

Introduction and motivation

Given a problem of interest, let \mathcal{M} be the solution manifold. Assumption of the reduced basis method: \mathcal{M} can be well approximated by a sequence of finite dimensional spaces, meaning the Kolmogorov n -width D_n of \mathcal{M} decays fast as a function of n . For convection dominated problems D_n can decay quite slowly, and this translates in a poor efficiency of the reduced basis method. Here we show how we have tried to overcome this situation, explaining the idea presented in [3], whose main feature is the presence of a preprocessing step, which is carried out right after the offline step.

FSI problem

Problem: simulate the displacement in the time interval $[0, T]$ of a thin structure Σ_t at the top of a 2D rectangle filled with a fluid Ω_t^f . We adopt an Arbitrary Lagrangian Eulerian (**ALE**) formulation.

$$\begin{cases} J\rho_f(\partial_t \mathbf{u}_f + F^{-1}(\mathbf{u}_f - \partial_t d_f \mathbf{e}_y) \cdot \nabla) \mathbf{u}_f - \operatorname{div}(J\sigma^f F^{-T}) = \mathbf{b}_f & \text{in } \Omega^f \times [0, T], \\ \operatorname{div}(JF^{-1} \mathbf{u}_f) = 0 & \text{in } \Omega^f \times [0, T], \\ \rho_s h_s \partial_{tt} d_s - c_0 \partial_{xx} d_s + c_1 d_s = -\sigma^f \mathbf{n} \cdot \mathbf{n} & \text{in } \Sigma, \end{cases} \quad \begin{cases} d_f = d_s & \text{in } \Sigma_t, & \text{continuity of the displacement} \\ \mathbf{u}_f = \partial_t d_s \mathbf{e}_y & \text{in } \Sigma_t, & \text{continuity of the velocity.} \end{cases}$$

To impose the continuity conditions we use two Lagrange multipliers λ_u and λ_d .

Transport phenomenon



Figure: snapshots for p_f at different timesteps. Let γ_n be the abscissa of the peak of the pressure wave at timestep t_n : γ_n changes in time, since the peak of the wave travels along the domain. We have a transport phenomenon.

Kolmogorov n -width

Kolmogorov n -width (of \mathcal{M}_{p_f})

$$D_n(\mathcal{M}_{p_f}, \|\cdot\|) = \inf_{E_n} \sup_{p \in \mathcal{M}_{p_f}} \inf_{q \in E_n} \|p - q\|_X.$$

E_n is any linear subspace of dimension n embedded in X .

Link between D_n and POD

$$\int_0^T \|p_f(\cdot; t) - \Pi_{POD} p_f(\cdot; t)\|_X dt = \sum_{i > N_{POD}} \lambda_i,$$

Preprocessing step (for \mathcal{M}_{p_f}) [3]

Family of **smooth** and **invertible** mappings $\mathcal{F} = \{F : \Omega^f \rightarrow \Omega^f\}$ s.t. $\forall t \in [0; T], \exists F_t \in \mathcal{F}$ s. t.

$$\mathcal{M}_{p_f, \mathcal{F}} = \{p_f(F_t^{-1}(\cdot), t); t \in [0; T]\}$$

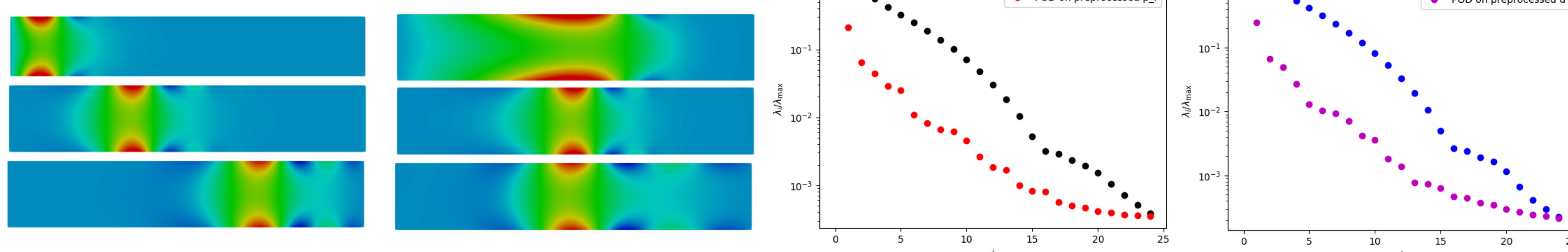
has a smaller Kolmogorov n -width.

After preprocessing: $\{\Phi_k^{p_f}\}_{k=1}^N$ s. t. $\operatorname{span}\{\Phi_k^{p_f}\}_k$ approaches to a given

accuracy $\mathcal{M}_{p_f, \mathcal{F}}$, N small. At each time step, look for coordinates $\{\alpha_k^{n+1}\}$ and a suitable map $F_{n+1} \in \mathcal{F}$ such that $p_f(\cdot, t^{n+1})$ is well approximated by:

$$p_N^{n+1} = \sum_{k=1}^N \alpha_k^{n+1} \Phi_k^{p_f} \circ F_{n+1}.$$

Results



Left column: p_f before and after the preprocessing.

The peaks of the waves are all aligned at the same point.

Right column: POD on \mathcal{M}_{p_f} , \mathcal{M}_d and on $\mathcal{M}_{p_f, \mathcal{F}}$ and $\mathcal{M}_{d, \mathcal{F}}$.

After the preprocessing, we reach a magnitude of 10^{-3} with less than 15 modes.

References

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- [4] Ballarin F., Maday Y., Nonino M., Rozza G., article in preparation.

Acknowledgements

We acknowledge the support by European Union Funding for Research and Innovation – Horizon 2020 Program – in the framework of European Research Council Executive Agency: Consolidator Grant H2020 ERC CoG 2015 AROMA-CFD project 681447 “Advanced Reduced Order Methods with Applications in Computational Fluid Dynamics”.