## Non-commutative differential equations.

Localization, independence and unicity.

# V.C. Bùi, Matthieu Deneufchâtel,G.H.E. Duchamp, Nihar Gargava, Hoang Ngoc Minh, Q.H. Ngô. Collaboration at various stages of the work and in the framework of the Project <br> Evolution Equations in Combinatorics and Physics : <br> N. Behr, K. A. Penson, C. Tollu. 

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## Foreword: Goal of this talk

In this talk, I will show tools and sketch proofs about Noncommutative Differential (Evolution) Equations.
The main item of data (not to say the only one) is that of Noncommutative Formal Power Series with variable coefficients which allows to explore in a compact and effective (in the sense of computability, hence needing fraction fields or a localization process) way the Magnus group of proper exponentials and the Hausdorff group of Lie exponentials (i.e. group-like series for the dual of the shuffle product).

Parts of this work are connected with Dyson series and take place within the project: Evolution Equations in Combinatorics and Physics. Today we will focus on mathematical motivations and properties (namely localization).

This talk also prepares data structures used in the next talk.

## Review of the facts

- $\zeta(s)=\sum_{n \geq 1} \frac{1}{n^{s}}$
- when one multiplies two of these, one gets

$$
\zeta\left(s_{1}\right) \zeta\left(s_{2}\right)=\sum_{n_{1}, n_{2} \geq 1} \frac{1}{n_{1}^{s_{1}} n_{2}^{s_{2}}}=\zeta\left(s_{1}, s_{2}\right)+\zeta\left(s_{1}+s_{2}\right)+\zeta\left(s_{2}, s_{1}\right)
$$

- leading to the following definition of MultiZeta Values (MZV)

$$
\begin{equation*}
\zeta\left(s_{1}, \ldots, s_{k}\right):=\sum_{n_{1}>\ldots>n_{k} \geq 1} \frac{1}{n_{1}^{s_{1}} \ldots n_{k}^{s_{k}}} \quad ; \quad s_{1}>1 \tag{1}
\end{equation*}
$$

- On the other hand, one has the classical polylogarithms defined, for $k \geq 1,|z|<1$, by

$$
L i_{k}(z):=\sum_{n \geq 1} \frac{z^{n}}{n^{k}}
$$

## Overview of the facts/2

- The analogue of the classical polylogarithms for MZV reads

$$
L i_{y_{s_{1}} \ldots y_{s_{k}}}(z):=\sum_{n_{1}>\ldots>n_{k} \geq 1} \frac{z^{n_{1}}}{n_{1}^{s_{1}} \ldots n_{k}^{s_{k}}}
$$

- They satisfy the recursion (ladder stepdown)

$$
\begin{align*}
z \frac{d}{d z} L i_{y_{s_{1}} \ldots y_{s_{k}}} & =L i_{y_{s_{1}-1} \ldots y_{s_{k}}} \text { if } s_{1}>1 \\
(1-z) \frac{d}{d z} L i_{1 . y_{s_{2}} \ldots y_{s_{k}}} & =L i_{y_{s_{2}} \ldots y_{s_{k}}} \text { if } k>1 \\
L i_{1}(z) & =\log \left(\frac{1}{1-z}\right) \tag{2}
\end{align*}
$$

- For the next step, we code the moves $z \frac{d}{d z}$ (resp. $(1-z) \frac{d}{d z}$ ) - or more precisely their sections $\int_{*_{0}}^{z} \frac{f(s)}{s} d s$ (resp. $\left.\int_{*_{1}}^{z} \frac{f(s)}{1-s} d s\right)$ - with $x_{0}$ (resp. $x_{1}$ ).

- Calling $S$ the prospective completed generating series

$$
\begin{equation*}
\sum_{w \in X^{*}}\langle S \mid w\rangle(z) w ; X=\left\{x_{0}, x_{1}\right\} \tag{3}
\end{equation*}
$$

Drinfel'd [1] indirectly proposed a way to complete the tree: from the general theory, the following system

$$
\left\{\begin{array}{l}
\mathbf{d}(S)=\left(\frac{x_{0}}{z}+\frac{x_{1}}{-1}\right) . S  \tag{4}\\
\lim _{\substack{z \rightarrow 0 \\
z \in \Omega}} S(z) e^{-x_{0} \log (z)}=1_{\mathcal{H}(\Omega)\langle X\rangle\rangle}
\end{array}\right.
$$

has a unique solution which is precisely Li (precise meaning of $\mathbf{d}$, the term by term derivation, is to be given below, see (6)).

- Minh [2] indicated a way to effectively compute this solution through (improper) iterated integrals.

