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The Sharp Constant for the Burkholder-Davis-Gundy Inequality and Non-Smooth Pasting

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Abstract: We revisit the celebrated family of BDG-inequalities introduced by Burkholder, Gundy [8] and Davis [10] for continuous martingales. For the inequalities $\mathbb{E}[\tau^{\frac{p}{2}}] \leqslant C_p \mathbb{E}[(B^*(\tau))^p]$ with $0 < p < 2$ we propose a connection of the optimal constant C_p with an ordinary integro-differential equation which gives rise to a numerical method of finding this constant. Based on numerical evidence we are able to calculate, for $p = 1$, the explicit value of the optimal constant C_1, namely $C_1 = 1,27267\ldots$. In the course of our analysis, we find a remarkable appearance of "non-smooth pasting" for a solution of a related ordinary integro-differential equation.

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1. Introduction

We consider the following version of the Burkholder-Davis-Gundy inequality [8], [10]:

Theorem 1.1. *There is a constant $C > 0$ such that, for every bounded stopping time τ, we have*

$$\mathbb{E}\Big[\tau^{\frac{1}{2}}\Big] \leqslant C\,\mathbb{E}[B^*(\tau)]. \tag{1}$$

Here $(B(t))_{t\geqslant 0}$ denotes a standard Brownian motion, starting at $B(0) = 0$.

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By $B^*(t)$ we denote the corresponding running maximum of the absolute value

$$B^*(t) := \sup_{0 \leqslant u \leqslant t} |B(u)|.$$

It is obvious that the set of constants C which satisfy inequality (1) is a closed, unbounded interval in $\mathbb{R}_+$. By the results of [5] it is known that $C = \frac{3}{2}$ is contained in this set. To the best of our knowledge, this is the smallest constant known in the previous literature. In the present paper we establish the optimal value for this constant.

Theorem 1.2. *There is an ordinary integro-differential equation (see* (31) *below) depending on real parameters $C > 0$ and $t_0 > 0$ such that C satisfies* (1) *if and only if there is t_0 such that this equation has a well-defined solution.*

Numerical solutions of the equation (31) *reveal that the smallest such C, i.e. the optimal constant in the Burkholder-Davis-Gundy inequality* (1)*, equals*

$$\widehat{C} \approx 1,27267\ldots.$$

The paper is organised as follows. As usual in stochastic control theory, we first introduce the *value function* of the *optimal stopping* problem which corresponds to the inequality (1). After some structural facts about the stopping problem we turn to some analytic properties of the value function in Section 3. We deduce the OIDE (ordinary integro-differential equation) which is referred to in Theorem 1.2. The subsequent section is devoted to properties of solutions to the fundamental OIDE (31) which are needed to identify these solutions with the value function of the stopping problem in Section 5.

The critical $\widehat{t}_0 > 0$ associated to the optimal constant $\widehat{C}$ via (31) below also turns out to be of somewhat independent interest: if ρ denotes the first moment, say after $t = 1$, when t is bigger than $cB^*(t)^2$, then $\mathbb{E}[\rho^{\frac{1}{2}}]$ is finite or infinite depending on whether c is smaller or bigger than $\widehat{t}_0$ (Proposition 5.6 and 5.7). In Section 6 we state a pointwise version of the BDG inequalities and in Section 7 we briefly discuss the case of general $0 < p < 2$ without entering into a numerical analysis. Finally, in Section 8 we discuss the fact why the constant $\widehat{C} = \sqrt{3}$ which was established by D. Burkholder [7] as the optimal constant for (1) in the case of martingales which are not necessarily continuous, is different from the present constant $\widehat{C} = 1,27267\ldots$ which holds true for continuous processes. We relate this discrepancy with a certain lack of concavity of the value function.

