

Finite-strain Poynting-Thomson model: Existence and linearization

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Joint work with Martin Kružík (Czech Academy of Sciences)
and Ulisse Stefanelli (University of Vienna)

2nd Austrian Calculus of Variations Day





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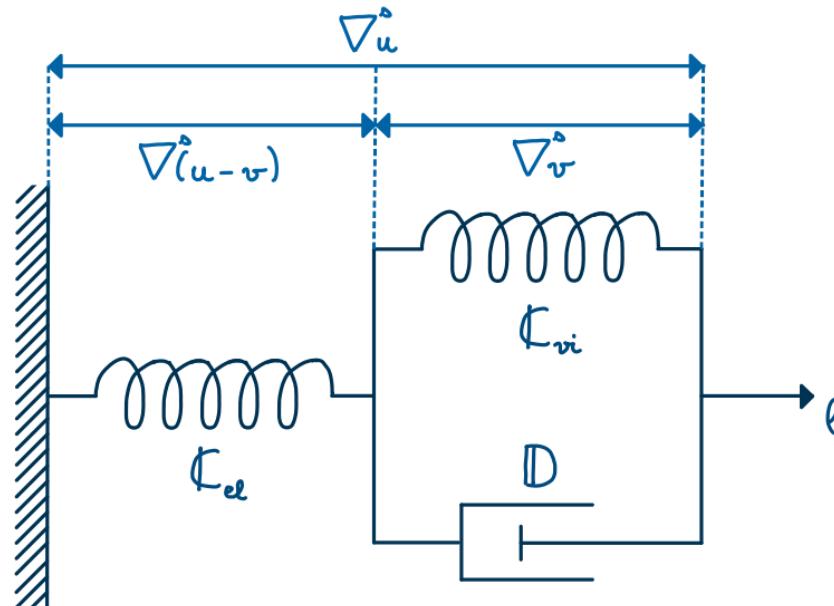


Outline

- Preliminaries
 - Assumptions
 - Energy and Dissipation
- Existence
- Linearization



What's our problem?

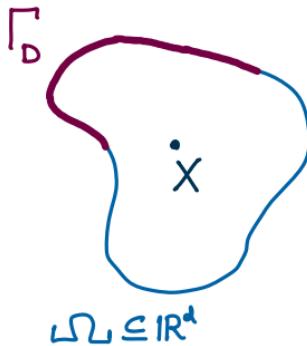


$$\begin{cases} -\operatorname{div}(\mathbb{D}\nabla^s \ddot{v} + C_{vv}\nabla^s v) = l \\ -\operatorname{div}(C_{el}\nabla^s(u-v)) = l \end{cases}$$

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Domains and Deformations

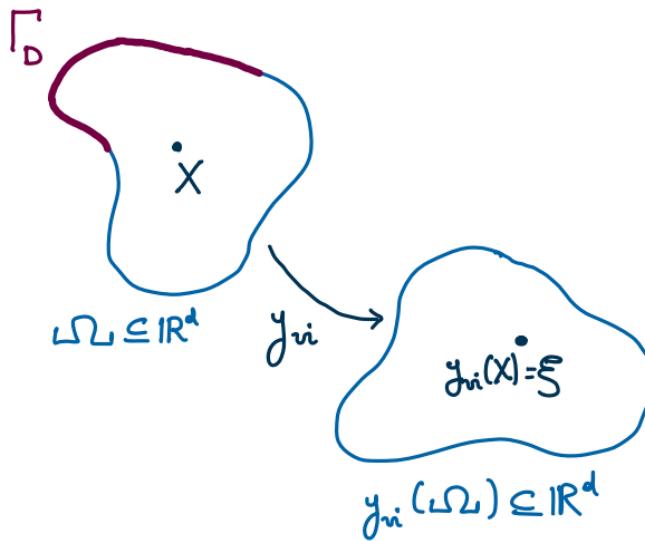
$\Omega \subseteq \mathbb{R}^d$ $\xrightarrow{d \geq 2}$
non empty, open, connected, Lipschitz





