

Affine holonomies and parabolic geometries

Andreas Čap

University of Vienna
Faculty of Mathematics

Srni, January 2009

- The classification of affine holonomies is one of the cornerstones of differential geometry.

- The classification of affine holonomies is one of the cornerstones of differential geometry.
- While some general patterns in the lists of possible affine holonomies were noticed for a long time, the existence part was proved case by case over a long period.

- The classification of affine holonomies is one of the cornerstones of differential geometry.
- While some general patterns in the lists of possible affine holonomies were noticed for a long time, the existence part was proved case by case over a long period.
- More recently, it was noticed that almost all the possible non-Riemannian affine holonomies can be produced by two constructions starting from the canonical parabolic geometries on generalized flag manifolds.

- The classification of affine holonomies is one of the cornerstones of differential geometry.
- While some general patterns in the lists of possible affine holonomies were noticed for a long time, the existence part was proved case by case over a long period.
- More recently, it was noticed that almost all the possible non-Riemannian affine holonomies can be produced by two constructions starting from the canonical parabolic geometries on generalized flag manifolds.
- Based on work of M. Cahen and L. Schwachhöfer (arXiv:math/0402221), and myself (arXiv:0804.1838, PAMS **137** (2009), 1073-1080).

Contents

- 1 Background on affine holonomy
- 2 Holonomies related to $|1|$ -gradings
- 3 Holonomies related to contact gradings

Structure

- 1 Background on affine holonomy
- 2 Holonomies related to $|1|$ -gradings
- 3 Holonomies related to contact gradings

Definition of Holonomy

Let M be a smooth manifold of dimension n and let ∇ be a linear connection on the tangent bundle TM . For a point $x \in M$, the *holonomy of ∇ at x* is the closed subgroup of $GL(T_x M)$ generated by parallel transports with respect to ∇ along piecewise smooth closed loops based at x .

Definition of Holonomy

Let M be a smooth manifold of dimension n and let ∇ be a linear connection on the tangent bundle TM . For a point $x \in M$, the *holonomy of ∇ at x* is the closed subgroup of $GL(T_x M)$ generated by parallel transports with respect to ∇ along piecewise smooth closed loops based at x .

Identifying $GL(T_x M)$ with $GL(n, \mathbb{R})$, the subgroups obtained from different points in M are all conjugate. Thus one may view the holonomy group $\text{Hol}(\nabla)$ of ∇ as a subgroup of $GL(n, \mathbb{R})$ defined up to conjugation, or equivalently as a Lie group endowed with a representation on \mathbb{R}^n defined up to isomorphism.

In many cases it is desirable to eliminate the influence of the fundamental group of M . To do this, one passes to the *restricted holonomy group* $\text{Hol}_0(\nabla)$ is the group obtained from parallel transports along null-homotopic loops. It is the connected component of the identity of $\text{Hol}(\nabla)$.

In many cases it is desirable to eliminate the influence of the fundamental group of M . To do this, one passes to the *restricted holonomy group* $\text{Hol}_0(\nabla)$ is the group obtained from parallel transports along null-homotopic loops. It is the connected component of the identity of $\text{Hol}(\nabla)$.

The Lie algebra $\mathfrak{hol}(\nabla)$ of the holonomy group is called the *holonomy Lie algebra* of ∇ . It is best viewed as an abstract Lie algebra endowed with a representation on \mathbb{R}^n (up to isomorphism).

In many cases it is desirable to eliminate the influence of the fundamental group of M . To do this, one passes to the *restricted holonomy group* $\text{Hol}_0(\nabla)$ is the group obtained from parallel transports along null-homotopic loops. It is the connected component of the identity of $\text{Hol}(\nabla)$.

The Lie algebra $\mathfrak{hol}(\nabla)$ of the holonomy group is called the *holonomy Lie algebra* of ∇ . It is best viewed as an abstract Lie algebra endowed with a representation on \mathbb{R}^n (up to isomorphism).