2. The Value Function of an Optimal Stopping Problem

Fix a constant $C > 0$. Following a well-known path in optimal control theory we define the value function

$$V(t, b, b^*) := \sup_{\tau \in \mathcal{T}(t)} \mathbb{E}^{(t,b,b^*)}[\tau^{\frac{1}{2}} - CB^*(\tau)], \tag{2}$$

where $\mathcal{T}(t)$ denotes the set of bounded stopping times $\tau \geqslant t$ and $\mathbb{E}^{(t,b,b^*)}$ denotes the expectation conditionally on starting the Brownian motion B at time t with the values $B_t = b, B_t^* = b^*$. The domain of definition of V is

$$D = \{(t, b, b^*): \quad 0 \leqslant t < \infty, \quad 0 \leqslant |b| \leqslant b^* < \infty\}. \tag{3}$$

Equivalently we can write

$$V(t, b, b^*) := \sup_{\tau \in \mathcal{T}} \mathbb{E}[\sqrt{t + \tau} - C(b^* \vee (b + B(\tau))^*], \tag{4}$$

which follows from the strong Markov property and stationarity of increments of Brownian motion.

Denote by $\widehat{C}$ the infimum of $C > 0$ such that (1) holds true. Clearly $\widehat{C}$ still satisfies (1). If $C < \widehat{C}$ then $V(t, b, b^*) \equiv \infty$, otherwise we have:

Lemma 2.1. *Let $C \geqslant \widehat{C}$ then V defined via (2) is*

(i) continuous,
(ii) finite-valued, and
(iii) $t \mapsto V(t, b, b^*) - \sqrt{t}$ is decreasing for fixed $|b| \leqslant b^*$.

In particular (ii) follows from the bounds

$$\sqrt{t} + Cb^* \geqslant V(t, b, b^*) \geqslant \sqrt{t} - Cb^*. \tag{5}$$

Proof. The lower bound of V follows from choosing the stopping time $t \in \mathcal{T}(t)$. For the upper bound observe that we can estimate for an arbitrary $\tau \in \mathcal{T}$

$$\begin{aligned}\sqrt{t + \tau} - C(b^* \vee (b + B(\tau))^* &\leqslant \sqrt{t} + \sqrt{\tau} - C(b + B(\tau))^* \\ &\leqslant \sqrt{t} + \sqrt{\tau} - CB(\tau)^* + C|b| \\ &\leqslant \sqrt{t} + Cb^* + \sqrt{\tau} - CB(\tau)^*.\end{aligned}$$

Taking expectations we get the upper bound for V from the representation in (4).

Next observe that for $\tau \in \mathcal{T}$ we have for $t < t'$

$$\sqrt{t + \tau} - C(b^* \vee (b + B(\tau))^* - \sqrt{t} \leqslant \sqrt{t' + \tau} - C(b^* \vee (b + B(\tau))^* - \sqrt{t'}$$

by concavity of the square root. Now (iii) follows by taking expectations suprema.

For (i), please refer to Sections 7 and 9.2 in [14]. ☐

To exclude the trivial case, we assume in the sequel that $C \geqslant \widehat{C}$.

For fixed C, the *stopping region* $S \subseteq D$ and the *non-stopping region* $NS \subseteq D$ are defined by

$$S := \{V = t^{\frac{1}{2}} - Cb^*\}, \quad NS := \{V > t^{\frac{1}{2}} - Cb^*\}. \tag{6}$$

To characterize the stopping region S first note that it is certainly not a good idea to stop when $|B(t)| < B^*(t)$.

Lemma 2.2. *Let $(t, b, b^*) \in D$ with $|b| < b^*$. Then $(t, b, b^*) \in NS$.*

Proof. Consider the first exit time of the interval $[-b^*, b^*]$. □

Next we observe a useful scaling property of V (compare Burkholder [7]).

Lemma 2.3. *For $a > 0$ and $(t, b, b^*) \in D$, we have*

$$V(a^2 t, ab, ab^*) = aV(t, b, b^*). \tag{7}$$

Proof. This follows directly from the scaling property of Brownian motion: if $(B_t)_{t \geqslant 0}$ is a standard Brownian motion, then $(a^{-1} B_{a^2 t})_{t \geqslant 0}$ again is a standard Brownian motion. Also, a random time $a^2 \tau$ is a stopping time for the first process if and only if τ is a stopping time for the second process. □

This allows us to derive the following Lemma where the first part is a direct consequence of Lemmas 2.1 (iii) and 2.3 and the second part is technical and deferred to the appendix in Lemma B.3.