1. V. Drinfel'd, On quasitriangular quasi-hopf algebra and a group closely connected with Gal( $(\mathbb{Q} / \mathbb{Q})$, Leningrad Math. J., 4, 829-860, 1991.
2. H. N. Minh, Summations of polylogarithms via evaluation transform,

Mathematics and Computers in Simulation, Vol. 42, 4-6, Nov. 1996, pp. 707-728

## Explicit construction of Drinfeld's $G_{0}$

Given a word $w$, we note $|w|_{x_{1}}$ the number of occurrences of $x_{1}$ within $w$

$$
\alpha_{0}^{z}(w)=\left\{\begin{array}{rll}
1_{\Omega} & \text { if } & w=1_{X^{*}}  \tag{5}\\
\int_{0}^{z} \alpha_{0}^{s}(u) \frac{d s}{1-s} & \text { if } & w=x_{1} u \\
\int_{1}^{z} \alpha_{0}^{s}(u) \frac{d s}{s} & \text { if } & w \in x_{0}^{*} \\
\int_{0}^{z} \alpha_{0}^{s}(u) \frac{d s}{s} & \text { if } & w=x_{0} u \text { and }|u|_{x_{1}}>0
\end{array}\right.
$$

The third line of this recursion implies

$$
\alpha_{0}^{z}\left(x_{0}^{n}\right)=\frac{\log (z)^{n}}{n!}
$$

one can check that (a) all the integrals (although improper for the fourth line) are well defined (b) the series $S=\sum_{w \in X^{*}} \alpha_{0}^{z}(w) w$ satisfies (4).


Some coefficients with $X=\left\{x_{0}, x_{1}\right\} ; u_{0}(z)=\frac{1}{z} ; u_{1}(z)=\frac{1}{1-z}, t_{0}=0$

$$
\left\langle S \mid x_{1}^{n}\right\rangle=\frac{(-\log (1-z))^{n}}{n!} \quad ; \quad\left\langle S \mid x_{0} x_{1}\right\rangle=\underbrace{\operatorname{Li}_{2}(z)}_{\text {cl.not. }}=\operatorname{Li}_{x_{0} x_{1}}(z)=\sum_{n \geq 1} \frac{z^{n}}{n^{2}}
$$

$$
\left\langle S \mid x_{0}^{2} x_{1}\right\rangle=\underbrace{\operatorname{Li}_{3}(z)}_{\text {cl.not. }}=\operatorname{Li}_{x_{0}^{2} x_{1}}(z)=\sum_{n \geq 1} \frac{z^{n}}{n^{3}} \quad ; \quad\left\langle S \mid x_{1} x_{0} x_{1}\right\rangle=\operatorname{Li}_{x_{1} x_{0} x_{1}}(z)=\operatorname{Li}_{[1,2]}(z)=\sum_{n_{1}>n_{2} \geq 1} \frac{z^{n_{1}}}{n_{1} n_{2}^{2}}
$$

$\left\langle S \mid x_{0} x_{1}^{2}\right\rangle=\operatorname{Li}_{x_{0} x_{1}^{2}}(z)=\operatorname{Li}_{[2,1]}(z)=\sum_{n_{1}>n_{2} \geq 1} \frac{z^{n_{1}}}{n_{1}^{2} n_{2}} \quad ; \quad\left\langle S \mid x_{0}^{n}\right\rangle=\frac{\log ^{n}(z)}{n!}$
We need now to do an excursion through the world of iterated integrals and hyperlogarithms but, first, let us recall some definitions of differential algebra.

## Some definitions and exemples of differential algebra

## Definition [Differential spaces]

A differential ring is a pair $(\mathcal{A}, d)$ with $\mathcal{A}$ a ring (with unit) and $d \in \mathfrak{D e r}(\mathcal{A})$ a distinguished derivation i.e. $d \in \operatorname{End}_{\mathbb{Z}}(\mathcal{A})$ s.t.

$$
d\left(f_{1} f_{2}\right)=d\left(f_{1}\right) f_{2}+f_{1} d\left(f_{2}\right) \text { holds identically }
$$

It is an easy exercise to show that $\operatorname{ker}(d)$ is a subring of $\mathcal{A}$.
A differential $k$-algebra is a differential ring where $\operatorname{ker}(d)=k$ is a field.

## Examples

Ex1) $\left(C^{\infty}(I, \mathbb{R}), \frac{d}{d x}\right)(I \subset \mathbb{R}$, an open interval) is a differential $\mathbb{R}$-algebra. Ex2) $\left(C^{\infty}\left(I_{1}, l_{2}, \mathbb{R}\right), \frac{d}{d x}\right)\left(l_{i}\right.$, as above, $\left.I_{1} \cap I_{2}=\emptyset\right)$ is only a differential ring. $\mathrm{Ex} 3)\left(\mathcal{H}(\Omega), \frac{d}{d z}\right)(\Omega$ is a connected open subset of $\mathbb{C})$ is a differential $\mathbb{C}$-algebra.