By the Ambrose–Singer theorem, the holonomy Lie algebra at x is generated by parallelly transporting the values of the curvature and its iterated covariant derivatives at arbitrary points of M to x .

Geometric meaning of the holonomy group

- Parallel sections for ∇ are in bijective correspondence with elements in \mathbb{R}^n which are invariant under $\text{Hol}(\nabla)$.

Geometric meaning of the holonomy group

- Parallel sections for ∇ are in bijective correspondence with elements in \mathbb{R}^n which are invariant under $\text{Hol}(\nabla)$.
- This extends to tensor bundles. For example, there exists a Riemannian metric which is compatible with ∇ if and only if $\text{Hol}(\nabla)$ is (conjugate to) a subgroup of $O(n)$.

Geometric meaning of the holonomy group

- Parallel sections for ∇ are in bijective correspondence with elements in \mathbb{R}^n which are invariant under $\text{Hol}(\nabla)$.
- This extends to tensor bundles. For example, there exists a Riemannian metric which is compatible with ∇ if and only if $\text{Hol}(\nabla)$ is (conjugate to) a subgroup of $O(n)$.
- In this sense $\text{Hol}(\nabla)$ can be thought of as the smallest structure group of a geometric structure compatible with ∇ .

Geometric meaning of the holonomy group

- Parallel sections for ∇ are in bijective correspondence with elements in \mathbb{R}^n which are invariant under $\text{Hol}(\nabla)$.
- This extends to tensor bundles. For example, there exists a Riemannian metric which is compatible with ∇ if and only if $\text{Hol}(\nabla)$ is (conjugate to) a subgroup of $O(n)$.
- In this sense $\text{Hol}(\nabla)$ can be thought of as the smallest structure group of a geometric structure compatible with ∇ .
- The various compatible geometric structures can be used to define subclasses of holonomy groups, e.g. (pseudo-)Riemannian and symplectic holonomies (compatible with a symplectic form).

The holonomy problem

Classify the possible holonomy groups (or Lie algebras) of affine connections assuming that

The holonomy problem

Classify the possible holonomy groups (or Lie algebras) of affine connections assuming that

- 1 ∇ is torsion free

The holonomy problem

Classify the possible holonomy groups (or Lie algebras) of affine connections assuming that

- 1 ∇ is torsion free
- 2 ∇ is not locally symmetric (i.e. the curvature R of ∇ is not parallel).

The holonomy problem

Classify the possible holonomy groups (or Lie algebras) of affine connections assuming that

- 1 ∇ is torsion free
- 2 ∇ is not locally symmetric (i.e. the curvature R of ∇ is not parallel).
- 3 The representation of $\text{Hol}(\nabla)$ on \mathbb{R}^n is irreducible.

The holonomy problem

Classify the possible holonomy groups (or Lie algebras) of affine connections assuming that

- 1 ∇ is torsion free
- 2 ∇ is not locally symmetric (i.e. the curvature R of ∇ is not parallel).
- 3 The representation of $\text{Hol}(\nabla)$ on \mathbb{R}^n is irreducible.

Without the first condition, the problem becomes meaningless and the second is rather harmless. Irreducibility is not a real restriction for Riemannian holonomies by the de-Rham theorem, but in general it is a purely technical assumption.

Berger's lists

In fundamental work on the holonomy problem, M. Berger compiled two lists of possible holonomy Lie algebras. He claimed that one contained all possible Riemannian holonomy groups, while the other should contain all non-Riemannian holonomy groups up to finitely many exceptions.

Berger's lists

In fundamental work on the holonomy problem, M. Berger compiled two lists of possible holonomy Lie algebras. He claimed that one contained all possible Riemannian holonomy groups, while the other should contain all non-Riemannian holonomy groups up to finitely many exceptions.