Lemma 2.4. *Let $0 \leqslant t \leqslant t'$ and $b \in \mathbb{R}$. Then $(t, b, |b|) \in S$ implies $(t', b, |b|) \in S$.*

Hence, for fixed $C \geqslant \widehat{C}$ there is a smallest $t_0 \in [0, \infty]$ such that $(t, b, |b|) \in S$ if and only if

$$\frac{t}{|b|^2} \geqslant t_0. \tag{8}$$

In fact, we have $t_0 \in (0, \infty)$.

The next result is a standard result in optimal control theory and also intuitively rather obvious. Again, the proof is deferred to the appendix.

Lemma 2.5. *Suppose $C \geqslant \widehat{C}$ and let (t, b, b^*) be in the non-stop region NS. Consider a Brownian motion $(B(u))_{t \leqslant u}$ starting at time t conditionally on $B(t) = b$ and $B^*(t) = b^*$. Let τ be the first hitting time of the stopping region S, i.e.*

$$\tau = \inf\{u \geqslant t : (u, B(u), B^*(u)) \in S\} \tag{9}$$

Then the value process stopped at time τ

$$M(u)^\tau := V(u \wedge \tau, B(u \wedge \tau), B^*(u \wedge \tau)), \qquad u \geqslant t, \tag{10}$$

is a martingale.

The unstopped value process

$$M(u) := V(u, B(u), B^*(u)), \qquad u \geqslant t, \tag{11}$$

still is a supermartingale.

We conclude this section with a minor technical remark. In the above statement, as well as in most of the paper, we follow the usual language of optimal control theory to condition on the event $\{B(t) = b, B^*(t) = b^*\}$. As this is a null set under $\mathbb{P}$ this procedure needs some proper interpretation in order to make it rigorous.

Let us now introduce some notation to make this a bit clearer.

We denote by $(\mathcal{F}(u))_{u\geqslant 0}$ the (right-continuous, saturated) filtration generated by the Brownian motion $(B(u))_{u\geqslant 0}$. Of course, in definition (2) the stopping time $\tau \in \mathcal{T}(t)$ is understood with respect to this filtration. But it is clear from the Markov property that, for fixed (t, b, b^*), we may assume that $\tau \in \mathcal{T}(t)$ depends only on the behavior of the Brownian motion $(B(u))_{u\geqslant t}$ after time t and not on the previous behavior of $(B(u))_{0\leqslant u\leqslant t}$ (except for the requirements $B(t) = b$ and $B^*(t) = b^*$).

To formalize this fact, we denote by $(\mathcal{G}^{(t)}(u))_{u\geqslant t}$ the (right-continuous, saturated) filtration generated by $(B(u) - B(t))_{u\geqslant t}$. A stopping time $\tau \in \mathcal{T}(t)$ (i.e., with respect to the filtration $(\mathcal{F}(u))_{u\geqslant 0}$) then may also be considered as a randomized stopping time with respect to the filtration $(\mathcal{G}^{(t)}(u))_{u\geqslant t}$, the randomization given by the trajectories of $(B(u))_{0\leqslant u\leqslant t}$. As $(B(u))_{0\leqslant u\leqslant t}$ is independent of the filtration $(\mathcal{G}^{(t)}(u))_{u\geqslant t}$, we conclude that the value of (2) does not change whether we optimize over the randomized or the non-randomized stopping times with respect to the filtration $(\mathcal{G}^{(t)}(u))_{u\geqslant t}$. For an introduction to the notion of randomized stopping times, please refer to [3]

The bottom line of these considerations is that we may assume w.l.o.g. in (2) that $\tau \in \mathcal{T}(t)$ is a stopping time with respect to the filtration $(\mathcal{G}^{(t)}(u))_{u\geqslant t}$.

Now, the statement Lemma 2.5 could be rephrased without referring to conditioning on a null set, by noting that τ is a stopping time with respect to the filtration $(\mathcal{G}^{(t)}(u))_{t\leqslant u}$.

All other statements in the paper referring to conditioning on the values $B(t)$ and $B^*(t)$ could be made rigorous in an analogous way if the reader insists, but we do not further elaborate on these technicalities.