## Some definitions/2 and a construction.

## A construction

Let $(\mathcal{A}, d)$ be a commutative differential ring, $X$ an alphabet and $\mathcal{A}\langle\langle X\rangle\rangle$ be the corresponding algebra of (noncommutative, if $|X| \geq 2$ ) series. We extend $d$ to series by

$$
\begin{equation*}
\mathbf{d}(S):=\sum_{w \in X^{*}} d(\langle S \mid w\rangle) w \tag{6}
\end{equation*}
$$

It is an easy exercise to show that $\mathbf{d}$ is a derivation of $\mathcal{A}\langle\langle X\rangle\rangle$ and that $\operatorname{ker}(\mathbf{d})=k\langle\langle X\rangle\rangle($ here $k=\operatorname{ker}(d))$.

Recall that an operator $s \in \operatorname{End}_{\mathbb{Z}}(\mathcal{A})$ is a section of $d$ iff $d \circ s=l d_{\mathcal{A}}$. For example, in $\left(\mathcal{H}(\Omega), \frac{d}{d z}\right)$ has a section iff $\Omega$ is simply connected. In this case, all the sections read

$$
f \mapsto \lambda+\int_{z_{0}}^{z} f(s) d s ; \lambda \in \mathbb{C}
$$

## Lappo-Danilevskij setting

## J. A. Lappo-Danilevskij (J. A. Lappo-Danilevsky), Mémoires sur la théorie des systémes des équations différentielles linéaires. Vol. I, Travaux Inst. Physico-Math. Stekloff, 1934, Volume 6, 1-256

§ 2. Hyperlogarithmes. En abordant la résolution algorithmique du problème de Poincare, nous introduisons le système des tonctions

$$
L_{b}\left(a_{j_{1}}, a_{j_{2}}, \ldots, a_{j_{v}} \mid x\right), \quad\left(j_{1}, j_{2}, \ldots, j_{v}=1,2, \ldots, m ; v=1,2,3 \ldots\right)
$$

définies par les relations de récurrence:

$$
L_{b}\left(a_{j_{1}} \mid x\right)=\int_{b}^{x} \frac{d x}{x-a_{j_{1}}}=\log \frac{x-a_{j_{1}}}{b-a_{j_{1}}} ;
$$

$$
\begin{equation*}
L_{b}\left(a_{j_{1}} a_{i_{2}} \ldots a_{j_{v}} \mid x\right)=\int_{b}^{x} \frac{L_{b}\left(a_{j_{1}} \ldots a_{j_{v-1}} \mid x\right)}{x-a_{i_{v}}} d x \tag{10}
\end{equation*}
$$

où $b$ est un point fixe à distance finie, distinct des points $a_{1}, a_{2}, \ldots, a_{m}$.


## Lappo-Danilevskij setting/2

Let $\left(a_{i}\right)_{1 \leq i \leq n}$ be a family of complex numbers (all different) and $z_{0} \notin\left\{a_{i}\right\}_{1 \leq i \leq n}$, then

## Definition [Lappo-Danilevskij, 1928]

$$
L\left(a_{i_{1}}, \ldots, a_{i_{n}} \mid z_{0} \xrightarrow[\sim]{\gamma} z\right)=\int_{z_{0}}^{z} \int_{z_{0}}^{s_{n}} \ldots\left[\int_{z_{0}}^{s_{1}} \frac{d s}{s-a_{i_{1}}}\right] \cdots \frac{d s_{n}}{s_{n}-a_{i_{n}}} .
$$



## Remarks

(1) The result depends only on the homotopy class of the path and then the result is a holomorphic function on $\widetilde{B}\left(B=\mathbb{C} \backslash\left\{a_{1}, \cdots, a_{n}\right\}\right)$
(2) We can also study them in an open (simply connected) subset like the cleft plane


Figure: The cleft plane.

## Remarks/2

(3) The set of functions $\alpha_{z_{0}}^{z}(\lambda)=L\left(a_{i_{1}}, \ldots, a_{i_{n}} \mid z_{0} \stackrel{\gamma}{\sim} z\right.$ ) (or $1_{\Omega}$ if the list is void) has a lot of nice combinatorial properties

- Noncommutative ED with left multiplier
- Linear independence
- Shuffle property
- Factorisation
- Possibility of left or right multiplicative renormalization at a neighbourhood of the singularities
- Extension to rational functions

Now, in order to use the rich allowance of notations invented by algebraists, computer scientists, combinatorialists and physicists about NonCommutative Formal Power Series (NCFPS ${ }^{1}$ ), we code the lists by words which will permit to do linear algebra and topology on the indexing.
${ }^{1}$ This was the initial intent of the series of conferences FPSAC.