Domains and Deformations

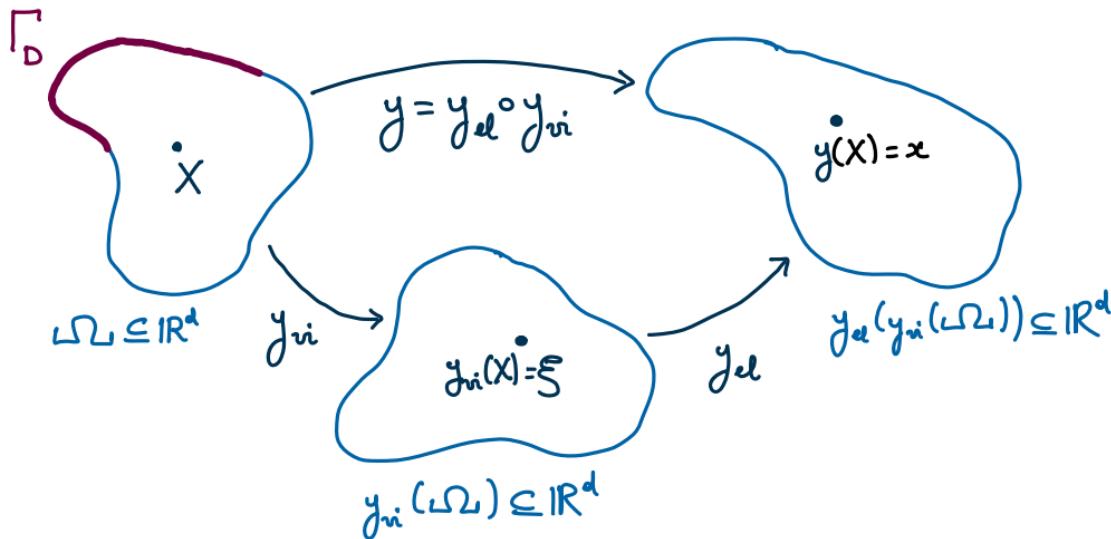
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Domains and Deformations

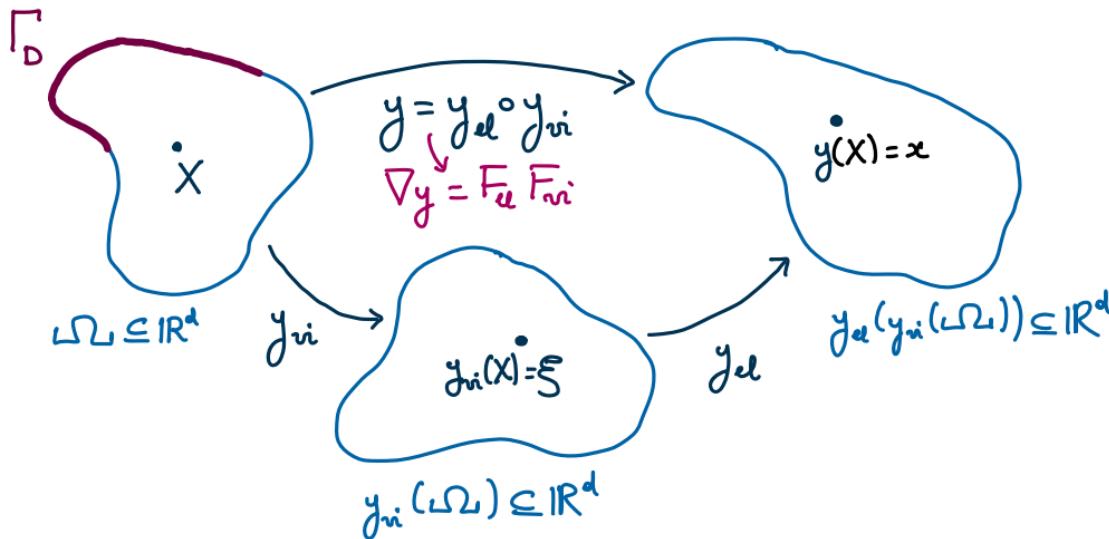
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Domains and Deformations

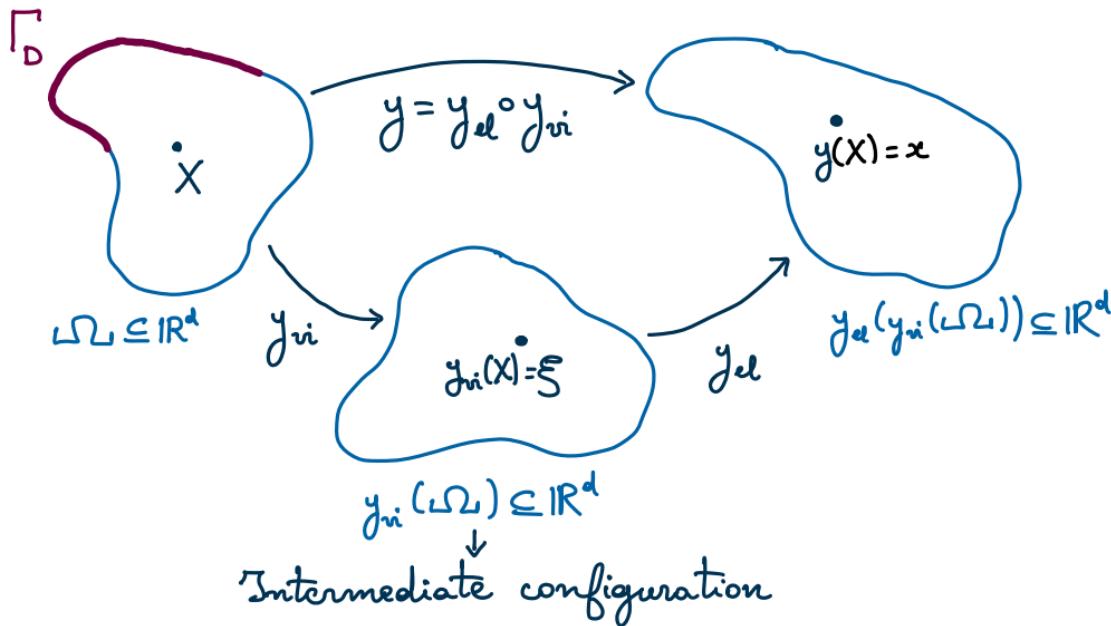
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Domains and Deformations