3. The Value Function from an Analytic Perspective

Again fix $C \geqslant \widehat{C}$. Differentiating the scaling equation (7) with respect to a and setting $a = 1$ we obtain, at least formally, the PDE

$$2tV_t + bV_b + b^* V_{b*} = V. \tag{12}$$

The optimal constant C for inequality (1) will be determined by analyzing whether this PDE has a reasonable solution for given $C > 0$ or not.

We need some preparation. For $0 < h < 1$ we denote by $f^h(s)$ the density of the distribution of the stopping time $\rho^h = \inf\{t : |B(t)| = 1\}$, where B is a Brownian motion starting at $B(0) = 1 - h$.

Define

$$g(s) = \lim_{h\searrow 0} \frac{f^h(s)}{h}, \qquad s > 0.$$

It is well-known (e.g. [11, Exercise 2.2.8.11]) that there is an explicit representation of $f^h(s)$ as an infinite sum. By differentiation of each summand we obtain an explicit infinite sum representation also for $g(s)$ (see the appendix below).

The function g appears in the formulation of the subsequent lemma which will turn out to be of crucial relevance for our analysis.

Lemma 3.1. *Let $W : D \to \mathbb{R}^+$ be a continuous function such that*

(a) $b^* \mapsto W(t,b,b^*)$ is Lipschitz continuous and
(b) $W(t,1,1) - \sqrt{t}$ is decreasing.

Furthermore let $S \subseteq D$ be defined by $S_W := \{(t,b,|b|) \in D : t/b^2 \geqslant t_W\}$ for some fixed t_W. Consider a standard Brownian Motion $B(t)$ and define τ_W to be the first hitting time of S_W. Suppose that $X(t) := W(t,B(t),B^*(t))$ is a supermartingale and $X(t \wedge \tau_W)$ is a martingale. Further assume that the process $X(t \wedge \tau_W \wedge \sigma^h)$ is uniformly integrable where σ^h is given by $\sigma^h := \inf\{s \geqslant t : |B(s)| = 1 + h\}$.

Then,

(i)

$$W_{b*}(t,1,1) := \lim_{h \searrow 0} \frac{1}{h}[W(t,1,1+h) - W(t,1,1)] = 0 \tag{13}$$
$$\text{for } 0 < t < t_W$$

(ii)

$$W_b(t,1,1) := \lim_{h \searrow 0} \frac{1}{h}[W(t,1,1) - W(t,1-h,1] \tag{14}$$
$$= -\int_0^\infty [W(t+s,1,1) - W(t,1,1)]g(s)ds$$

Observe that (i) in the above Lemma would follow directly from Ito's formula if we assume that W is sufficiently differentiable by considering

$$dX(t) = (W_t + \tfrac{1}{2}W_{bb})dt + W_b dB(t) + W_{b*}dB^*(t) \tag{15}$$

which is the increment of a martingale. The process $dB^*(t)$ is non-decreasing and its variation is a.s. singular with respect to Lebesgue measure. A necessary condition for $(W(t,B(t),B^*(t)))_{\tau_W \geqslant t}$ to be a martingale therefore is that W_{b*} vanishes a.s. with respect to the variation measure of dB^*. This indicates that $W_{b*}(t,b,b^*) = 0$ should hold true whenever $|b| = b^*$ and (t,b,b^*) is in the non-stop region NS. In particular, we should have $W_{b*}(t,1,1) = 0$, for $t < t_W$.

Proof of 3.1. (i) For $h > 0$ as in (13) define, conditionally on $B(t) = 1$ and $B^*(t) = 1$, the stopping times

$$\sigma^h := \inf\{u \geqslant t : |B(u)| = 1 + h\} \qquad \text{and} \tag{16}$$
$$\tau^h := \sigma^h \wedge \tau_W. \tag{17}$$

Recall that the random variable τ_W is a stopping time with respect to the filtration $(\mathcal{G}^{(t)}(u))_{t \leqslant u}$. Note that the process $(u, B(u), B^*(u))_{u \geqslant t}$, starting at $B(t) = 1$ and $B^*(t) = 1 + h$, also remains in $D \backslash S_W$ up to the stopping time τ_W. To see this, we distinguish two cases:

(i) $t \leqslant u < \tau^h$: Here we have $B(u) < 1+h = B^*(u)$ and thus $(u, B(u), B^*(u)) \in D \backslash S_W$.