## Coding by words

Consider again the mapping

$$
\alpha_{z_{0}}^{z}(\lambda)=L\left(a_{i_{1}}, \ldots, a_{i_{n}} \mid z_{0} \xrightarrow[\sim]{\gamma} z\right)=: \alpha_{z_{0}}^{z}\left(x_{i_{1}} \ldots x_{i_{n}}\right)
$$

Lappo-Danilevskij recursion is from left to right, we will use here right to left indexing to match with ${ }^{2}$

1. P. Cartier, Jacobiennes généralisées, monodromie unipotente et intégrales itérées, Séminaire Bourbaki, Volume 30 (1987-1988), Talk no. 687, p. 31-52
2. V. Drinfel'd, On quasitriangular quasi-hopf algebra and a group closely connected with $\operatorname{Gal}(\overline{\mathbb{Q}} / \mathbb{Q})$, Leningrad Math. J., 4, 829-860, 1991.
3. H.J. Susmann, A product expansion for Chen Series, in Theory and Applications of Nonlinear Control Systems, C.I. Byrns and Lindquist (eds). 323-335, 1986
4. P. Deligne, Equations Différentielles à Points Singuliers Réguliers, Lecture Notes in Math, 163, Springer-Verlag (1970).
[^0]
## Words

We recall basic definitions and properties of the free monoid [1]:

- An alphabet is a set $X$ (of variables, indeterminates etc.
- Words of length $n\left(\right.$ set $\left.X^{n}\right)$ are mappings $w:[1 \cdots n] \rightarrow X$. The letter at place $j$ is $w[j]$, the empty word $1_{X^{*}}$ is the sole mapping $\emptyset \rightarrow X$ (i.e. of length 0 ). As such, we get, by composition
- of $\mathfrak{S}_{n}$ on the right (noted w. $\sigma$ ) and
- of the transformation monoid $X^{X}$ on the left
- Words concatenate by shifting and union of domains, this law is noted conc
- $\left(X^{*}\right.$, conc, $\left.1_{X^{*}}\right)$ is the free monoid of base $X$.
- Given a total order on $X,\left(X^{*}\right)$ is totally ordered by the graded lexicographic ordering $\prec_{\text {glex }}$ (length first and then lexicographic from left to right). This ordering is compatible with the monoid structure.
[1] M. Lothaire, Combinatorics on Words, 2nd Edition, Cambridge Mathematical Library (1997)


## Lyndon words and factorizations

- Let $c=[2 \cdots n, 1]$ be the large cycle
- a Lyndon word is a word which is strict minimum of its conjugacy class (as a family) i.e. $(\forall 1 \leq k<n)\left(I \prec_{\text {lex }} I . \sigma^{k}\right)$
- Each word $w$ factorizes uniquely as $w=l_{1}^{\alpha_{1}} \ldots l_{n}^{\alpha_{n}}$ with $l_{i} \in \mathcal{L} y n(X)$ and $I_{1} \prec \cdots \prec I_{n}$ (strict). We write

$$
\begin{equation*}
X^{*}=\prod_{I \in \mathcal{L y n}(X)}^{\searrow} I^{*} \tag{7}
\end{equation*}
$$

- If $\left(P_{l}\right)_{l \in \mathcal{L} y n(X)}$ is any multihomogeneous basis of $\operatorname{Lie}_{R}\langle X\rangle(R$ a $\mathbb{Q}$-algebra) then

$$
\sum_{w \in X^{*}} w \otimes w=\prod_{l \in \mathcal{L y n}(X)}^{\searrow} e^{S_{l} \otimes P_{l}}
$$

where $P_{w}$ is computed after eq. 7 and $S_{w}$ is such that $\left\langle S_{u} \mid P_{v}\right\rangle=\delta_{u, v}$.

## Noncommutative generating series

Let $X^{*}$ be the set of words constructed on the alphabet $X$. We now have a function $w \mapsto \alpha_{z_{0}}^{z}(w)$ which maps words to holomorphic functions on $\Omega$. This is a noncommutative series of variables in $X$ and coefficients in $\mathcal{H}(\Omega)$. It is convenient here to use the "sum notation".

$$
S=\sum_{w \in X^{*}} \alpha_{z_{0}}^{z}(w) w
$$

and it is not difficult to see that $S$ is the unique solution of

$$
\left\{\begin{align*}
\mathbf{d}(S) & =M . S \text { with } M=\sum_{i=1}^{n} \frac{x_{i}}{z-a_{i}}  \tag{8}\\
S\left(z_{0}\right) & =1_{\mathcal{H}(\Omega)\langle X\rangle\rangle}
\end{align*}\right.
$$

## The series $S_{\text {Pic }}^{z_{0}}$

The series $S$ can be computed by Picard's process

$$
S_{0}=1_{X^{*}} ; S_{n+1}=1_{X^{*}}+\int_{z_{0}}^{z} M \cdot S_{n}
$$

and its limit is $S_{P i c}^{z_{0}}:=\lim _{n \rightarrow \infty} S_{n}=\sum_{w \in X^{*}} \alpha_{z_{0}}^{z}(w) w$. One has,

## Proposition

i) Series $S_{\text {Pic }}^{z_{0}}$ is the unique solution of

$$
\left\{\begin{align*}
\mathbf{d}(S) & =M . S \text { with } M=\sum_{i=1}^{n} \frac{x_{i}}{z-a_{i}}  \tag{9}\\
S\left(z_{0}\right) & =1_{\mathcal{H}(\Omega)\langle X\rangle\rangle}
\end{align*}\right.
$$

ii) The complete set of solutions of $\mathbf{d}(S)=M . S$ is $S_{\text {Pic }}^{z_{0}} \cdot \mathbb{C}\langle\langle X\rangle\rangle$.