Over many years many people, in particular R. Bryant, corrected an extend Berger's second list, adding (infinitely many) so-called exotic holonomies. Proving existence of holonomy groups in many cases needed lots of effort and case-by-case considerations. The problem was finally solved by S. Merkulov and L. Schwachhöfer in 2001. Similarities of the final list with other classification results were noted, but not used systematically.

Structure

- 1 Background on affine holonomy
- 2 Holonomies related to $|1|$ -gradings
- 3 Holonomies related to contact gradings

Let \mathfrak{g} be a simple Lie algebra endowed with a grading of the form $\mathfrak{g} = \mathfrak{g}_{-1} \oplus \mathfrak{g}_0 \oplus \mathfrak{g}_1$. Such gradings are well understood since their classification is equivalent to the classification of Hermitian symmetric spaces. Then

Let \mathfrak{g} be a simple Lie algebra endowed with a grading of the form $\mathfrak{g} = \mathfrak{g}_{-1} \oplus \mathfrak{g}_0 \oplus \mathfrak{g}_1$. Such gradings are well understood since their classification is equivalent to the classification of Hermitian symmetric spaces. Then

- \mathfrak{g}_0 is reductive with 1-dimensional center

Let \mathfrak{g} be a simple Lie algebra endowed with a grading of the form $\mathfrak{g} = \mathfrak{g}_{-1} \oplus \mathfrak{g}_0 \oplus \mathfrak{g}_1$. Such gradings are well understood since their classification is equivalent to the classification of Hermitian symmetric spaces. Then

- \mathfrak{g}_0 is reductive with 1-dimensional center
- The adjoint action restricts to an irreducible representation of \mathfrak{g}_0 on the vector space \mathfrak{g}_{-1} .

Let \mathfrak{g} be a simple Lie algebra endowed with a grading of the form $\mathfrak{g} = \mathfrak{g}_{-1} \oplus \mathfrak{g}_0 \oplus \mathfrak{g}_1$. Such gradings are well understood since their classification is equivalent to the classification of Hermitian symmetric spaces. Then

- \mathfrak{g}_0 is reductive with 1-dimensional center
- The adjoint action restricts to an irreducible representation of \mathfrak{g}_0 on the vector space \mathfrak{g}_{-1} .
- Both this representations and its restriction to the semisimple part of \mathfrak{g}_0 are possible holonomy Lie algebras

Let \mathfrak{g} be a simple Lie algebra endowed with a grading of the form $\mathfrak{g} = \mathfrak{g}_{-1} \oplus \mathfrak{g}_0 \oplus \mathfrak{g}_1$. Such gradings are well understood since their classification is equivalent to the classification of Hermitian symmetric spaces. Then

- \mathfrak{g}_0 is reductive with 1-dimensional center
- The adjoint action restricts to an irreducible representation of \mathfrak{g}_0 on the vector space \mathfrak{g}_{-1} .
- Both this representations and its restriction to the semisimple part of \mathfrak{g}_0 are possible holonomy Lie algebras
- This exhaust all entries except $\mathfrak{sp}(2n)$ on Berger's original second list, as well as some exotic holonomies.

Let G be the simply connected Lie group with Lie algebra \mathfrak{g} . Then there are natural subgroups $G_0 \subset P \subset G$ corresponding to the Lie subalgebras \mathfrak{g}_0 , and $\mathfrak{p} = \mathfrak{g}_0 \oplus \mathfrak{g}_1$, respectively. Moreover, there is an Abelian normal vector subgroup $P_+ \subset P$ such that $P = G_0 \times P_+$. The quotient $M := G/P$ is a compact Hermitian symmetric space, and $E := G/P_+ \rightarrow M$ is a first order structure with structure group G_0 , with TM and T^*M corresponding to the representations \mathfrak{g}_{-1} and \mathfrak{g}_1 of G_0 .