(ii) $\tau^h \leqslant u < \tau_W$: In this case $B^*(u)$ is the same for $B^*(t) = 1$ and $B^*(t) = 1+h$.

As $t < t_0$ we have that τ is a.s. strictly positive. This implies that

$$\lim_{h \searrow 0} \mathbb{P}[\sigma^h = \tau^h] = 1, \tag{18}$$

as $\lim_{h \searrow 0} \sigma^h = t$, almost surely.

We may write

$$\begin{aligned} &W(t,1,1+h) - W(t,1,1) \\ &\quad= \mathbb{E}^{(t,1,1+h)}[W(\tau^h, B(\tau^h), B^*(\tau^h))] - \mathbb{E}^{(t,1,1)}[W(\tau^h, B(\tau^h), B^*(\tau^h))] \\ &\quad= \mathbb{E}^{(t,1,1+h)}[W(\tau^h, B(\tau^h), 1+h)] - \mathbb{E}^{(t,1,1)}[W(\tau^h, B(\tau^h), B^*(\tau^h))]. \end{aligned} \tag{19}$$

Here we use that $B^*(\tau^h) = 1+h$ conditionally on $B^*(t) = 1+h$ as $\tau^h \leqslant \sigma^h$ by definition. Furthermore we make use of the martingale property of $W(t, B(t), B^*(t))$ and the optional stopping theorem. For the use of the latter we need the assumption that $(W(u \wedge \tau^h, B(u \wedge \tau^h), B^*(u \wedge \tau^h)))_{u \geqslant t}$ is uniformly integrable.

On the set $\{\sigma^h = \tau^h\}$ we have $B^*(\tau^h) = B^*(\sigma^h) = 1+h$ for both initial conditions $B(t) = 1, B^*(t) = 1+h$ and $B(t) = 1, B^*(t) = 1$. Therefore, the value $W(\tau^h, B(\tau^h), B^*(\tau^h))$ is the same under both initial conditions. It follows that

$$\begin{aligned} &\mathbb{E}^{(t,1,1+h)}[W(\tau^h, B(\tau^h), 1+h)\mathbb{1}_{\{\sigma^h = \tau^h\}}] \\ &\qquad - \mathbb{E}^{(t,1,1)}[W(\tau^h, B(\tau^h), B^*(\tau^h))\mathbb{1}_{\{\sigma^h = \tau^h\}}] = 0. \end{aligned}$$

On the remaining set $\{\tau^h < \sigma^h\}$ we have $B^*(\tau^h) \in [1, 1+h]$. Because W is Lipschitz continuous in the variable b^* with some constant L we may estimate

$$\begin{aligned} &\mathbb{E}^{(t,1,1+h)}[W(\tau^h, B(\tau^h), 1+h)\mathbb{1}_{\{\tau^h < \sigma^h\}}] \\ &\qquad - \mathbb{E}^{(t,1,1)}[W(\tau^h, B(\tau^h), B^*(\tau^h)\mathbb{1}_{\{\tau^h < \sigma^h\}}] \leqslant Lh\mathbb{P}[\tau^h < \sigma^h]. \end{aligned}$$

Dividing (19) by h and passing to the limit we obtain from (18) that

$$W_{b^*}(t,1,1) := \lim_{h \searrow 0} \frac{1}{h}[W(t,1,1+h) - W(t,1,1)] = 0$$

(ii) As X is a martingale before hitting S_W we have for ρ^h as above that

$$W(t, 1-h, 1) = \mathbb{E}^{(t,1-h,1)}[W(\rho^h, 1, 1)] = \int_0^\infty W(t+s, 1, 1) f^h(s) ds,$$

where the density f^h is given by

$$f^h(s) := \frac{1}{\sqrt{2\pi s^3}} \sum_{n=-\infty}^{\infty} \left[(4n+h)e^{-\frac{(4n+h)^2}{2s}} + (4n+2-h)e^{-\frac{(4n+2-h)^2}{2s}}\right]. \tag{20}$$

We can use this relation to calculate the derivative w.r.t. the second component:

$$-W_b(t,1,1) := \lim_{h\searrow 0} \frac{1}{h} \int_0^\infty [W(t+s,1,1) - W(t,1,1)] f^h(s) ds$$