These (Noncommutative) Differential Equations with Multipliers (as eq. 9) admit a powerful calculus and set of properties .

## Main facts about Non Comm. Diff. Eq.

## Theorem

Let us consider the following two-sided multiplier equation (TSM)

$$
\begin{equation*}
(T S M) \quad \mathbf{d} S=M_{1} S+S M_{2} . \tag{10}
\end{equation*}
$$

with $S \in \mathcal{H}(\Omega)\langle\langle X\rangle\rangle, M_{i} \in \mathcal{H}(\Omega)_{+}\langle\langle X\rangle\rangle$
(i) Solutions of (TSM) form a $\mathbb{C}$-vector space.
(ii) Solutions of (TSM) have their constant term (as coefficient of $1_{X^{*}}$ ) which are constant functions (on $\Omega$ ); there exists solutions with constant coefficient $1_{\Omega}$ (hence invertible).
(iii) If two solutions coincide at one point $z_{0} \in \Omega$ (or asymptotically), they coincide everywhere.

## Theorem (cont'd)

(iv) Let be the following one-sided equations

$$
\begin{equation*}
\left(L M_{1}\right) \quad \mathbf{d} S=M_{1} S \quad\left(R M_{2}\right) \quad \mathbf{d} S=S M_{2} \tag{11}
\end{equation*}
$$

and let $S_{1}$ (resp. $S_{2}$ ) be a solution of $\left(L M_{1}\right)$ (resp. $\left(L M_{2}\right)$ ), then $S_{1} S_{2}$ is a solution of (TSM). Conversely, every solution of (TSM) can be constructed so.
(v) Let $S_{\text {Pic }, L M_{1}}^{z_{0}}$ (resp. $S_{\text {Pic }, R M_{2}}^{z_{0}}$ ) the unique solution of $\left(L M_{1}\right)$ (resp. $\left.\left(R M_{2}\right)\right)$ s.t. $S\left(z_{0}\right)=1_{\mathcal{H}(\Omega)_{+}\langle\langle X\rangle\rangle}$ then, the space of all solutions of (TSM) is

$$
S_{P i c, L M_{1}}^{z_{0}} \cdot \mathbb{C}\langle\langle X\rangle\rangle . S_{P i c, R M_{2}}^{z_{0}}
$$

(vi) If $M_{i}, i=1,2$ are primitive for $\Delta_{\text {ШI }}$ and if $S$, a solution of (TSM), is group-like at one point (or asymptotically), it is group-like everywhere (over $\Omega$ ).

## Linear independence without monodromy: Abstract theorem

## Theorem (DDMS, 2011)

Let $(\mathcal{A}, d)$ be a $k$-commutative associative differential algebra with unit $(k e r(d)=k$ is a field) and $\mathcal{C}$ be a differential subfield of $\mathcal{A}$ (i.e. $d(\mathcal{C}) \subset \mathcal{C}$ ). We suppose that $S \in \mathcal{A}\langle\langle X\rangle$ is a solution of the differential equation

$$
\begin{equation*}
\mathbf{d}(S)=M S ;\left\langle S \mid 1_{X^{*}}\right\rangle=1_{\mathcal{A}} \tag{12}
\end{equation*}
$$

where the multiplier $M$ is a homogeneous series (a polynomial in the case of finite $X$ ) of degree 1, i.e.

$$
\begin{equation*}
M=\sum_{x \in X} u_{x} x \in \mathcal{C}\langle\langle X\rangle\rangle \tag{13}
\end{equation*}
$$

The following conditions are equivalent :

## Abstract theorem/2

## Theorem (cont'd)

i) The family $(\langle S \mid w\rangle)_{w \in X^{*}}$ of coefficients of $S$ is free over $\mathcal{C}$.
ii) The family of coefficients $(\langle S \mid y\rangle)_{y \in X \cup\left\{1_{x^{*}}\right\}}$ is free over $\mathcal{C}$.
iii) The family $\left(u_{x}\right)_{x \in X}$ is such that, for $f \in \mathcal{C}$ and $\alpha_{x} \in k$

$$
\begin{equation*}
d(f)=\sum_{x \in X} \alpha_{x} u_{x} \Longrightarrow(\forall x \in X)\left(\alpha_{x}=0\right) . \tag{14}
\end{equation*}
$$

iv) The family $\left(u_{x}\right)_{x \in X}$ is free over $k$ and

$$
\begin{equation*}
d(\mathcal{C}) \cap \operatorname{span}_{k}\left(\left(u_{x}\right)_{x \in X}\right)=\{0\} . \tag{15}
\end{equation*}
$$

Independence of Hyperlogarithms over Function Fields via Algebraic Combinatorics, M. Deneufchâtel, GHED, V. Hoang Ngoc Minh and A. I. Solomon, 4th International Conference on Algebraic Informatics, Linz (2011). Proceedings, Lecture Notes in Computer Science, 6742, Springer.