Let G be the simply connected Lie group with Lie algebra \mathfrak{g} . Then there are natural subgroups $G_0 \subset P \subset G$ corresponding to the Lie subalgebras \mathfrak{g}_0 , and $\mathfrak{p} = \mathfrak{g}_0 \oplus \mathfrak{g}_1$, respectively. Moreover, there is an Abelian normal vector subgroup $P_+ \subset P$ such that $P = G_0 \times P_+$. The quotient $M := G/P$ is a compact Hermitian symmetric space, and $E := G/P_+ \rightarrow M$ is a first order structure with structure group G_0 , with TM and T^*M corresponding to the representations \mathfrak{g}_{-1} and \mathfrak{g}_1 of G_0 .

The theory of Weyl structures for parabolic geometries leads to the class of *Weyl connections* on the principal bundle E . Moreover, there always is the subclass of *exact Weyl connections* which come from a further reductions with structure group the semisimple part of G_0 .

The Weyl connections are exactly the torsion free connections on E . A crucial part of the theory is that they form an affine spaces modelled on $\Omega^1(M)$, while exact Weyl connections are affine over exact one-forms.

The Weyl connections are exactly the torsion free connections on E . A crucial part of the theory is that they form an affine spaces modelled on $\Omega^1(M)$, while exact Weyl connections are affine over exact one-forms.

On the homogeneous model, all Weyl connections have vanishing Weyl curvature, so the curvature is concentrated in the Rho-tensor. There are explicit formulae for the change of Weyl connections and their Rho-tensors with respect to this affine structure in terms of the Lie algebra structure of \mathfrak{g} :

The Weyl connections are exactly the torsion free connections on E . A crucial part of the theory is that they form an affine space modelled on $\Omega^1(M)$, while exact Weyl connections are affine over exact one-forms.

On the homogeneous model, all Weyl connections have vanishing Weyl curvature, so the curvature is concentrated in the Rho-tensor. There are explicit formulae for the change of Weyl connections and their Rho-tensors with respect to this affine structure in terms of the Lie algebra structure of \mathfrak{g} :

$$\begin{aligned}\hat{\nabla}_\xi \eta &= \nabla_\xi \eta - \{ \{ \Upsilon, \xi \}, \eta \} \\ \hat{P}(\xi) &= P(\xi) + \nabla_\xi \Upsilon + \frac{1}{2} \{ \Upsilon, \{ \Upsilon, \xi \} \}\end{aligned}$$

First one constructs an exact Weyl connection ∇ on M , such that locally around $o = eP \in M$, the Rho tensor vanishes identically. Choosing a change $\Upsilon \in \Omega^1(M)$ with vanishing k -jet in o , we conclude that the curvature \hat{R} of has vanishing $(k - 1)$ -jet in o and that

$$\hat{\nabla}^k \hat{R}(o) = (\text{id} \otimes \partial)(\nabla^{k+1} \Upsilon(o)),$$

where ∂ is the Lie algebra differential, which describes the contribution of the Rho-tensor to the curvature.

First one constructs an exact Weyl connection ∇ on M , such that locally around $o = eP \in M$, the Rho tensor vanishes identically. Choosing a change $\Upsilon \in \Omega^1(M)$ with vanishing k -jet in o , we conclude that the curvature \hat{R} of has vanishing $(k - 1)$ -jet in o and that

$$\hat{\nabla}^k \hat{R}(o) = (\text{id} \otimes \partial)(\nabla^{k+1} \Upsilon(o)),$$

where ∂ is the Lie algebra differential, which describes the contribution of the Rho-tensor to the curvature.

Now $\nabla^{k+1} \Upsilon(o)$ can be prescribed arbitrarily, and with a bit of Lie theory one shows that for $k = 5$, one can find a one form (respectively an exact one-form) Υ such that that the values of $\hat{\nabla}^k \hat{R}(o)$ exhaust all of \mathfrak{g}_0 (respectively its semisimple part).