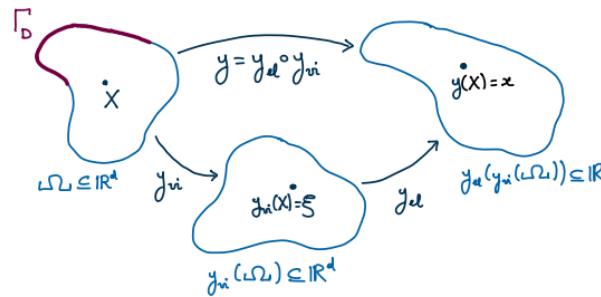
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Domains and Deformations

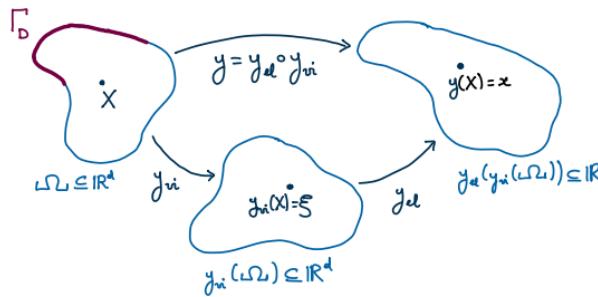
- $y_{vi}(\Omega) \rightarrow$ some regularity required





Domains and Deformations

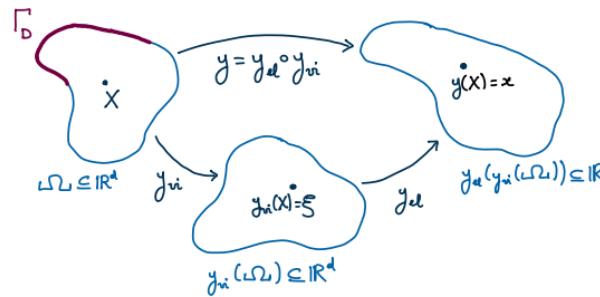
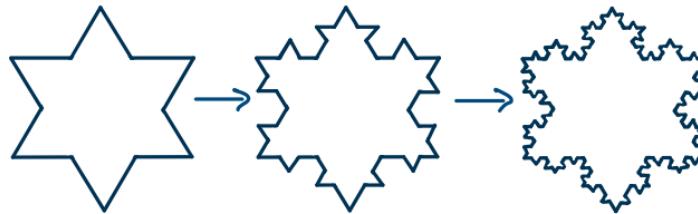
- $y_{\nu_i}(\Omega_i) \rightarrow$ some regularity required
 - Sobolev extension domains
 - closed under Hausdorff convergence





Domains and Deformations

- $y_{\text{in}}(\Omega)$ → some regularity required
 - Sobolev extension domains
 - closed under Hausdorff convergence

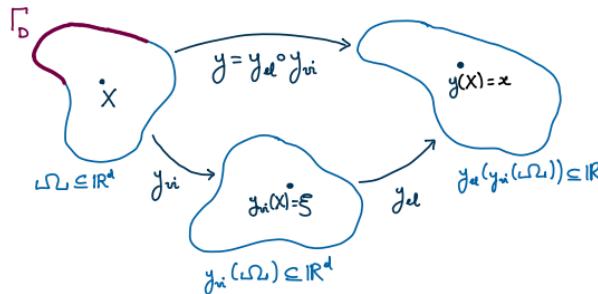




Domains and Deformations

- $y_{\text{in}}(\Omega)$ → some regularity required
 - Sobolev extension domains
 - closed under Hausdorff convergence

e.g.) Uniformly Lipschitz or (ε, δ) -domains





y_{vi} viscous deformation

- $y_{vi} \in W^{1,p_{vi}}(\Omega_1; \mathbb{R}^d)$, $p_{vi} > d(d-1)$
- $\det \nabla y_{vi} = 1$ a.e in Ω_1 (locally volume preserving)



