

Viscoelasticity and Growth

Andrea Chiesa

Oberwolfach Workshop
Singularities in Discrete Systems

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universität
wien

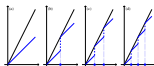


Taming Complexity in
Partial Differential Systems



Vienna School
of Mathematics

Torino



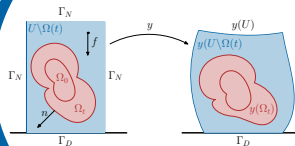
StrD

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Viscoelastic growth

U. Stefanelli

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MCF

K. Takasao

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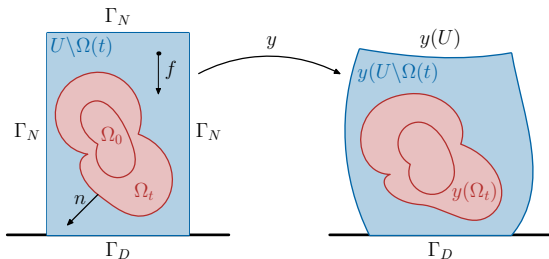
K. Švadlenka

Deformation

$$y: U \rightarrow \mathbb{R}^d$$

Accretion

$$\Omega(t) := \{\theta(x) < t\}$$



$$\begin{aligned} -\operatorname{div}(\partial_F W^a(\nabla y) + \partial_{\dot{F}} R^a(\nabla y, \nabla \dot{y}) - \operatorname{div} DH(\nabla^2 y)) &= f && \text{in } [0, T] \times \Omega(t) \\ -\operatorname{div}(\partial_F W^r(\nabla y) + \partial_{\dot{F}} R^r(\nabla y, \nabla \dot{y}) - \operatorname{div} DH(\nabla^2 y)) &= f && \text{in } [0, T] \times (U \setminus \overline{\Omega(t)}) \end{aligned}$$

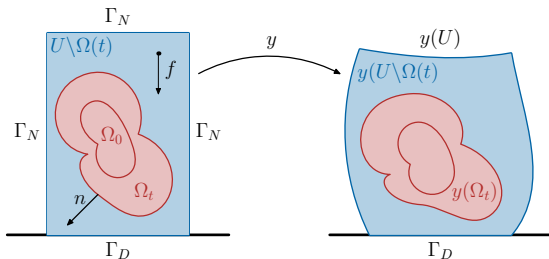
$$\gamma(y(\theta(x), x), \nabla y(\theta(x), x)) | \nabla \theta(x) | = 1 \quad \text{in } U \setminus \overline{\Omega_0}$$

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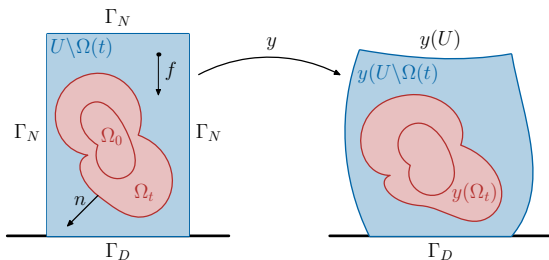
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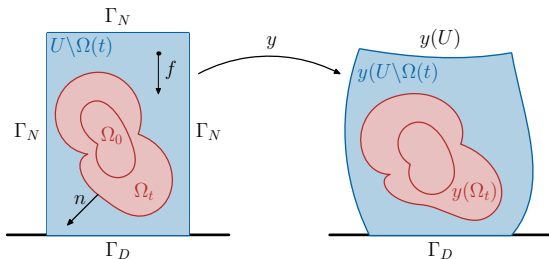
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Theorem (C.-Stefanelli, 2025)

There exist a solution $(y, \theta) \in C^1([0, T] \times U; \mathbb{R}^d) \times C^{0,1}(U)$ to the system satisfying the Energy Equality

$$\begin{aligned}
& \int_U (W^a(\nabla y) \mathbb{1}_{\Omega(t)} + W^r(\nabla y) \mathbb{1}_{U \setminus \Omega(t)} + H(\nabla^2 y) - f \cdot y) \, dx - E_0 \\
& = - \int_0^t \int_U (2R^a(\nabla y, \nabla \dot{y}) \mathbb{1}_{\Omega(t)} + 2R^r(\nabla y, \nabla \dot{y}) \mathbb{1}_{U \setminus \Omega(t)} + \dot{f} \cdot y) \, dx \, ds \\
& \quad + \int_0^t \int_{\{\theta=s\}} \frac{W^a(\nabla y) - W^r(\nabla y)}{|\nabla \theta|} \, d\mathcal{H}^{d-1} \, ds.
\end{aligned}$$

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- A. Chiesa, U. Stefanelli. Viscoelasticity and accretive phase-change at finite strains. *Z. Angew. Math. Phys.* 76, 53 (2025)

Thank you for your attention!