Main result for $|1|$ -gradings

Since the values of the covariant derivatives of the curvature are well known to lie in the holonomy Lie algebra, we conclude:

Theorem

For any $|1|$ -graded Lie algebra \mathfrak{g} , the Lie algebra \mathfrak{g}_0 and its semisimple part both are realized as the holonomy Lie algebra of non-locally symmetric affine connections on the compact Hermitian symmetric space G/P .

Structure

- 1 Background on affine holonomy
- 2 Holonomies related to $|1|$ -gradings
- 3 Holonomies related to contact gradings

Contact gradings

A contact grading of a simple Lie algebra \mathfrak{g} is a grading of the form $\mathfrak{g} = \mathfrak{g}_{-2} \oplus \mathfrak{g}_{-1} \oplus \mathfrak{g}_0 \oplus \mathfrak{g}_1 \oplus \mathfrak{g}_2$ such that \mathfrak{g}_{-2} has dimension one and the Lie bracket $\mathfrak{g}_{-1} \times \mathfrak{g}_{-1} \rightarrow \mathfrak{g}_{-2}$ is non-degenerate.

Contact gradings

A contact grading of a simple Lie algebra \mathfrak{g} is a grading of the form $\mathfrak{g} = \mathfrak{g}_{-2} \oplus \mathfrak{g}_{-1} \oplus \mathfrak{g}_0 \oplus \mathfrak{g}_1 \oplus \mathfrak{g}_2$ such that \mathfrak{g}_{-2} has dimension one and the Lie bracket $\mathfrak{g}_{-1} \times \mathfrak{g}_{-1} \rightarrow \mathfrak{g}_{-2}$ is non-degenerate.

- If \mathfrak{g} admits a contact grading, then this grading is unique up to isomorphism.

Contact gradings

A contact grading of a simple Lie algebra \mathfrak{g} is a grading of the form $\mathfrak{g} = \mathfrak{g}_{-2} \oplus \mathfrak{g}_{-1} \oplus \mathfrak{g}_0 \oplus \mathfrak{g}_1 \oplus \mathfrak{g}_2$ such that \mathfrak{g}_{-2} has dimension one and the Lie bracket $\mathfrak{g}_{-1} \times \mathfrak{g}_{-1} \rightarrow \mathfrak{g}_{-2}$ is non-degenerate.

- If \mathfrak{g} admits a contact grading, then this grading is unique up to isomorphism.
- Any complex simple Lie algebra \mathfrak{g} admits a contact grading.

Contact gradings

A contact grading of a simple Lie algebra \mathfrak{g} is a grading of the form $\mathfrak{g} = \mathfrak{g}_{-2} \oplus \mathfrak{g}_{-1} \oplus \mathfrak{g}_0 \oplus \mathfrak{g}_1 \oplus \mathfrak{g}_2$ such that \mathfrak{g}_{-2} has dimension one and the Lie bracket $\mathfrak{g}_{-1} \times \mathfrak{g}_{-1} \rightarrow \mathfrak{g}_{-2}$ is non-degenerate.

- If \mathfrak{g} admits a contact grading, then this grading is unique up to isomorphism.
- Any complex simple Lie algebra \mathfrak{g} admits a contact grading.
- A real simple Lie algebra \mathfrak{g} admits a contact grading if and only if \mathfrak{g} contains a highest root space.

Contact gradings

A contact grading of a simple Lie algebra \mathfrak{g} is a grading of the form $\mathfrak{g} = \mathfrak{g}_{-2} \oplus \mathfrak{g}_{-1} \oplus \mathfrak{g}_0 \oplus \mathfrak{g}_1 \oplus \mathfrak{g}_2$ such that \mathfrak{g}_{-2} has dimension one and the Lie bracket $\mathfrak{g}_{-1} \times \mathfrak{g}_{-1} \rightarrow \mathfrak{g}_{-2}$ is non-degenerate.