Admissible states: viscous deformations

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- $y_{vi} \in W^{1,p_{vi}}(\Omega_1; \mathbb{R}^d)$, $p_{vi} > d(d-1)$

- $\det \nabla y_{vi} = 1$ a.e in Ω_1 (locally volume preserving)

↑
disappears in
change of variables

→ we cannot ask it for the elastic deformation

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Admissible states: viscous deformations

y_{vi} viscous deformation

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- y_{vi} homeomorphism
- y_{vi} locally invertible
- Chain rule

$$\nabla y(x) = \nabla y_{\infty}(y_{vi}(x)) \nabla y_{vi}(x)$$



y_{vi} viscous deformation

- $y_{vi} \in W^{1,p_{vi}}(\Omega_1; \mathbb{R}^d)$, $p_{vi} > d(d-1)$
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- y_{vi} homeomorphism
- y_{vi} locally invertible
- Chain rule

$$\begin{aligned}\nabla y(x) &= \nabla y_{\infty}(y_{vi}(x)) \nabla y_{vi}(x) \\ \hookrightarrow \nabla y &= F_u F_{vi}\end{aligned}$$



Admissible states: viscous deformations

y_{vi} viscous deformation

- $y_{vi} \in W^{1,p_{vi}}(\Omega_1; \mathbb{R}^d)$, $p_{vi} > d(d-1)$
- $\det \nabla y_{vi} = 1$ a.e in Ω_1 (locally volume preserving)
- other assumptions

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Energy

Total energy of the system:

$$E(t, y_e, y_n) := \underbrace{W(y_e, y_n)}_{\text{Stored energy}} - \underbrace{\langle l(t), y_e \circ y_n \rangle}_{\substack{\text{work of external actions} \\ \downarrow}} + \cdot l \in W^{1,2}(0, T; W^{1,1}(\Omega; \mathbb{R}^d))^*$$

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Energy

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$$W(y_{el}, y_{vi}) := \underbrace{\int_{y_{vi}(\Omega_1)} W_{el}(\nabla y_{el}(\xi)) d\xi}_{\text{stored elastic energy}} + \underbrace{\int_{\Omega_2} W_{vi}(\nabla y_{vi}(x)) dx}_{\text{stored viscous energy}}$$



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NO second gradient $\nabla^2 y_{vi}$

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Energy

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$$E(t, y_{ee}, y_{ni}) := \underbrace{W(y_{ee}, y_{ni})}_{\text{Stored energy}} - \underbrace{\langle l(t), y_{ee} \circ y_{ni} \rangle}_{\text{work of external actions}}$$

$$W(y_{ee}, y_{ni}) := \underbrace{\int_{y_{ni}(\Omega)} W_{ee}(\nabla y_{ee}(\xi)) d\xi}_{\text{stored elastic energy}} + \underbrace{\int_{\Omega} W_{ni}(\nabla y_{ni}(x)) dx}_{\text{stored viscous energy}}$$

- $W_{ee} : \mathbb{R}^{d \times d} \rightarrow \mathbb{R}$ polyconvex

$$0 \leq c|A|^p \leq W_{ee}(A) \leq \frac{1}{c}(1+|A|^m)$$

- $W_{ni} : \mathbb{R}^{d \times d} \rightarrow \overline{\mathbb{R}}$ polyconvex

$$W_{ni}(A) \geq \begin{cases} c|A|^{p_n} - \frac{1}{c} & A \in \text{SL}(d) \\ \infty & \text{otherwise} \end{cases}$$



Energy

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- $W_{ee} : \mathbb{R}^{dxd} \rightarrow \mathbb{R}$ polyconvex

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- $W_{ni} : \mathbb{R}^{dxd} \rightarrow \overline{\mathbb{R}}$ polyconvex, closed

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weakly lower semicontinuous



Energy

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- $0 \leq c|A|^p \leq W_{ee}(A) \leq \frac{1}{c}(1+|A|^m)$

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- $W_{ni}(A) \geq \begin{cases} c|A|^p - \frac{1}{c} & A \in SL(d) \\ \infty & \text{otherwise} \end{cases}$

we cannot impose $W_{ee} = +\infty$ when $\det A \leq 0$! weakly lower semicontinuous