## Need for localization

In practical cases, we have a differential subalgebra of $\mathcal{C}_{0} \subset \mathcal{H}(\Omega)$

- $\mathbb{C}[z]$
- $\mathbb{C}\left[z, z^{-1},(1-z)^{-1}\right]$
- $\mathbb{C}\left[z^{\alpha}(1-z)^{-\beta}\right]_{\alpha, \beta \in \mathbb{C}}$

Realizing the fraction field $\operatorname{Fr}\left(\mathcal{C}_{0}\right)$ as (differential) field of germs makes the computation difficult to handle. It is easier to check the freeness of the " basic triangle" directly with the algebra. For instance, for the polylogarithms, we just have to show that, given 3 polynomials,

$$
\begin{equation*}
P_{1}(z)+P_{2}(z) \log (z)+P_{3}(z)\left(\log \left(\frac{1}{1-z}\right)\right)=0_{\Omega} \Longrightarrow P_{i} \equiv 0 \tag{16}
\end{equation*}
$$

which is straightforward (with the freeness of the comparison scale $x \mapsto x^{u} \log (x)^{v}$ in $] 0,1[)$.

## Localization

## Theorem (Thm1 in "Linz", Localized form)

Let $(\mathcal{A}, d)$ be a commutative associative differential ring $(\operatorname{ker}(d)=k$ being a field) and $\mathcal{C}$ be a differential subring (i.e. $d(\mathcal{C}) \subset \mathcal{C}$ ) of $\mathcal{A}$ which is an integral domain containing the field of constants.
We suppose that, for all $x \in X, u_{x} \in \mathcal{C}$ and that $S \in \mathcal{A}\langle\langle X\rangle$ is a solution of the differential equation (12) and that $\left(u_{x}\right)_{x \in X} \in \mathcal{C}^{X}$.
The following conditions are equivalent :
i) The family $(\langle S \mid w\rangle)_{w \in X^{*}}$ of coefficients of $S$ is free over $\mathcal{C}$.
ii) The family of coefficients $(\langle S \mid y\rangle)_{y \in X \cup\left\{1_{x^{*}}\right\}}$ is free over $\mathcal{C}$.
iii') For all $f_{1}, f_{2} \in \mathcal{C}, f_{2} \neq 0$ and $\alpha \in k^{(X)}$, we have the property

$$
\begin{equation*}
W\left(f_{1}, f_{2}\right)=f_{2}^{2}\left(\sum_{x \in X} \alpha_{x} u_{x}\right) \Longrightarrow(\forall x \in X)\left(\alpha_{x}=0\right) \tag{17}
\end{equation*}
$$

where $W\left(f_{1}, f_{2}\right)$, the wronskian, stands for $d\left(f_{1}\right) f_{2}-f_{1} d\left(f_{2}\right)$.

In fact, in the localized form and with $\mathcal{C}$ not a differential field, (iii) is strictly weaker than (iii'), as shows the following family of counterexamples
(1) $\Omega=\mathbb{C} \backslash(]-\infty, 0])$
(2) $X=\left\{x_{0}\right\}, u_{0}=z^{\beta}, \beta \notin \mathbb{Q}$
(3) $\mathcal{C}_{0}=\mathbb{C}\left\{\left\{z^{\beta}\right\}\right\}=\mathbb{C} .1_{\Omega} \oplus \operatorname{span}_{\mathbb{C}}\left\{z^{(k+1) \beta-1}\right\}_{k, I \geq 0}$
(9) $S=1_{\Omega}+\left(\sum_{n \geq 1} \frac{z^{n(\beta+1)}}{(\beta+1)^{n} n!}\right)$

Let us show that, for these data (iii) holds but not (i). Firstly, we show that $\mathcal{C}_{0}=\mathbb{C}\left\{\left\{z^{\beta}\right\}\right\}$ corresponds to the given direct sum. We remark that the family $\left(z^{\alpha}\right)_{\alpha \in \mathbb{C}}$ is $\mathbb{C}$-linearly free (within $\mathcal{H}(\Omega)$ ), which is a consequence of the fact that they are eigenfunctions, for different eigenvalues, of the Euler operator $z \frac{d}{d z}$.