- If \mathfrak{g} admits a contact grading, then this grading is unique up to isomorphism.
- Any complex simple Lie algebra \mathfrak{g} admits a contact grading.
- A real simple Lie algebra \mathfrak{g} admits a contact grading if and only if \mathfrak{g} contains a highest root space.
- The list of all contact gradings is also well known from its relation to the classification of quaternionic symmetric spaces.

Fix a contact grading $\mathfrak{g} = \mathfrak{g}_{-2} \oplus \mathfrak{g}_{-1} \oplus \mathfrak{g}_0 \oplus \mathfrak{g}_1 \oplus \mathfrak{g}_2$. Then

Fix a contact grading $\mathfrak{g} = \mathfrak{g}_{-2} \oplus \mathfrak{g}_{-1} \oplus \mathfrak{g}_0 \oplus \mathfrak{g}_1 \oplus \mathfrak{g}_2$. Then

- $[\mathfrak{g}_{-2}, \mathfrak{g}_2] \subset \mathfrak{g}_0$ is the line spanned by the grading element E and $\mathfrak{g}_{-2} \oplus \mathbb{R} \cdot E \oplus \mathfrak{g}_2 \cong \mathfrak{sl}(2, \mathbb{R})$.

Fix a contact grading $\mathfrak{g} = \mathfrak{g}_{-2} \oplus \mathfrak{g}_{-1} \oplus \mathfrak{g}_0 \oplus \mathfrak{g}_1 \oplus \mathfrak{g}_2$. Then

- $[\mathfrak{g}_{-2}, \mathfrak{g}_2] \subset \mathfrak{g}_0$ is the line spanned by the grading element E and $\mathfrak{g}_{-2} \oplus \mathbb{R} \cdot E \oplus \mathfrak{g}_2 \cong \mathfrak{sl}(2, \mathbb{R})$.
- The orthocomplement of E in \mathfrak{g}_0 is a subalgebra \mathfrak{h} which is either semisimple or reductive with one-dimensional center.

Fix a contact grading $\mathfrak{g} = \mathfrak{g}_{-2} \oplus \mathfrak{g}_{-1} \oplus \mathfrak{g}_0 \oplus \mathfrak{g}_1 \oplus \mathfrak{g}_2$. Then

- $[\mathfrak{g}_{-2}, \mathfrak{g}_2] \subset \mathfrak{g}_0$ is the line spanned by the grading element E and $\mathfrak{g}_{-2} \oplus \mathbb{R} \cdot E \oplus \mathfrak{g}_2 \cong \mathfrak{sl}(2, \mathbb{R})$.
- The orthocomplement of E in \mathfrak{g}_0 is a subalgebra \mathfrak{h} which is either semisimple or reductive with one-dimensional center.
- As a module over $\mathfrak{sl}(2, \mathbb{R}) \oplus \mathfrak{h}$, the subspace $\mathfrak{g}_{-1} \oplus \mathfrak{g}_1$ decomposes as $\mathbb{R}^2 \otimes V$ and V carries a natural, \mathfrak{h} -invariant symplectic form.

Fix a contact grading $\mathfrak{g} = \mathfrak{g}_{-2} \oplus \mathfrak{g}_{-1} \oplus \mathfrak{g}_0 \oplus \mathfrak{g}_1 \oplus \mathfrak{g}_2$. Then

- $[\mathfrak{g}_{-2}, \mathfrak{g}_2] \subset \mathfrak{g}_0$ is the line spanned by the grading element E and $\mathfrak{g}_{-2} \oplus \mathbb{R} \cdot E \oplus \mathfrak{g}_2 \cong \mathfrak{sl}(2, \mathbb{R})$.
- The orthocomplement of E in \mathfrak{g}_0 is a subalgebra \mathfrak{h} which is either semisimple or reductive with one-dimensional center.
- As a module over $\mathfrak{sl}(2, \mathbb{R}) \oplus \mathfrak{h}$, the subspace $\mathfrak{g}_{-1} \oplus \mathfrak{g}_1$ decomposes as $\mathbb{R}^2 \otimes V$ and V carries a natural, \mathfrak{h} -invariant symplectic form.
- If \mathfrak{g} is not of type A_n or C_n , then the representation of \mathfrak{h} on V is a possible (symplectic) holonomy Lie algebra. None of these were on Berger's original list.