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Dissipation

Dissipation of the system

$$\Psi(t, \nabla y_{ni}, \nabla \dot{y}_{ni}) := \int_{\Omega} \psi(\nabla y_{ni}, \nabla \dot{y}_{ni}^{-1}) dx$$

$$\downarrow$$
$$\psi(A) := \frac{|A|^{p_p}}{p_p}$$

• convex
• $\int \psi$ w.r.t.
 $\psi \geq \psi(0) = 0$

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Dissipation

Dissipation of the system

$$\Psi(t, \nabla y_{ni}, \nabla y_{ni}^{-1}) := \int_{\Omega} \psi(\nabla y_{ni}, \nabla y_{ni}^{-1}) \, dx$$

$$\psi(A) := \frac{|A|^{p_\psi}}{p_\psi} \quad \begin{array}{l} \text{convex} \\ : \int \psi \text{ w.r.t. } \lambda \\ : \psi \geq \psi(0) = 0 \end{array}$$



$$\bullet |\nabla y_{ni}| \leq \underbrace{|\nabla y_{ni} \nabla y_{ni}^{-1}|}_{\in L^{p_\psi}} \underbrace{|\nabla y_{ni}^{-1}|}_{\in L^{p_n}} \in L^{p_n} \quad \frac{1}{p_n} = \frac{1}{p_\psi} + \frac{1}{p_{ni}} < 1$$

p_ψ must be
"large enough"

Existence



Time-discretization scheme

- $\mathcal{T}_\tau := \{0 = t_0 < t_1 < \dots < t_N = T\} \quad t_i - t_{i-1} = \tau = \frac{T}{N}$



- $(y_{el}^0, y_{vi}^0) \in \mathcal{K}$ compatible initial condition
 $E(0, y_{el}^0, y_{vi}^0) < \infty$

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Time-discretization scheme

- $\mathcal{T}_\tau := \{0 = t_0 < t_1 < \dots < t_N = T\} \quad t_i - t_{i-1} = \tau = \frac{T}{N}$



- $(y_\alpha^0, y_{\alpha i}^0) \in \mathcal{A}$ compatible initial condition

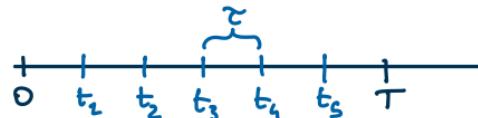
Incremental minimization problem, $i = 1, \dots, N$

$$\inf_{(y_\alpha, y_{\alpha i}) \in \mathcal{A}} \left\{ \mathcal{E}(t_i, y_\alpha, y_{\alpha i}) + \int_{t_{i-1}}^{t_i} \tau \psi \left(\frac{\nabla(y_{\alpha i} - y_{\alpha i}^{i-1})}{\tau} (\nabla y_{\alpha i}^{i-1})^{-1} \right) \right\} \quad (\text{IP})$$

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Incremental minimization problem, $i = 1, \dots, N$

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*finite difference
instead of ∇y_n*



Time-discretization scheme

- $\mathcal{T}_\tau := \{0 = t_0 < t_1 < \dots < t_N = T\} \quad t_i - t_{i-1} = \tau = \frac{T}{N}$



- $(y_d^0, y_u^0) \in \mathcal{A}$ compatible initial condition

Incremental minimization problem, $i = 1, \dots, N$

$$\inf_{(y_d, y_u) \in \mathcal{A}} \left\{ \mathcal{E}(t_i, y_d, y_u) + \int_{t_{i-1}}^{t_i} \tau \psi \left(\frac{\nabla(y_u - y_u^{i-1})}{\tau} (\nabla y_u^{i-1})^{-1} \right) \right\} \quad (\text{IP})$$

Theorem (IP) admits minimizers (not unique)



A "weaker" solution for the continuum problem

Theorem ("Existence" for the continuum problem)

Given $(y_{el}^0, y_{in}^0) \in \mathcal{A}$, for any sequence $(\Pi_\varepsilon)_\varepsilon$ of partitions of the interval $[0, T]$ with mesh sizes $\varepsilon \rightarrow 0$, there exist a subsequence $(\Pi_{\varepsilon_n})_{n \in \mathbb{N}}$ and functions $(y_{el}, y_{in}): [0, T] \rightarrow \mathcal{A}$ such that, for a.e. $t \in [0, T]$,

- Approximability

$$(y_{el}^{\varepsilon_n}(t), y_{in}^{\varepsilon_n}(t)) \xrightarrow{n \rightarrow \infty} (y_{el}(t), y_{in}(t)) \quad \text{in } \mathcal{A}$$

constant interpolant
of the incremental solutions
corresponding to Π_{ε_n}



A "weaker" solution for the continuum problem

Theorem ("Existence" for the continuum problem)

