)$, i.e.: find a map

$$R : \text{Imm}(M, \mathbb{R}^2) \mapsto C^\infty(M, \mathbb{R}^n)$$

such that

$$G_c^{a,b}(h, k) = R^* \langle h, k \rangle_{L^2} = \langle T_c R.h, T_c R.k \rangle_{L^2}.$$

[YounesMichorShahMumford2008] [SrivastavaKlassenJoshiJermyn2011]

The R transform on open curves

Theorem

The metric $G^{a,b}$ is the pullback of the flat L^2 metric via the transform R :

$$R^{a,b} : \text{Imm}([0, 2\pi], \mathbb{R}^2) \rightarrow C^\infty([0, 2\pi], \mathbb{R}^3)$$
$$R^{a,b}(c) = |c'|^{1/2} \left(a \begin{pmatrix} v \\ 0 \end{pmatrix} + \sqrt{4b^2 - a^2} \begin{pmatrix} 0 \\ 1 \end{pmatrix} \right) .$$

The metric $G^{a,b}$ is flat on open curves, geodesics are the preimages under the R -transform of geodesics on the flat space $\text{Im } R$ and the geodesic distance between $c, \bar{c} \in \text{Imm}([0, 2\pi], \mathbb{R}^2) / \text{trans}$ is given by the integral over the pointwise distance in the image $\text{Im}(R)$. The curvature on $B([0, 2\pi], \mathbb{R}^2)$ is non-negative.

The R transform on open curves II

Image of R is characterized by the condition:

$$(4b^2 - a^2)(R_1^2(c) + R_2^2(c)) = a^2 R_3^2(c)$$

Define the flat cone

$$C^{a,b} = \{q \in \mathbb{R}^3 : (4b^2 - a^2)(q_1^2 + q_2^2) = a^2 q_3^2, q_3 > 0\}.$$

Then $\text{Im } R = C^\infty(S^1, C^{a,b})$. The inverse of R is given by:

$$R^{-1} : \text{im } R \rightarrow \text{Imm}([0, 2\pi], \mathbb{R}^2) / \text{trans}$$

$$R^{-1}(q)(\theta) = p_0 + \frac{1}{2ab} \int_0^\theta |q(\theta)| \begin{pmatrix} q_1(\theta) \\ q_2(\theta) \end{pmatrix} d\theta.$$

The R transform on closed curves I

Characterize image using the inverse:

$$R^{-1}(q)(\theta) = p_0 + \frac{1}{2ab} \int_0^\theta |q(\theta)| \begin{pmatrix} q_1(\theta) \\ q_2(\theta) \end{pmatrix} d\theta.$$

$R^{-1}(q)(\theta)$ is closed iff

$$F(q) = \int_0^{2\pi} |q(\theta)| \begin{pmatrix} q_1(\theta) \\ q_2(\theta) \end{pmatrix} d\theta = 0$$

A basis of the orthogonal complement $(T_q \mathcal{C}^{a,b})^\perp$ is given by the two gradients $\text{grad}^{L^2} F_i(q)$

The R transform on closed curves II

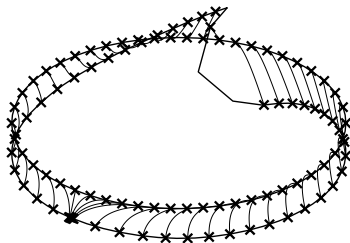
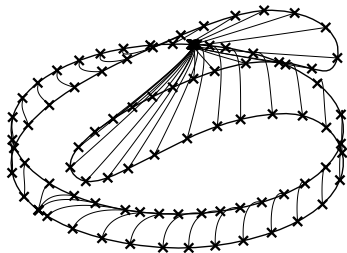
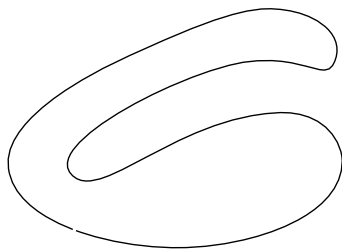
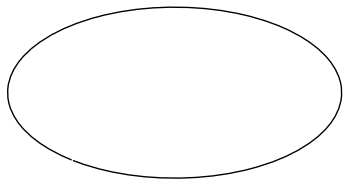
Theorem