Fix a contact grading $\mathfrak{g} = \mathfrak{g}_{-2} \oplus \mathfrak{g}_{-1} \oplus \mathfrak{g}_0 \oplus \mathfrak{g}_1 \oplus \mathfrak{g}_2$. Then

- $[\mathfrak{g}_{-2}, \mathfrak{g}_2] \subset \mathfrak{g}_0$ is the line spanned by the grading element E and $\mathfrak{g}_{-2} \oplus \mathbb{R} \cdot E \oplus \mathfrak{g}_2 \cong \mathfrak{sl}(2, \mathbb{R})$.
- The orthocomplement of E in \mathfrak{g}_0 is a subalgebra \mathfrak{h} which is either semisimple or reductive with one-dimensional center.
- As a module over $\mathfrak{sl}(2, \mathbb{R}) \oplus \mathfrak{h}$, the subspace $\mathfrak{g}_{-1} \oplus \mathfrak{g}_1$ decomposes as $\mathbb{R}^2 \otimes V$ and V carries a natural, \mathfrak{h} -invariant symplectic form.
- If \mathfrak{g} is not of type A_n or C_n , then the representation of \mathfrak{h} on V is a possible (symplectic) holonomy Lie algebra. None of these were on Berger's original list.

The algebras $\mathfrak{h} \subset \mathfrak{sp}(V)$ obtained in this way are called *special symplectic* subalgebras.

special symplectic connections

Using the structure theory of simple Lie algebras, one can show directly that the Ricci-type contraction induces a surjection from the module $K(\mathfrak{h})$ of formal curvatures onto \mathfrak{h} . This leads to a subspace $\mathcal{R}(\mathfrak{h}) \subset K(\mathfrak{h})$ which is isomorphic to \mathfrak{h} and complementary to Ricci flat formal curvatures.

special symplectic connections

Using the structure theory of simple Lie algebras, one can show directly that the Ricci-type contraction induces a surjection from the module $K(\mathfrak{h})$ of formal curvatures onto \mathfrak{h} . This leads to a subspace $\mathcal{R}(\mathfrak{h}) \subset K(\mathfrak{h})$ which is isomorphic to \mathfrak{h} and complementary to Ricci flat formal curvatures.

Definition (Cahen–Schwachhöfer)

Let (M, ω) be a symplectic manifold. A *special symplectic connection* on M is a torsion free symplectic connection ∇ on TM whose curvature in each point is contained in $\mathcal{R}(\mathfrak{h})$ for some special symplectic subalgebra \mathfrak{h} .

special symplectic connections

Using the structure theory of simple Lie algebras, one can show directly that the Ricci-type contraction induces a surjection from the module $K(\mathfrak{h})$ of formal curvatures onto \mathfrak{h} . This leads to a subspace $\mathcal{R}(\mathfrak{h}) \subset K(\mathfrak{h})$ which is isomorphic to \mathfrak{h} and complementary to Ricci flat formal curvatures.

Definition (Cahen–Schwachhöfer)

Let (M, ω) be a symplectic manifold. A *special symplectic connection* on M is a torsion free symplectic connection ∇ on TM whose curvature in each point is contained in $\mathcal{R}(\mathfrak{h})$ for some special symplectic subalgebra \mathfrak{h} .

Using the classification results, this definition can be turned into something much more concrete:

Special symplectic connections are exactly the following:

Special symplectic connections are exactly the following:

- The Levi–Civita connections of Bochner–Kähler metrics and Bocher–bi–Lagranean metrics (A_n -type).

Special symplectic connections are exactly the following:

- The Levi–Civita connections of Bochner–Kähler metrics and Bocher–bi–Lagrangian metrics (A_n -type).
- Symplectic connections of Ricci type (C_n -type).