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- Approximability

$$(y_{el}^{\varepsilon_k}(t), y_{ni}^{\varepsilon_k}(t)) \xrightarrow{k \rightarrow \infty} (y_{el}(t), y_{ni}(t)) \quad \text{in } \mathcal{A}$$

- Energy inequality

$$\mathcal{E}(t, y_{el}(t), y_{ni}(t)) + \int_0^t \Psi(s, y_{ni}(s)) ds \leq \mathcal{E}(0) - \int_0^t \langle \dot{e}(s), y(s) \rangle ds$$



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- Approximability

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- Semicontinuity

$$\mathcal{E}(t, y_{el}(t), y_{ni}(t)) \leq \mathcal{E}(t, \tilde{y}_{el}, y_{ni}(t)) \quad \forall \tilde{y}_{el} \text{ s.t. } (\tilde{y}_{el}, y_{ni}(t)) \in \mathcal{A}$$

Linearization

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Linearization

Define:

$$v := \frac{y_{ri} - id_n}{\varepsilon} \quad u := \frac{y_{re} - id_n}{\varepsilon}$$

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Linearization

Define:

$$v := \frac{y_{ni} - id_n}{\varepsilon} \quad u := \frac{y_{el} - id_n}{\varepsilon}$$

By Taylor expansion we expect:

$$\underbrace{\left(\frac{1}{\varepsilon^2}\int_{\Omega} W_{el}\left(\underbrace{(\mathbf{I} + \varepsilon \nabla u)}_{\nabla y}, \underbrace{(\mathbf{I} + \varepsilon \nabla v)^{-1}}_{(\nabla y_{ni})^{-1}}\right)\right)}_{\text{rescaling}} \longrightarrow \frac{1}{2} \int_{\Omega} C_{el} \nabla(u-v) : \nabla(u-v)$$



Define:

$$v := \frac{y_{vi} - id_n}{\varepsilon} \quad u := \frac{y_{el} - id_n}{\varepsilon}$$

By Taylor expansion we expect:

$$\begin{aligned} & \left(\frac{1}{\varepsilon^2} \int_{\Omega} W_{el} \left(\underbrace{(\mathbf{I} + \varepsilon \nabla u)}_{\nabla y} \left(\underbrace{\mathbf{I} + \varepsilon \nabla v}_{(\nabla y_{vi})^{-1}} \right)^{-1} \right) \right) \longrightarrow \frac{1}{2} \int_{\Omega} C_{el} \nabla(u-v) : \nabla(u-v) \\ & \text{rescaling} \\ & \frac{1}{\varepsilon^2} \int_{\Omega} W_{vi} (\mathbf{I} + \varepsilon \nabla v) \longrightarrow \frac{1}{2} \int_{\Omega} C_{vi} \nabla v : \nabla v \end{aligned}$$



Linearization

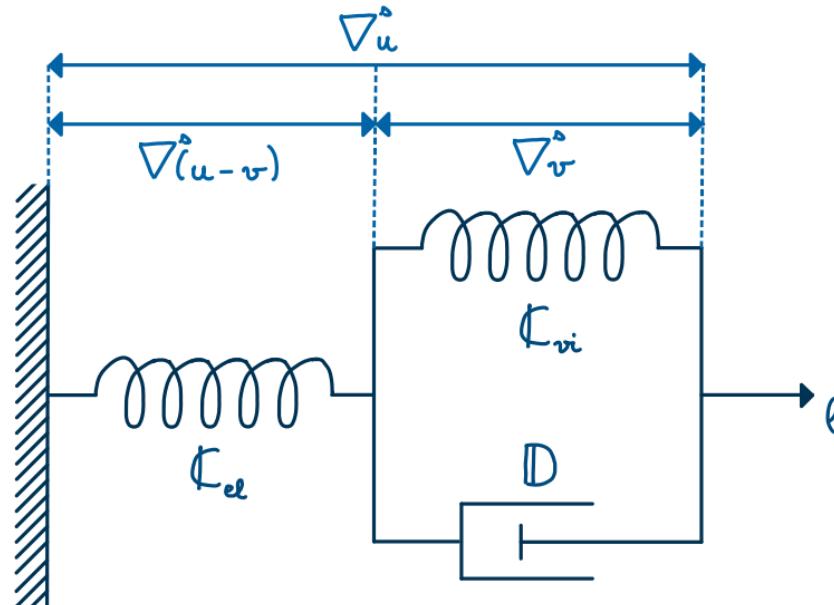
Define:

$$v := \frac{y_{vi} - id_n}{\varepsilon} \quad u := \frac{y - id_n}{\varepsilon}$$

