

Finite-strain Poynting-Thomson model: Existence and linearization

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Joint work with Martin Kružík (Czech Academy of Sciences)
and Ulisse Stefanelli (University of Vienna)

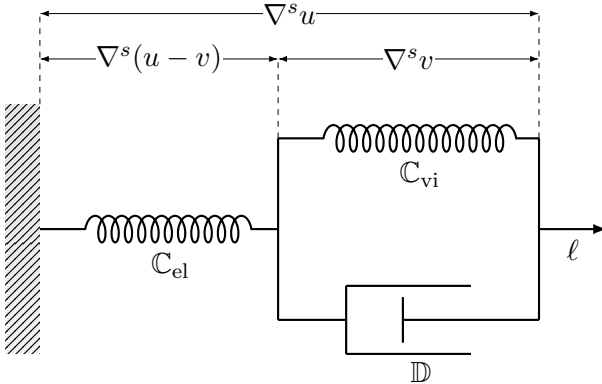
22nd GAMM Seminar on Microstructures

28/01/2023



- Preliminaries
 - Assumptions
 - Energy and Dissipation
- Existence

What's our problem?

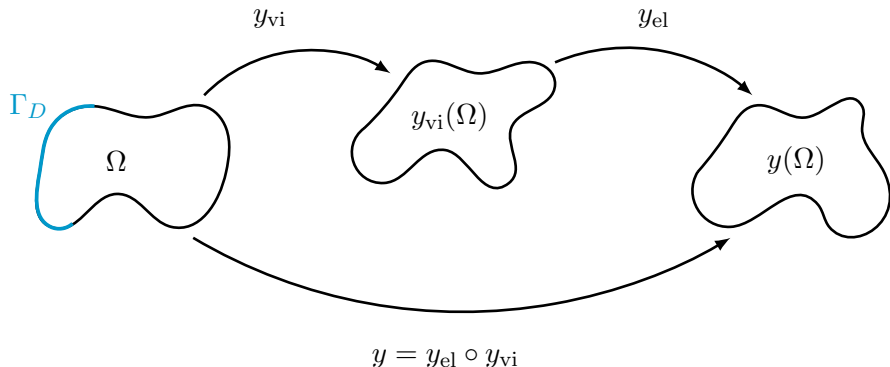


$$\begin{cases} -\operatorname{div}(\mathbb{C}_{el} \nabla(u - v)) = \ell & \text{in } \Omega \\ -\operatorname{div}(\mathbb{D} \nabla \dot{v} + \mathbb{C}_{vi} \nabla v) = \ell & \text{in } \Omega \end{cases}$$

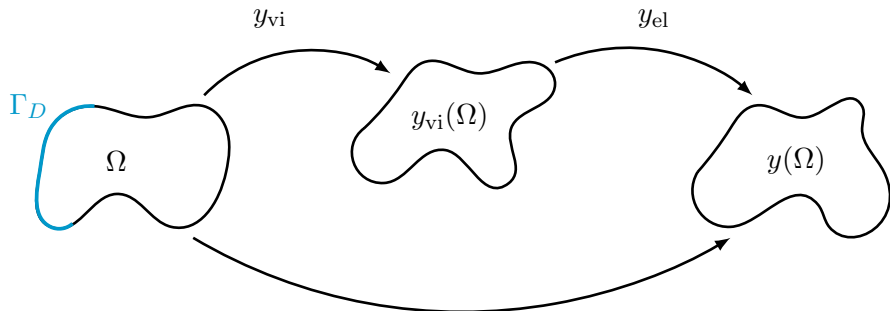
Preliminaries

Domains and Deformations

$\Omega \subset \mathbb{R}^d$ non empty, Lipschitz domain



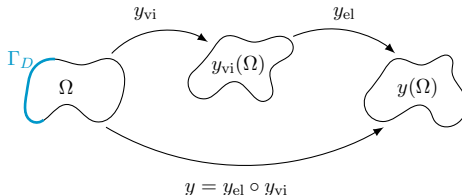
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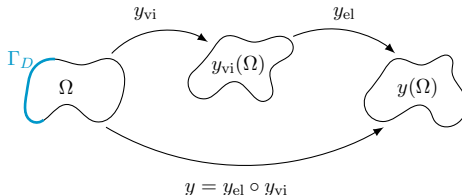
$$y = y_{el} \circ y_{vi}$$

$$\nabla y = F_{el} F_{vi}$$

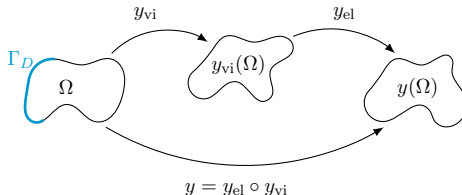
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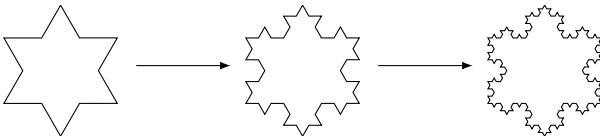
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- y_{vi} viscous deformation:

- $y_{vi} \in W^{1,p_{vi}}(\Omega; \mathbb{R}^d)$, $p_{vi} > d(d-1)$
- $\det \nabla y_{vi} = 1$ a.e. in Ω (locally volume preserving)

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disappears in
change of variable

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Total energy of the system:

$$\mathcal{E}(t, y_{\text{el}}, y_{\text{vi}}) := \underbrace{\mathcal{W}(y_{\text{el}}, y_{\text{vi}})}_{\text{Stored energy}} - \underbrace{\langle \ell(t), y_{\text{el}} \circ y_{\text{vi}} \rangle}_{\text{work of external actions}}$$

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- $W_{\text{el}} : \mathbb{R}^{d \times d} \rightarrow \mathbb{R}$ polyconvex
- $c_1 |A|^{p_{\text{el}}} \leq W_{\text{el}}(A) \leq \frac{1}{c_1} (1 + |A|^{p_{\text{el}}})$
- $W_{\text{vi}} : \mathbb{R}^{d \times d} \rightarrow \overline{\mathbb{R}}$ polyconvex
- $W_{\text{vi}}(A) \geq \begin{cases} c_2 |A|^{p_{\text{vi}}} - \frac{1}{c_2} & A \in SL(d) \\ \infty & \text{otherwise} \end{cases}$

Instantaneous dissipation of the system:

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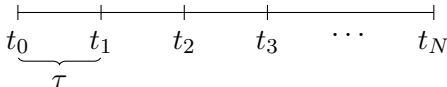
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$$\left. \begin{array}{l} \bullet \psi : \mathbb{R}^{d \times d} \rightarrow \mathbb{R} \text{ convex, differentiable at } 0 \\ \bullet \psi(A) \geq c_3 |A|^{p_\psi} \\ \bullet \psi(\lambda A) = |\lambda|^{p_\psi} \psi(A) \end{array} \right\} \rightsquigarrow \psi(A) := \frac{|A|^{p_\psi}}{p_\psi}$$

Existence

The Time Discretization Scheme

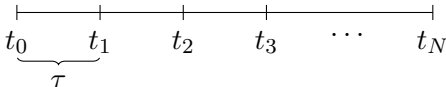
- $\Pi_\tau := \{0 = t_0 < t_1 < \dots < t_N = T\}$, $t_i - t_{i-1} = \tau = T/N$



- $(y_{\text{el}}^0, y_{\text{vi}}^0)$ compatible initial condition

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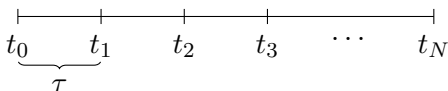
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Incremental minimization problem, $i = 1, \dots, N$:

$$\inf_{(y_{\text{el}}, y_{\text{vi}}) \in \mathcal{A}} \left\{ \mathcal{E}(t_i, y_{\text{el}}, y_{\text{vi}}) + \int_{\Omega} \tau \psi \left(\frac{\nabla(y_{\text{vi}} - y_{\text{vi}}^{i-1})}{\tau} (\nabla y_{\text{vi}}^{i-1})^{-1} \right) \right\} \quad (IP)$$

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Theorem

Problem (IP) admits minimizers (not unique).

Theorem (C.-Kružík-Stefanelli)

Given $(y_{\text{el}}^0, y_{\text{vi}}^0) \in \mathcal{A}$, for any sequence $(\Pi_\tau)_\tau$ of partitions of the interval $[0, T]$ with mesh sizes $\tau \rightarrow 0$, there exist a (not relabeled) subsequence and functions $(y_{\text{el}}, y_{\text{vi}}) : [0, T] \rightarrow \mathcal{A}$ such that, for a.e. $t \in [0, T]$,

- [Approximation]

$$(\bar{y}_{\text{el},\tau}(t), \bar{y}_{\text{vi},\tau}(t)) \rightharpoonup (y_{\text{el}}(t), y_{\text{vi}}(t)) \quad \text{in } \mathcal{A},$$