Special symplectic connections are exactly the following:

- The Levi–Civita connections of Bochner–Kähler metrics and Bocher–bi–Lagrangian metrics (A_n -type).
- Symplectic connections of Ricci type (C_n -type).
- Connections with special symplectic holonomy (all other types).

Special symplectic connections are exactly the following:

- The Levi–Civita connections of Bochner–Kähler metrics and Bocher–bi–Lagrangian metrics (A_n -type).
- Symplectic connections of Ricci type (C_n -type).
- Connections with special symplectic holonomy (all other types).

Let G be a connected Lie group with Lie algebra \mathfrak{g} and $P \subset G$ a parabolic subgroup corresponding to $\mathfrak{g}_0 \oplus \mathfrak{g}_1 \oplus \mathfrak{g}_2$. Then G/P carries a natural geometric structure, which includes a contact subbundle $H \subset T(G/P)$ coming from \mathfrak{g}_{-1} . For this parabolic geometry, there also is the notion of Weyl structures and Weyl connections. The construction of Cahen–Schwachhöfer uses this setting (but not the language of Weyl structures).

For any $A \in \mathfrak{g}$, the right invariant vector field R_A generates a one-parameter group of automorphisms of the parabolic geometry on G/P . We assume that in some point, the image of R_A in $\mathfrak{X}(G/P)$ is transverse to the contact subbundle. This is satisfied for generic elements A , and then it holds on an open subset $U \subset G/P$. On U we obtain from A

For any $A \in \mathfrak{g}$, the right invariant vector field R_A generates a one-parameter group of automorphisms of the parabolic geometry on G/P . We assume that in some point, the image of R_A in $\mathfrak{X}(G/P)$ is transverse to the contact subbundle. This is satisfied for generic elements A , and then it holds on an open subset $U \subset G/P$. On U we obtain from A

- A non-vanishing vector field ξ_A , which is transverse to the contact subbundle.

For any $A \in \mathfrak{g}$, the right invariant vector field R_A generates a one-parameter group of automorphisms of the parabolic geometry on G/P . We assume that in some point, the image of R_A in $\mathfrak{X}(G/P)$ is transverse to the contact subbundle. This is satisfied for generic elements A , and then it holds on an open subset $U \subset G/P$. On U we obtain from A

- A non-vanishing vector field ξ_A , which is transverse to the contact subbundle.
- An induced contact form, which determines an exact Weyl structure.

For any $A \in \mathfrak{g}$, the right invariant vector field R_A generates a one-parameter group of automorphisms of the parabolic geometry on G/P . We assume that in some point, the image of R_A in $\mathfrak{X}(G/P)$ is transverse to the contact subbundle. This is satisfied for generic elements A , and then it holds on an open subset $U \subset G/P$. On U we obtain from A

- A non-vanishing vector field ξ_A , which is transverse to the contact subbundle.
- An induced contact form, which determines an exact Weyl structure.

The flow lines of ξ_A foliate U and for any open subset $V \subset U$ for which the space of leaves is a smooth manifold, Cahen–Schwachhöfer prove:

Theorem (Cahen–Schwachhöfer)

- The contact structure on U descends to a symplectic structure on V .

Theorem (Cahen–Schwachhöfer)

- The contact structure on U descends to a symplectic structure on V .
- The Weyl connection induced by the contact form associated to ξ_A descends a special symplectic connection on V .

Theorem (Cahen–Schwachhöfer)

- The contact structure on U descends to a symplectic structure on V .
- The Weyl connection induced by the contact form associated to ξ_A descends a special symplectic connection on V .

The results of Cahen–Schwachhöfer actually go much further. They prove that up to local isomorphism any special symplectic connection is obtained in this way. This implies that special symplectic connections are automatically real analytic, and it leads to a description of the moduli space of all such connections, as well as a complete classification of homogeneous examples on simply connected manifolds.