By Taylor expansion we expect:

$$\begin{aligned} \underbrace{\frac{1}{\varepsilon^2} \int_{\Omega} W_{ei} \left(\underbrace{(I + \varepsilon \nabla u)}_{\nabla y} \left(\underbrace{(I + \varepsilon \nabla v)^{-1}}_{(\nabla y_{vi})^{-1}} \right) \right)}_{\text{rescaling}} &\longrightarrow \frac{1}{2} \int_{\Omega} C_{ei} \nabla(u-v) : \nabla(u-v) \\ \frac{1}{\varepsilon^2} \int_{\Omega} W_{vi} (I + \varepsilon \nabla v) &\longrightarrow \frac{1}{2} \int_{\Omega} C_{vi} \nabla v : \nabla v \end{aligned}$$

$$\frac{1}{\varepsilon^2} \int_{\Omega} \Psi \left(\varepsilon \nabla \dot{v} (I + \varepsilon \nabla v)^{-1} \right) \longrightarrow \frac{1}{2} \int_{\Omega} D \nabla \dot{v} : \nabla \dot{v}$$



$$\begin{cases} -\operatorname{div}(\mathbb{D}\nabla^s \ddot{v} + C_{vr}\nabla^s v) = l \\ -\operatorname{div}(C_{el}\nabla^s(u-v)) = l \end{cases}$$

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Linearization result

Theorem (Linearization) Let $(u_\varepsilon, v_\varepsilon)_\varepsilon$ be a sequence of approximable solutions. \rightarrow of the rescaled functional



Linearization result

Theorem (Linearization) Let $(u_\varepsilon, v_\varepsilon)_\varepsilon$ be a sequence of approximable solutions. Under suitable assumptions, there exist functions $(u, v): [0, T] \rightarrow H^1_0(\Omega; \mathbb{R}^d) \times H^1_{\#}(\Omega; \mathbb{R}^d)$ such that, for every $t \in [0, T]$, up to a non relabeled subsequence,

- $u_\varepsilon(t) \rightarrow u(t), v_\varepsilon(t) \rightarrow v(t) \text{ in } H^2(\Omega; \mathbb{R}^d)$
- $\nabla v_\varepsilon(t) \rightarrow \nabla v(t) \text{ in } L^2(\Omega; \mathbb{R}^{d \times d})$



Theorem (Linearization) Let $(u_\varepsilon, v_\varepsilon)_\varepsilon$ be a sequence of approximable solutions. Under suitable assumptions, there exist functions $(u, v): [0, T] \rightarrow H^1_0(\Omega; \mathbb{R}^d) \times H^1_{\#}(\Omega; \mathbb{R}^d)$ such that, for every $t \in [0, T]$, up to a non relabeled subsequence,

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$$\nabla v_\varepsilon(t) \rightarrow \nabla v(t) \text{ in } L^2(\Omega; \mathbb{R}^{d \times d})$$

- Energy inequality

$$\begin{aligned} & \int_{\Omega} \mathbb{C}_{ee} \nabla(u(t) - v(t)) : \nabla(u(t) - v(t)) + \int_{\Omega} \mathbb{C}_{vv} \nabla v(t) : \nabla v(t) - \langle l^\circ(t), u(t) \rangle + \\ & + \int_0^t \int_{\Omega} \mathbb{D} \nabla v(t) : \nabla v(t) \leq \mathcal{E}^\circ(0) - \int_0^t \langle \dot{l}^\circ(s), u(s) \rangle \end{aligned}$$



Theorem (Linearization) Let $(u_\varepsilon, v_\varepsilon)_\varepsilon$ be a sequence of approximable solutions. Under suitable assumptions, there exist functions $(u, v) : [0, T] \rightarrow H^1_B(\Omega; \mathbb{R}^d) \times H^1_{\#}(\Omega; \mathbb{R}^d)$ such that, for every $t \in [0, T]$, up to a non relabeled subsequence,

- $u_\varepsilon(t) \rightarrow u(t), v_\varepsilon(t) \rightarrow v(t)$ in $H^2(\Omega; \mathbb{R}^d)$

$$\nabla v_\varepsilon(t) \rightarrow \nabla v(t) \quad \text{in } L^2(\Omega; \mathbb{R}^{d \times d})$$

- **Energy inequality**

$$\int_{\Omega} \mathbb{C}_{ee} \nabla(u(t) - v(t)) : \nabla(u(t) - v(t)) + \int_{\Omega} \mathbb{C}_{vi} \nabla v(t) : \nabla v(t) - \langle l^\circ(t), u(t) \rangle + \int_0^t \int_{\Omega} \mathbb{D} \nabla v(t) : \nabla v(t) \leq \varepsilon^\circ(0) - \int_0^t \langle \dot{l}^\circ(\lambda), u(\lambda) \rangle$$