## Then

$$
\mathbb{C}\left\{\left\{z^{\beta}\right\}\right\}=\mathbb{C} 1_{\Omega} \oplus \operatorname{span}_{\mathbb{C}}\left\{z^{(k+1) \beta-I}\right\}_{k, I \geq 0}=\operatorname{span}_{\mathbb{C}}\left\{z^{\left(k^{\prime}\right) \beta-I}\right\}_{k^{\prime}, l \geq 0}
$$

comes from the fact that the RHS is a subset of the LHS as, for all, $k, I \geq 0, z^{(k+1) \beta-I} \in \mathbb{C}\left\{\left\{z^{\beta}\right\}\right\}$. Finally $1_{\Omega} \in \mathbb{C}\left\{\left\{z^{\beta}\right\}\right\}$ by definition $(\mathbb{C}\{\{X\}\}$ is a $\mathbb{C}$-AAU).
(iii) is fulfilled. Here
$u_{0}(z)=z^{\beta}$ is such that, for any $f \in \mathcal{C}_{0}$ and $c_{0}$ in $\mathbb{C}$, we have

$$
\begin{equation*}
c_{0} u_{0}=\partial_{z}(f) \Longrightarrow\left(c_{0}=0\right) \tag{18}
\end{equation*}
$$

But (i) is not because we have the following relation

$$
(\beta+1) z^{\beta-1}\left\langle S \mid x_{0}\right\rangle-z^{2 \beta} \cdot 1_{\Omega}=0
$$

## Sketch of the proof

After some technicalities, we show that (12) can be transported in $\mathcal{A}\left[\left(\mathcal{C}^{\times}\right)^{-1}\right]$ by means of the following commutative diagram and back.


## Concrete theorem

## Theorem (DDMS, 2011)

Let $S \in \mathcal{H}(\Omega)\langle\langle X\rangle\rangle$ be a solution of the (Left Multiplier) equation

$$
\mathbf{d}(S)=M S ;\left\langle S \mid 1_{X^{*}}\right\rangle=1_{\Omega} .
$$

The following are equivalent:
i) the family $(\langle S \mid w\rangle)_{w \in X^{*}}$ of coefficients is independant (linearly) over $\mathcal{C}$.
ii) the family of coefficients $(\langle S \mid x\rangle)_{x \in X \cup\left\{1_{x^{*}}\right\}}$ is independant (linearly) over $\mathcal{C}$.
iii) the family $\left(u_{x}\right)_{x \in X}$ is such that, for $f \in \mathcal{C}$ et $\alpha_{x} \in \mathbb{C}$

$$
\mathrm{d}(f)=\sum_{x \in X} \alpha_{x} u_{x} \Longrightarrow(\forall x \in X)\left(\alpha_{x}=0\right)
$$

## Solutions as m-characters with values in $\mathcal{H}(\Omega)$

We have seen that solutions of systems like that of hyperlogarithms (8) possess the shuffle property i.e. defining the shuffle product by the recursion

$$
\begin{aligned}
u \amalg 1_{Y^{*}} & =1_{Y^{*} \amalg u} u=u \text { and } \\
a u \amalg b v & =a\left(u_{\amalg} b v\right)+b(a u \amalg v)
\end{aligned}
$$

one has

$$
\begin{equation*}
\left.\left\langle S_{P i c}^{z_{0}}\right| u \text { шI } v\right\rangle=\left\langle S_{P i c}^{z_{0}} \mid u\right\rangle\left\langle S_{P i c}^{z_{0}} \mid v\right\rangle ;\left\langle S \mid 1_{X^{*}}\right\rangle=1_{\Omega} \tag{20}
\end{equation*}
$$

(product in $\mathcal{H}(\omega)$ ).
Now it is not difficult to check that the characters of type (20) form a group (these are characters on a Hopf algebra, see below). I would be interesting to have at our disposal a system of local coordinates in order to perform estimates in neighbourhood of the singularities.

## Applying MRS to a shuffle character

Now, remarking that this factorization lives within the subalgebra

$$
\operatorname{Iso}(X)=\left\{T \in R\left\langle\left\langle X^{*} \otimes X^{*}\right\rangle\right\rangle \mid(u \otimes v \in \operatorname{supp}(T) \Longrightarrow|u|=|v|)\right\}
$$

if $Z$ is any shuffle character, one has

$$
Z=(Z \otimes I d)\left(\sum_{w \in X^{*}} w \otimes w\right)=\prod_{I \in \mathcal{L} y n X}^{\searrow} e^{\left\langle Z \mid S_{l}\right\rangle P_{l}}
$$

We would like to get such a factorisation at our disposal for other types of (deformed) shuffle products, this will be done in the second part of the talk. Let us first, with this factorization (MRS) at hand, construct explicitely Drinfeld's solution $G_{0}$.