The image $\mathcal{C}^{a,b}$ of the manifold of closed curves under the R -transform is a codimension 2 submanifold of the flat space $\text{Im}(R)_{\text{open}}$. A basis of the orthogonal complement $(T_q \mathcal{C}^{a,b})^\perp$ is given by the two vectors

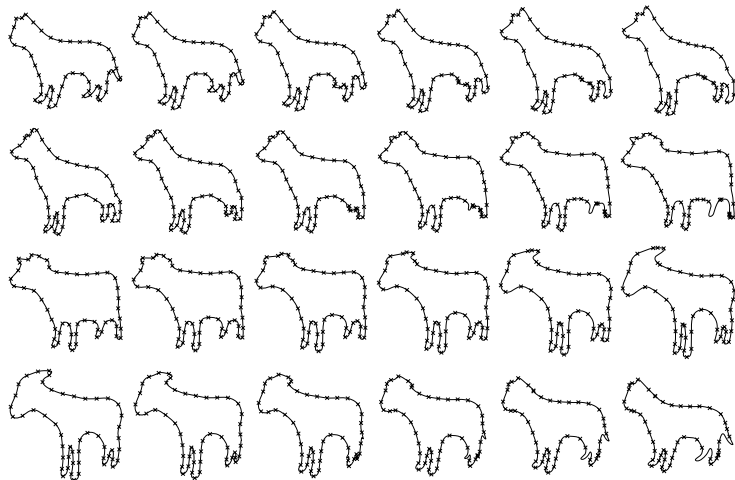
$$U_1(q) = \frac{1}{\sqrt{q_1^2 + q_2^2}} \begin{pmatrix} 2q_1^2 + q_2^2 \\ q_1 q_2 \\ 0 \end{pmatrix} + \frac{2}{a} \sqrt{4b^2 - a^2} \begin{pmatrix} 0 \\ 0 \\ q_1 \end{pmatrix},$$

$$U_2(q) = \frac{1}{\sqrt{q_1^2 + q_2^2}} \begin{pmatrix} q_1 q_2 \\ q_1^2 + 2q_2^2 \\ 0 \end{pmatrix} + \frac{2}{a} \sqrt{4b^2 - a^2} \begin{pmatrix} 0 \\ 0 \\ q_2 \end{pmatrix}.$$

compress and stretch

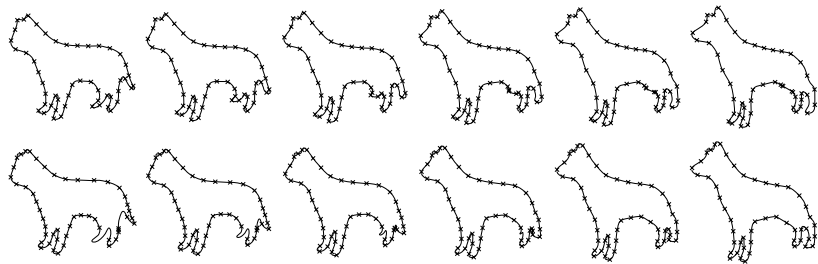


A geodesic Rectangle

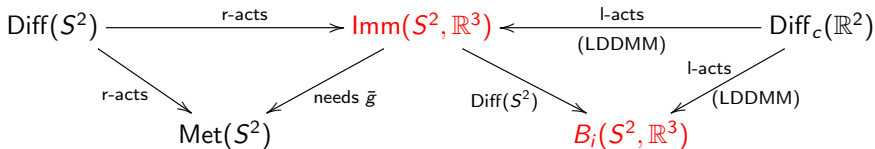


Non-symmetric distances

l_1	l_2	$l_1 \rightarrow l_2$			$l_2 \rightarrow l_1$			%diff
		# iterations	# points	distance	# iterations	# points	distance	
cat	cow	28	456	7.339	33	462	8.729	15.9
cat	dog	36	475	8.027	102	455	10.060	20.2
cat	donkey	73	476	12.620	102	482	12.010	4.8
cow	donkey	32	452	7.959	26	511	7.915	0.6
dog	donkey	15	457	8.299	10	476	8.901	6.8
shark	airplane	63	491	13.741	40	487	13.453	2.1