We split this integral into two parts at some point $\alpha > 0$ and observe that $f^h(s)$ is continuous and $f^h(s) \searrow 0$ for $h \searrow 0$ pointwise at $s > 0$ and thus by Dini's Theorem also uniformly (monotone) on any interval $[\alpha, K]$, for $0 < h < h_0(\alpha)$. Therefore we have

$$\begin{aligned} &\lim_{h\searrow 0} \frac{1}{h} \int_\alpha^K [W(t+s,1,1) - W(t,1,1)] f^h(s) ds \\ &\quad = \int_\alpha^K [W(t+s,1,1) - W(t,1,1)] g(s) ds \end{aligned} \tag{21}$$

for g given by

$$g(s) := \lim_{h\searrow 0} \frac{f^h(s)}{h} = \frac{1}{\sqrt{2\pi s^3}} \left[1 + 2 \cdot \sum_{n=1}^\infty (-1)^n \left(1 - \frac{(2n)^2}{s}\right) e^{-\frac{(2n)^2}{2s}} \right]. \tag{22}$$

As before, because $u \mapsto W(u,1,1) - \sqrt{u}$ is decreasing and $s \mapsto \sqrt{t+s} - \sqrt{t}$ is concave, we have $W(t+s,1,1) - W(t,1,1) \leqslant \sqrt{t+s} - \sqrt{t} \leqslant s\frac{1}{2\sqrt{t}}$. Therefore the integrand is dominated by $\frac{sf^h(s)}{2\sqrt{t}h}$.

For $K > 0$ we can then estimate

$$\begin{aligned} \frac{1}{h} \int_K^\infty s f^h(s) ds &= \frac{1}{h} \mathbb{P}[\rho^h > K] \mathbb{E}[(B_{\rho^h} - B_0)^2 | \rho^h > K] \\ &= \mathbb{P}[\rho^h > K](2-h) \leqslant 2\mathbb{P}[\rho^h > K]. \end{aligned}$$

This probability tends to 0 uniformly in K, thus the integrals over $[K, \infty)$ can be neglected and we can replace K by ∞ in (21).

For the other part of the integral we first observe that

$$\begin{aligned} &\lim_{h\searrow 0} \frac{1}{h} \int_0^\alpha s f^h(s) ds \\ &\quad = \lim_{h\searrow 0} \frac{1}{h} \int_0^\infty s f^h(s) ds - \frac{1}{h} \int_\alpha^\infty s f^h(s) ds \\ &\quad = \lim_{h\searrow 0} \frac{1}{h} \mathbb{E}[\rho^h] - \frac{1}{h} \int_\alpha^\infty s f^h(s) ds \\ &\quad = \lim_{h\searrow 0} 2 - h - \frac{1}{h} \int_\alpha^\infty s f^h(s) ds = 2 - \int_\alpha^\infty s\, g(s) ds. \end{aligned}$$

The last integral converges to 2 for $\alpha \to 0$ by monotone convergence.

We conclude by setting $M \geqslant |W_t(u,1,1)|$ for $u \in [t, t+\alpha]$, making the estimate

$$\left|\frac{1}{h}\int_0^\alpha [W(t+s,1,1)-W(t,1,1)]f^h(s)ds\right| \leqslant \frac{M}{h}\int_0^\alpha sf^h(s)ds$$
$$\overset{h\to 0}{\to} M\left(2-\int_\alpha^\infty sg(s)ds\right),$$

and then taking the limit for $\alpha \to 0$. □

We can now apply this technical Lemma to our value function V by checking that the assumptions of the previous Lemma are satisfied by the value function V:

Lemma 3.2. *Let $V : D \to \mathbb{R}$ be the value function for (2). Then,*

(i)

$$V_{b*}(t,1,1) := \lim_{h\searrow 0}\frac{1}{h}[V(t,1,1+h)-V(t,1,1)] = 0 \tag{23}$$
$$\textit{for } 0<t<t_0$$

(ii)

$$\begin{aligned} V_b(t,1,1) &:= \lim_{h\searrow 0}\frac{1}{h}[V(t,1,1)-V(t,1-h,1] \\ &= -\int_0^\infty [V(t+s,1,1)-V(t,1,1)]g(s)ds \end{aligned} \tag{24}$$