- **Semistability**

$$\int_{\Omega} \mathbb{C}_{ee} \nabla(u(t) - v(t)) : \nabla(u(t) - v(t)) - \langle l^\circ(t), u(t) \rangle \leq \int_{\Omega} \mathbb{C}_{ee} \nabla(\tilde{u} - v(t)) : \nabla(\tilde{u} - v(t)) - \langle l^\circ(t), \tilde{u} \rangle \quad \forall \tilde{u} \in H^1_B(\Omega; \mathbb{R}^d)$$



Theorem (Linearization) Let $(u_\varepsilon, v_\varepsilon)_\varepsilon$ be a sequence of approximable solutions. Under suitable assumptions, there exist functions $(u, v) : [0, T] \rightarrow H^2(\Omega; \mathbb{R}^d) \times H^1(\Omega; \mathbb{R}^d)$ such that, for every $t \in [0, T]$, up to a non relabeled subsequence,

- $u_\varepsilon(t) \rightarrow u(t), v_\varepsilon(t) \rightarrow v(t)$ in $H^2(\Omega; \mathbb{R}^d)$

$$\nabla v_\varepsilon(t) \rightarrow \nabla v(t) \quad \text{in } L^2(\Omega; \mathbb{R}^{d \times d})$$

- **Energy inequality**

$$\int_{\Omega} \mathcal{L}_{ee} \nabla(u(t) - v(t)) : \nabla(u(t) - v(t)) + \int_{\Omega} \mathcal{L}_{vi} \nabla v(t) : \nabla v(t) - \langle l^\circ(t), u(t) \rangle + \int_0^t \int_{\Omega} D \nabla v(t) : \nabla \dot{v}(t) \leq \varepsilon^\circ(0) - \int_0^t \langle l^\circ(\lambda), u(\lambda) \rangle$$

- **Semireversibility** $\rightarrow u(t)$ unique given $v(t)$

$$\begin{aligned} \int_{\Omega} \mathcal{L}_{ee} \nabla(u(t) - v(t)) : \nabla(u(t) - v(t)) - \langle l^\circ(t), u(t) \rangle &\leq \\ &\leq \int_{\Omega} \mathcal{L}_{ee} \nabla(\tilde{u} - v(t)) : \nabla(\tilde{u} - v(t)) - \langle l^\circ(t), \tilde{u} \rangle \quad \forall \tilde{u} \in H_B^2(\Omega; \mathbb{R}^d) \end{aligned}$$



Theorem (Linearization) Let $(u_\varepsilon, v_\varepsilon)_\varepsilon$ be a sequence of approximable solutions. Under suitable assumptions, there exist functions $(u, v) : [0, T] \rightarrow H^2(\Omega; \mathbb{R}^d) \times H^1(\Omega; \mathbb{R}^d)$ such that, for every $t \in [0, T]$, up to a non relabeled subsequence,

- $u_\varepsilon(t) \rightarrow u(t)$, $v_\varepsilon(t) \rightarrow v(t)$ in $H^2(\Omega; \mathbb{R}^d)$

$$\nabla v_\varepsilon(t) \rightarrow \nabla v(t) \quad \text{in } L^2(\Omega; \mathbb{R}^{d \times d})$$

- **Energy inequality**

$$\int_{\Omega} \mathbb{C}_{ee} \nabla(u(t) - v(t)) : \nabla(u(t) - v(t)) + \int_{\Omega} \mathbb{C}_{vi} \nabla v(t) : \nabla v(t) - \langle l^\circ(t), u(t) \rangle + \int_0^t \int_{\Omega} \mathbb{D} \nabla v(t) : \nabla \dot{v}(t) \leq \varepsilon^\circ(0) - \int_0^t \langle \dot{l}^\circ(\lambda), u(\lambda) \rangle$$

- **Semireversibility** $\rightarrow u(t)$ unique given $v(t)$ \rightarrow uniqueness of v ?

$$\begin{aligned} \int_{\Omega} \mathbb{C}_{ee} \nabla(u(t) - v(t)) : \nabla(u(t) - v(t)) - \langle l^\circ(t), u(t) \rangle &\leq \\ &\leq \int_{\Omega} \mathbb{C}_{ee} \nabla(\tilde{u} - v(t)) : \nabla(\tilde{u} - v(t)) - \langle l^\circ(t), \tilde{u} \rangle \quad \forall \tilde{u} \in H_B^2(\Omega; \mathbb{R}^d) \end{aligned}$$

Thank you for your attention!