An example of a metric space with strongly negatively curved regions



$$G_f^\Phi(h, k) = \int_M \Phi(f) \bar{g}(h, k) \text{vol}(g)$$

[BauerHarmsMichor2012]

Non-vanishing geodesic distance

The pathlength metric on shape space induced by G^Φ separates points if one of the following holds:

- ▶ $\Phi \geq C_1 + C_2 \|\text{Tr}^g(S)\|^2$ with $C_1, C_2 > 0$ or
- ▶ $\Phi \geq C_3 \text{Vol}$

This leads us to consider $\Phi = \Phi(\text{Vol}, \|\text{Tr}^g(S)\|^2)$.

Special cases:

- ▶ G^A -metric: $\Phi = 1 + A \|\text{Tr}^g(S)\|^2$
- ▶ Conformal metrics: $\Phi = \Phi(\text{Vol})$

Geodesic equation on shape space $B_i(M, \mathbb{R}^n)$, with $\Phi = \Phi(\text{Vol}, \text{Tr}(L))$

$$f_t = a.\nu,$$

$$\begin{aligned} a_t = \frac{1}{\Phi} & \left[\frac{\Phi}{2} a^2 \text{Tr}(L) - \frac{1}{2} \text{Tr}(L) \int_M (\partial_1 \Phi) a^2 \text{vol}(g) - \frac{1}{2} a^2 \Delta(\partial_2 \Phi) \right. \\ & + 2ag^{-1}(d(\partial_2 \Phi), da) + (\partial_2 \Phi) \|da\|_{g^{-1}}^2 \\ & \left. + (\partial_1 \Phi) a \int_M \text{Tr}(L).a \text{vol}(g) - \frac{1}{2} (\partial_2 \Phi) \text{Tr}(L^2) a^2 \right] \end{aligned}$$

Sectional curvature on B_i

Chart for B_i centered at $\pi(f_0)$ so that $\pi(f_0) = 0$ in this chart:

$$a \in C^\infty(M) \longleftrightarrow \pi(f_0 + a \cdot \nu^{f_0}).$$

For a linear 2-dim. subspace $P \subset T_{\pi(f_0)}B_i$ spanned by a_1, a_2 , the sectional curvature is defined as:

$$k(P) = -\frac{G_{\pi(f_0)}^\Phi(\mathcal{R}_{\pi(f_0)}(a_1, a_2)a_1, a_2)}{\|a_1\|^2\|a_2\|^2 - G_{\pi(f_0)}^\Phi(a_1, a_2)^2}, \text{ where}$$

$$\begin{aligned} R_0(a_1, a_2, a_1, a_2) &= G_0^\Phi(R_0(a_1, a_2)a_1, a_2) = \\ &\frac{1}{2}d^2G_0^\Phi(a_1, a_1)(a_2, a_2) + \frac{1}{2}d^2G_0^\Phi(a_2, a_2)(a_1, a_1) \\ &\quad - d^2G_0^\Phi(a_1, a_2)(a_1, a_2) \\ &\quad + G_0^\Phi(\Gamma_0(a_1, a_1), \Gamma_0(a_2, a_2)) - G_0^\Phi(\Gamma_0(a_1, a_2), \Gamma_0(a_1, a_2)). \end{aligned}$$

Sectional curvature on B_i for $\Phi = \text{Vol}$

$$k(P) = -\frac{\mathcal{R}_0(a_1, a_2, a_1, a_2)}{\|a_1\|^2 \|a_2\|^2 - G_{\pi(f_0)}^\Phi(a_1, a_2)^2}, \text{ where}$$