Proof. V is continuous by Lemma 2.1 and Lipschitz-continuous in b^* by definition. We also have $V(t,1,1)-\sqrt{t}$ is decreasing by Lemma 2.1. Furthermore $V(t,B(t),B^*(t))$ is a martingale up to hitting S by Lemma 2.5. Thus, setting $W=V$, $S_W=S$ and $t_W=t_0$, it remains to check the required uniform integrability condition. We have

$$\begin{aligned} 0 \leqslant& V(u\wedge\tau^h, B(u\wedge\tau^h), B^*(u\wedge\tau^h)) \\ &\leqslant V(t, B(u\wedge\tau^h), B^*(u\wedge\tau^h)) + (\sqrt{u\wedge\tau^h}-\sqrt{t}) \\ &\leqslant V(t,0,1+h)+\sqrt{\tau^h} \leqslant V(t,0,1+h)+\frac{1}{4}+\tau^h. \end{aligned}$$

where the first estimate follows because the function $u \mapsto V(u,b,b^*)-\sqrt{u}$ is decreasing in u. The second inequality is due to the fact that V is decreasing in $|b|$ and increasing in b^* as well as $B^*(u\wedge\tau^h)\leqslant 1+h$. Now, $\tau^h \leqslant \sigma^h$ and σ^h has exponential moments and is therefore integrable which yields the desired uniform integrability.

Observe that τ^h is smaller than the first hitting time of the non-stop region NS no matter whether we condition on $(t,1,1)$ or $(t,1,1+h)$ which warrants the use of Lemma 2.5. □

The subsequent lemma shows that, for $t>t_0$, the behavior of V_b and V_{b*} follows a different pattern than the one given by Lemma 3.2. We find that

$$V_{b*}(t,1,1)+V_b(t,1,1) = -C \tag{25}$$

where we have to interpret this equation properly.

Lemma 3.3. *For $t > t_0$ we have*

$$\lim_{h \searrow 0} \frac{1}{h}[V(t, 1+h, 1+h) - V(t, 1, 1)] = -C. \tag{26}$$

Proof. For $t > t_0$ we have

$$V(t, b^*, b^*) = t^{\frac{1}{2}} - Cb^*,$$

for b^* in a neighbourhood of 1. □

To abbreviate notation we shall sometimes denote by $V(t)$ the function $V(t, 1, 1)$ (recall that we keep $C \geqslant \widehat{C}$ and the corresponding $t_0 = t_0(C)$ fixed). We thus obtain the following integro-differential equation for $V(t)$.

Lemma 3.4. *The function $V(t)$ satisfies the following equations*

$$2tV'(t) = V(t) + C, \qquad t > t_0, \tag{27}$$

$$2tV'(t) = V(t) + \int_0^\infty [V(t+s) - V(t)]g(s)ds, \qquad t < t_0. \tag{28}$$

Proof. The first assertion is obvious, as we have

$$V(t) = t^{\frac{1}{2}} - C, \quad \text{for} \quad t > t_0. \tag{29}$$

The second equation follows, at least formally, from (12), (23) and (24).

To justify (28) in a more pedantic way, note that for $a > 1$ we obtain from (7)

$$\begin{aligned} aV(t,1,1) - V(t,1,1) &= V(a^2t, a, a) - V(t,1,1) \\ &= (V(a^2t, a, a) - V(t, a, a)) \\ &+ (V(t, a, a) - V(t, 1, a)) \\ &+ (V(t, 1, a) - V(t, 1, 1)). \end{aligned}$$

Dividing by $a - 1$ and letting a decrease to 1, we deduce (28) from Lemma 3.2. □