- [Energy inequality]

$$\mathcal{E}(t, y_{\text{el}}(t), y_{\text{vi}}(t)) + \textcolor{red}{p}_\psi \int_0^t \Psi(s, y_{\text{vi}}(s)) \, ds \leq \mathcal{E}(0, y_{\text{el}}^0, y_{\text{vi}}^0) - \int_0^t \langle \dot{\ell}(s), y(s) \rangle \, ds,$$

- [Semistability]

$$\mathcal{E}(t, y_{\text{el}}(t), y_{\text{vi}}(t)) \leq \mathcal{E}(t, \tilde{y}_{\text{el}}, y_{\text{vi}}(t)) \quad \forall \tilde{y}_{\text{el}} \text{ with } (\tilde{y}_{\text{el}}, y_{\text{vi}}(t)) \in \mathcal{A}.$$



“Naive” Energy Inequality

$$\mathcal{E}(t, y_{\text{el}}(t), y_{\text{vi}}(t)) + \int_0^t \Psi(s, y_{\text{vi}}(s)) \, ds \leq \mathcal{E}(0, y_{\text{el}}^0, y_{\text{vi}}^0) - \int_0^t \langle \dot{\ell}(s), y(s) \rangle \, ds$$

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$$\begin{aligned} \mathcal{E}(t_i, y_{\text{el}}^i, y_{\text{vi}}^i) + \int_{\Omega} \tau \psi \left(\frac{\nabla(y_{\text{vi}}^i - y_{\text{vi}}^{i-1})}{\tau} (\nabla y_{\text{vi}}^{i-1})^{-1} \right) &\stackrel{\text{min}}{\leq} \mathcal{E}(t_i, y_{\text{el}}^{i-1}, y_{\text{vi}}^{i-1}) \\ &= \mathcal{E}(t_{i-1}, y_{\text{el}}^{i-1}, y_{\text{vi}}^{i-1}) - \int_{t_{i-1}}^{t_i} \langle \dot{\ell}, y^{i-1} \rangle \end{aligned}$$

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Summing up $\Downarrow i = 1, \dots, n$

$$\begin{aligned} \mathcal{E}(t_n, y_{\text{el}}^n, y_{\text{vi}}^n) + \sum_{i=1}^n \int_{\Omega} \tau \psi \left(\frac{\nabla(y_{\text{vi}}^i - y_{\text{vi}}^{i-1})}{\tau} (\nabla y_{\text{vi}}^{i-1})^{-1} \right) \\ \leq \mathcal{E}(0, y_{\text{el}}^0, y_{\text{vi}}^0) - \sum_{i=1}^n \int_{t_{i-1}}^{t_i} \langle \dot{\ell}, y^{i-1} \rangle \end{aligned}$$



Sharp Energy Inequality

$$\mathcal{E}(t, y_{\text{el}}(t), y_{\text{vi}}(t)) + p_{\psi} \int_0^t \Psi(s, y_{\text{vi}}(s)) \, ds \leq \mathcal{E}(0, y_{\text{el}}^0, y_{\text{vi}}^0) - \int_0^t \langle \dot{\ell}(s), y(s) \rangle \, ds$$



Sharp Energy Inequality

$$\mathcal{E}(t, y_{\text{el}}(t), y_{\text{vi}}(t)) + 2 \int_0^t \Psi(s, y_{\text{vi}}(s)) \, ds \leq \mathcal{E}(0, y_{\text{el}}^0, y_{\text{vi}}^0) - \int_0^t \langle \dot{\ell}(s), y(s) \rangle \, ds$$

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$$\Phi(\tau; y_{\text{old}}, y_{\text{el}}, y_{\text{vi}}) := \mathcal{E}(t_i, y_{\text{el}}, y_{\text{vi}}) + \tau \Psi \left(y_{\text{old}}, \frac{y_{\text{vi}} - y_{\text{old}}}{\tau} \right)$$

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Main reference:

- [1] A. Chiesa, M. Kružík, U. Stefanelli, Finite-strain Poynting-Thomson model: Existence and linearization. *Soon on ArXiv*.

Additional references:

- [2] M. Kružík, D. Melching, U. Stefanelli, Quasistatic evolution for dislocation-free finite plasticity. *ESAIM Control Optim. Calc. Var.* 26 (2020), Paper No. 123.
- [3] M. Kružík, T. Roubíček, *Mathematical methods in continuum mechanics of solids*, Interaction of Mechanics and Mathematics, Springer, Cham, 2019.
- [4] A. Mielke, U. Stefanelli, Linearized plasticity is the evolutionary Γ -limit of finite plasticity. *J. Eur. Math. Soc. (JEMS)*, 15 (2013), no. 3, pp. 923–948.

Thank you for your attention!