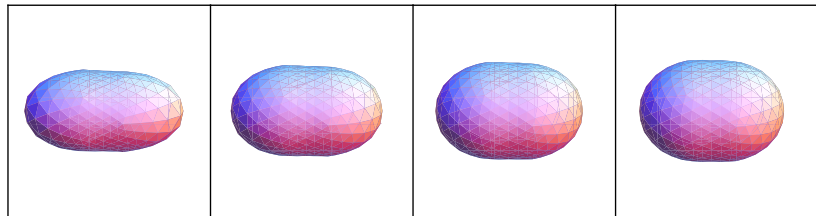
$$\begin{aligned} \mathcal{R}_0(a_1, a_2, a_1, a_2) = & -\frac{1}{2} \text{Vol} \int_M \|a_1 da_2 - a_2 da_1\|_{g^{-1}}^2 \text{vol}(g) \\ & + \frac{1}{4 \text{Vol}} \overline{\text{Tr}(L)^2} (\overline{a_1^2 \cdot a_2^2} - \overline{a_1 \cdot a_2^2}) \\ & + \frac{1}{4} (\overline{a_1^2 \cdot \text{Tr}(L)^2 a_2^2} - 2\overline{a_1 \cdot a_2 \cdot \text{Tr}(L)^2 a_1 \cdot a_2} + \overline{a_2^2 \cdot \text{Tr}(L)^2 a_1^2}) \\ & - \frac{3}{4 \text{Vol}} (\overline{a_1^2 \cdot \text{Tr}(L) a_2^2} - 2\overline{a_1 \cdot a_2 \cdot \text{Tr}(L) a_1 \cdot \text{Tr}(L) a_2} + \overline{a_2^2 \cdot \text{Tr}(L) a_1^2}) \\ & + \frac{1}{2} (\overline{a_1^2 \cdot \text{Tr}^g((da_2)^2)} - 2\overline{a_1 \cdot a_2 \cdot \text{Tr}^g(da_1 \cdot da_2)} + \overline{a_2^2 \cdot \text{Tr}^g((da_1)^2)}) \\ & - \frac{1}{2} (\overline{a_1^2 \cdot a_2^2 \cdot \text{Tr}(L^2)} - 2\overline{a_1 \cdot a_2 \cdot a_1 \cdot a_2 \cdot \text{Tr}(L^2)} + \overline{a_2^2 \cdot a_1^2 \cdot \text{Tr}(L^2)}). \end{aligned}$$

Sectional curvature on B_i for $\Phi = 1 + A \operatorname{Tr}(L)^2$

$$k(P) = -\frac{\mathcal{R}_0(a_1, a_2, a_1, a_2)}{\|a_1\|^2 \|a_2\|^2 - G_{\pi(f_0)}^\Phi(a_1, a_2)^2}, \text{ where}$$

$$\begin{aligned} \mathcal{R}_0(a_1, a_2, a_1, a_2) &= \int_M A(a_1 \Delta a_2 - a_2 \Delta a_1)^2 \operatorname{vol}(g) \\ &+ \int_M 2A \operatorname{Tr}(L) g_2^0((a_1 da_2 - a_2 da_1) \otimes (a_1 da_2 - a_2 da_1), s) \operatorname{vol}(g) \\ &+ \int_M \frac{1}{1 + A \operatorname{Tr}(L)^2} \left[-4A^2 g^{-1}(d \operatorname{Tr}(L), a_1 da_2 - a_2 da_1)^2 \right. \\ &- \left(\frac{1}{2} (1 + A \operatorname{Tr}(L)^2)^2 + 2A^2 \operatorname{Tr}(L) \Delta(\operatorname{Tr}(L)) + 2A^2 \operatorname{Tr}(L^2) \operatorname{Tr}(L)^2 \right) \\ &\quad \cdot \|a_1 da_2 - a_2 da_1\|_{g^{-1}}^2 + (2A^2 \operatorname{Tr}(L)^2) \|da_1 \wedge da_2\|_{g_0^2}^2 \\ &\left. + (8A^2 \operatorname{Tr}(L)) g_2^0(d \operatorname{Tr}(L) \otimes (a_1 da_2 - a_2 da_1), da_1 \wedge da_2) \right] \operatorname{vol}(g) \end{aligned}$$