Let us discuss the behaviour of the function $V(t)$ at $t = t_0$. As observed in the previous section, $V(t)$ is continuous so that we must have "continuous pasting" at t_0. It is the immediate reflex – at least it was so for the present authors – to expect *smooth pasting* of $V(t)$ at $t = t_0$ i.e. $\lim_{t \searrow t_0} V'(t) = \lim_{t \nearrow t_0} V'(t)$. By (27) and (28) this would result in determining t_0 by equating C with $\int_0^\infty (V(t_0 + s) - V(t_0))g(s)ds$. To our big surprise this turned out *not* to be the case; after some time of reconsidering we had to conclude that there is little reason why the smooth pasting principle should prevail in the present context. Here is one intuitive reason: for a fixed number $t_0 > 0$ we have that for almost all trajectories of a Brownian motion $B = (B(t))_{t \geqslant 0}$, starting at $B(0) = 0$, there is no $t > 0$ such that the two equalities $|B(t)| = B^*(t) = (\frac{t}{t_0})^{\frac{1}{2}}$ are simultaneously verified. By Lemma 2.4 we conclude that a discontinuity of the derivatives of $V(t, B(t), B^*(t))$ can only take place where these two equations are simultaneously satisfied. Roughly speaking: the Brownian motion B "*does not see*" a kink of the function $V(t)$ at $t = t_0$.

As a matter of fact, this natural example of a case of *non-smooth pasting* in the case of continuous martingales seems to us a remarkable feature of the present paper. The literature on *non-smooth pasting* is generally revolving around non-continuous processes. Some examples of non-smooth pasting for processes with jumps can be found in [1], [2], [6], [9] and [14].

4. The Integro-Differential-Equation

Fix the parameters $C > 0$ and $t_0 > 0$. We consider the ordinary integro-differential equation for the function $U = U^{C,t_0}$

$$U(t) = t^{\frac{1}{2}} - C, \qquad t \geqslant t_0, \tag{30}$$

$$2tU'(t) = U(t) + \int_0^\infty [U(t+s) - U(t)]g(s)ds, \qquad 0 < t \leqslant t_0, \tag{31}$$

where g is given by (22).

Here the fixed behaviour (30) of $U(t)$, for $t \geqslant t_0$, is considered as the initial condition, and subsequently the OIDE (ordinary integro-differential equation) (31) is solved by letting t decrease from t_0 to 0. For $t = t_0$, the derivative $U'(t_0)$ in (31) is understood as the *left* limit of $U'(t)$ when t increases to t_0.

It is standard to verify that, for $C > 0, t_0 > 0$, and $\epsilon > 0$ the solution U^{C,t_0} of (30) is well-defined for $t \in [\epsilon, \infty)$ and depends smoothly on the parameters C and t_0. On the other hand, the $2t$ term on the left hand side of (31) indicates that only for special cases of C and t_0 this solution can be extended to a continuous and finitely valued function $U(t)$, defined for all $t \in [0, \infty)$.

The evidence resulting from our numerical analysis of the solutions $(U^{C,t_0}(t))_{t>0}$, in dependence of C and t_0, can be resumed as follows:

Numerical Evidence 4.1.

(i) There is a smallest number $\check{C} > 0$ as well as a unique number $\check{t}_0 > 0$ such that the OIDE (31) admits a solution $U^{\check{C},\check{t}_0}(t)$ which has a finite limit $\lim_{t\to 0} U^{\check{C},\check{t}_0}(t)$. This solution is monotone increasing and $U^{\check{C},\check{t}_0}(t) \geqslant t^{\frac{1}{2}} - \check{C}$.

(ii) For $0 < C < \check{C}$ there does not exist $t_0 > 0$ such that $U(t) = U^{C,t_0}(t)$ remains bounded from below as $t \searrow 0$.

(iii) For $C > \check{C}$ there are precisely two values $t_1 = t_1(C), t_2 = t_2(C)$ depending on C in a continuous and one-to-one way such that $U^{C,t_i}(t)$ has a finite limit, as $t \searrow 0$, for $i = 1, 2$. These solutions satisfy $U^{C,t_i}(t) \geqslant t^{\frac{1}{2}} - C$.
For $t_0 \in (t_1, t_2)$, the solutions of the OIDE (31) tend to $+\infty$, for $t \searrow 0$, while, for $t_0 \notin [t_1, t_2]$, the solutions tend to $-\infty$, for $t \searrow 0$. We have $t_1(C) < \check{t}_0 < t_2(C)$ and $\lim_{C\to\check{C}} t_1(C) = \lim_{C\to\check{C}} t_2(C) = \check{t}_0$.