Negative Curvature: A toy example



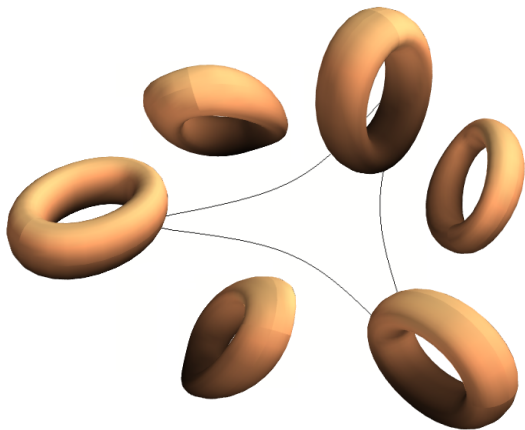
Ex1: $\Phi = 1 + .4 \text{Tr}(L)^2$

Ex2: $\Phi = e^{\text{Vol}}$

Ex3: $\Phi = e^{\text{Vol}}$

Another toy example

$$G_f^\Phi(h, k) = \int_{\mathbb{T}^2} \bar{g}((1 + \Delta)h, k) \text{vol}(g) \text{ on } \text{Imm}(\mathbb{T}^2, \mathbb{R}^3):$$



Special case: Diffeomorphism groups.

For $M = N$ the space $\text{Emb}(M, M)$ equals the *diffeomorphism group of M* . An operator $P \in \Gamma(L(T\text{Emb}; T\text{Emb}))$ that is invariant under reparametrizations induces a right-invariant Riemannian metric on this space. Thus one gets the geodesic equation for right-invariant Sobolev metrics on diffeomorphism groups and well-posedness of this equation. The geodesic equation on $\text{Diff}(M)$ in terms of the momentum p is given by

$$\begin{cases} p = Pf_t \otimes \text{vol}(g), \\ \nabla_{\partial_t} p = -Tf \cdot \bar{g}(Pf_t, \nabla f_t)^\sharp \otimes \text{vol}(g). \end{cases}$$

Note that this equation is not right-trivialized, in contrast to the equation given in [Arnold 1966]. The special case of theorem now reads as follows:

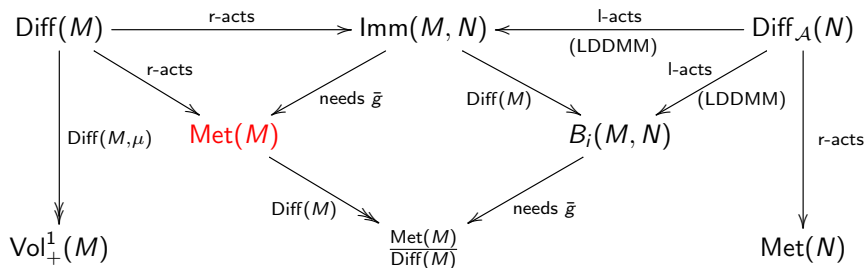
Theorem. [Bauer, Harms, M, 2011] *Let $p \geq 1$ and $k > \frac{\dim(M)}{2} + 1$ and let P satisfy the assumptions.*

The initial value problem for the geodesic equation has unique local solutions in the Sobolev manifold Diff^{k+2p} of H^{k+2p} -diffeomorphisms.

The solutions depend smoothly on t and on the initial conditions $f(0, \cdot)$ and $f_t(0, \cdot)$. The domain of existence (in t) is uniform in k and thus this also holds in $\text{Diff}(M)$.

Moreover, in each Sobolev completion Diff^{k+2p} , the Riemannian exponential mapping \exp^P exists and is smooth on a neighborhood of the zero section in the tangent bundle, and (π, \exp^P) is a diffeomorphism from a (smaller) neighbourhood of the zero section to a neighborhood of the diagonal in $\text{Diff}^{k+2p} \times \text{Diff}^{k+2p}$. All these neighborhoods are uniform in $k > \dim(M)/2 + 1$ and can be chosen H^{k_0+2p} -open, for $k_0 > \dim(M)/2 + 1$. Thus both properties of the exponential mapping continue to hold in $\text{Diff}(M)$.

About $\text{Met}(M)$



Weak Riemann metrics on $\text{Met}(M)$

All of them are $\text{Diff}(M)$ -invariant; natural, tautological.

$$G_g(h, k) = \int_M g_2^0(h, k) \text{vol}(g) = \int \text{Tr}(g^{-1} h g^{-1} k) \text{vol}(g), \quad L^2\text{-metr.}$$

$$\text{or} = \Phi(\text{Vol}(g)) \int_M g_2^0(h, k) \text{vol}(g) \quad \text{conformal}$$

$$\text{or} = \int_M \Phi(\text{Scal}^g) \cdot g_2^0(h, k) \text{vol}(g) \quad \text{curvature modified}$$

$$\text{or} = \int_M g_2^0((1 + \Delta^g)^p h, k) \text{vol}(g) \quad \text{Sobolev order } p$$

$$\text{or} = \int_M \left(g_2^0(h, k) + g_3^0(\nabla^g h, \nabla^g k) + \dots \right. \\ \left. + g_p^0((\nabla^g)^p h, (\nabla^g)^p k) \right) \text{vol}(g)$$

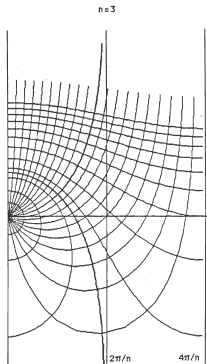
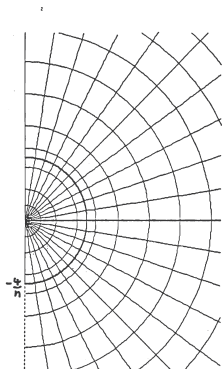
where Φ is a suitable real-valued function, $\text{Vol} = \int_M \text{vol}(g)$ is the total volume of (M, g) , Scal is the scalar curvature of (M, g) , and where g_2^0 is the induced metric on $\binom{0}{2}$ -tensors.

The L^2 -metric on the space of all Riemann metrics

[Ebin 1970]. Geodesics and curvature [Freed Groisser 1989].
[Gil-Medrano Michor 1991] for non-compact M . [Clarke 2009] showed that geodesic distance for the L^2 -metric is positive, and he determined the metric completion of $\text{Met}(M)$.

The geodesic equation is completely decoupled from space, it is an ODE:

$$g_{tt} = g_t g^{-1} g_t + \frac{1}{4} \text{Tr}(g^{-1} g_t g^{-1} g_t) g - \frac{1}{2} \text{Tr}(g^{-1} g_t) g_t$$



$$\exp_0(A) = \frac{2}{n} \log \left(\left(1 + \frac{1}{4} \text{Tr}(A)\right)^2 + \frac{n}{16} \text{Tr}(A_0^2) \right) Id$$

$$+ \frac{4}{\sqrt{n \text{Tr}(A_0^2)}} \arctan \left(\frac{\sqrt{n \text{Tr}(A_0^2)}}{4 + \text{Tr}(A)} \right) A_0.$$

Back to the the general metric on $\text{Met}(M)$.

We describe all these metrics uniformly as

$$\begin{aligned} G_g^P(h, k) &= \int_M g_2^0(P_g h, k) \text{vol}(g) \\ &= \int_M \text{Tr}(g^{-1} \cdot P_g(h) \cdot g^{-1} \cdot k) \text{vol}(g), \end{aligned}$$

where

$$P_g : \Gamma(S^2 T^* M) \rightarrow \Gamma(S^2 T^* M)$$

is a positive, symmetric, bijective pseudo-differential operator of order $2p$, $p \geq 0$, depending smoothly on the metric g , and also $\text{Diff}(M)$ -equivariantly:

$$\varphi^* \circ P_g = P_{\varphi^* g} \circ \varphi^*$$

The geodesic equation in this notation:

$$\begin{aligned}
 g_{tt} = P^{-1} & \left[(D_{(g, \cdot)} P g_t)^*(g_t) + \frac{1}{4} \cdot g \cdot \text{Tr}(g^{-1} \cdot P g_t \cdot g^{-1} \cdot g_t) \right. \\
 & + \frac{1}{2} g_t \cdot g^{-1} \cdot P g_t + \frac{1}{2} P g_t \cdot g^{-1} \cdot g_t - (D_{(g, g_t)} P) g_t \\
 & \left. - \frac{1}{2} \text{Tr}(g^{-1} \cdot g_t) \cdot P g_t \right]
 \end{aligned}$$

We can rewrite this equation to get it in a slightly more compact form:

$$\begin{aligned}
 (P g_t)_t & = (D_{(g, g_t)} P) g_t + P g_{tt} \\
 & = (D_{(g, \cdot)} P g_t)^*(g_t) + \frac{1}{4} \cdot g \cdot \text{Tr}(g^{-1} \cdot P g_t \cdot g^{-1} \cdot g_t) \\
 & \quad + \frac{1}{2} g_t \cdot g^{-1} \cdot P g_t + \frac{1}{2} P g_t \cdot g^{-1} \cdot g_t - \frac{1}{2} \text{Tr}(g^{-1} \cdot g_t) \cdot P g_t
 \end{aligned}$$

Well posedness of geodesic equation.

Assumptions Let $P_g(h)$, $P_g^{-1}(k)$ and $(D_{(g,\cdot)}Ph)^*(m)$ be linear pseudo-differential operators of order $2p$ in m, h and of order $-2p$ in k for some $p \geq 0$.

As mappings in the foot point g , we assume that all mappings are non-linear, and that they are a composition of operators of the following type:

(a) Non-linear differential operators of order $l \leq 2p$, i.e.,

$$A(g)(x) = A(x, g(x), (\hat{\nabla}g)(x), \dots, (\hat{\nabla}^l g)(x)),$$

(b) Linear pseudo-differential operators of order $\leq 2p$, such that the total (top) order of the composition is $\leq 2p$.

Since $h \mapsto P_g h$ induces a weak inner product, it is a symmetric and injective pseudodifferential operator. We assume that it is elliptic and selfadjoint. Then it is Fredholm and has vanishing index. Thus it is invertible and $g \mapsto P_g^{-1}$ is smooth

$H^k(S_+^2 T^* M) \rightarrow L(H^k(S^2 T^* M), H^{k+2p}(S^2 T^* M))$ by the implicit function theorem on Banach spaces.

Theorem. [Bauer, Harms, M. 2011] *Let the assumptions above hold. Then for $k > \frac{\dim(M)}{2}$, the initial value problem for the geodesic equation has unique local solutions in the Sobolev manifold $\text{Met}^{k+2p}(M)$ of H^{k+2p} -metrics. The solutions depend C^∞ on t and on the initial conditions $g(0, \cdot) \in \text{Met}^{k+2p}(M)$ and $g_t(0, \cdot) \in H^{k+2p}(S^2 T^*M)$. The domain of existence (in t) is uniform in k and thus this also holds in $\text{Met}(M)$.*

Moreover, in each Sobolev completion $\text{Met}^{k+2p}(M)$, the Riemannian exponential mapping \exp^P exists and is smooth on a neighborhood of the zero section in the tangent bundle, and (π, \exp^P) is a diffeomorphism from a (smaller) neighborhood of the zero section to a neighborhood of the diagonal in $\text{Met}^{k+2p}(M) \times \text{Met}^{k+2p}(M)$. All these neighborhoods are uniform in $k > \frac{\dim(M)}{2}$ and can be chosen H^{k_0+2p} -open, where $k_0 > \frac{\dim(M)}{2}$. Thus all properties of the exponential mapping continue to hold in $\text{Met}(M)$.

Conserved Quantities on $\text{Met}(M)$.

Right action of $\text{Diff}(M)$ on $\text{Met}(M)$ given by

$$(g, \phi) \mapsto \phi^* g.$$

Fundamental vector field (infinitesimal action):

$$\zeta_X(g) = \mathcal{L}_X g = -2 \text{Sym} \nabla(g(X)).$$

If metric G^P is invariant, we have the following conserved quantities

$$\begin{aligned} \text{const} &= G^P(g_t, \zeta_X(g)) \\ &= -2 \int_M g_t^0(\nabla^* \text{Sym} P g_t, g(X)) \text{vol}(g) \\ &= -2 \int_M g(g^{-1} \nabla^* P g_t, X) \text{vol}(g) \end{aligned}$$

Since this holds for all vector fields X ,

$(\nabla^* P g_t) \text{vol}(g) \in \Gamma(T^*M \otimes_M \text{vol}(M))$ is const. in t .

Thank you for your attention