## Extensions of MRS to other shuffles

| Name | Formula (recursion) | $\varphi$ | Type |
| :---: | :---: | :---: | :---: |
| Shuffle [21] | $a u ш b v=a(u ш b v)+b(a u ш v)$ | $\varphi \equiv 0$ | 1 |
| Stuffle [19] | $\begin{gathered} x_{i} u \uplus x_{j} v=x_{i}\left(u \pm x_{j} v\right)+x_{j}\left(x_{i} u \uplus v\right) \\ +x_{i+j}(u \uplus v) \end{gathered}$ | $\varphi\left(x_{i}, x_{j}\right)=x_{i+j}$ | I |
| Min-stuffle [7] | $\begin{gathered} x_{i} u \boxminus x_{j} v=x_{i}\left(u \boxminus x_{j} v\right)+x_{j}\left(x_{i} u \doteq v\right) \\ -x_{i+j}(u \sqcup v) \end{gathered}$ | $\varphi\left(x_{i}, x_{j}\right)=-x_{i+j}$ | III |
| Muffle [14] | $\begin{gathered} x_{i} u \bullet x_{j} v=x_{i}\left(u \bullet x_{j} v\right)+x_{j}\left(x_{i} u \bullet v\right) \\ +x_{i \times j}(u \bullet v) \end{gathered}$ | $\varphi\left(x_{i}, x_{j}\right)=x_{i \times j}$ | 1 |
| $q$-shuffle [3] |  | $\varphi\left(x_{i}, x_{j}\right)=q x_{i+j}$ | III |
| $q$-shuffle ${ }_{2}$ | $\begin{gathered} x_{i} u \uplus_{q} x_{j} v=x_{i}\left(u \uplus_{q} x_{j} v\right)+x_{j}\left(x_{i} u \uplus_{q} v\right) \\ \\ +q^{i . j} x_{i+j}\left(u \uplus_{q} v\right) \end{gathered}$ | $\varphi\left(x_{i}, x_{j}\right)=q^{i, j} x_{i+j}$ | II |
| $\begin{gathered} \hline \text { LDIAG }\left(1, q_{s}\right)[10] \\ \text { (non-crossed, } \\ \text { non-shifted) } \\ \hline \end{gathered}$ | $\begin{aligned} a u ш b v=a( & u ш b v)+b(a u ш v) \\ & +q_{s}^{\|a\|\|b\|} a . b(u ш v) \end{aligned}$ | $\varphi(a, b)=q_{s}^{\|a\|\|b\|}(a . b)$ | II |
| $\bar{q}$-Infiltration [12] | $\begin{gathered} a u \uparrow b v=a(u \uparrow b v)+b(a u \uparrow v) \\ +q \delta_{a, b} a(u \uparrow v) \end{gathered}$ | $\varphi(a, b)=q \delta_{a, b} a$ | III |
| AC-stuffle | $\begin{gathered} a u \omega_{\varphi} b v=a\left(u \omega_{\varphi} b v\right)+b\left(a u \omega_{\varphi} v\right) \\ +\varphi(a, b)\left(u \omega_{\varphi} v\right) \end{gathered}$ | $\begin{gathered} \varphi(a, b)=\varphi(b, a) \\ \varphi(\varphi(a, b), c)=\varphi(a, \varphi(b, c)) \end{gathered}$ | IV |
| Semigroupstuffle | $\begin{gathered} x_{t} u \omega_{\perp} x_{s} v=x_{t}\left(u \omega_{\perp} x_{s} v\right)+x_{s}\left(x_{t} u \omega_{\perp} v\right) \\ +x_{t \perp s}\left(u \omega_{\perp} v\right) \\ \hline \end{gathered}$ | $\varphi\left(x_{t}, x_{s}\right)=x_{t \perp s}$ | I |
| $\varphi$-shuffle | $\begin{aligned} & a u \uplus_{\varphi} b v=a\left(u ш_{\varphi} b v\right)+b\left(a u ш_{\varphi} v\right) \\ &+\varphi(a, b)\left(u \omega_{\varphi} v\right) \end{aligned}$ | $\varphi(a, b)$ law of AAU | V |

Of course, the $q$-shuffle is equal to the (classical) shuffle when $q=0$. As for the $q$ -

[^1]
## About Drinfeld's solutions $G_{0}, G_{1}$

We give below the computational construction of a solution with an asymptotic condition.
In his paper (2. above), V. Drinfel'd states that there is a unique solution (called $G_{0}$ ) of

$$
\left\{\begin{array}{l}
\mathbf{d}(S)=\left(\frac{x_{0}}{z}+\frac{x_{1}}{1-z}\right) \cdot S \\
\lim _{\substack{z \rightarrow 0 \\
z \in \Omega}} S(z) e^{-x_{0} \log (z)}=1_{\mathcal{H}(\Omega)\langle X\rangle\rangle}
\end{array}\right.
$$

and a unique solution (called $G_{1}$ ) of

$$
\left\{\begin{array}{l}
\mathbf{d}(S)=\left(\frac{x_{0}}{z}+\frac{x_{1}}{1-z}\right) \cdot S \\
\lim _{\substack{z \rightarrow 1 \\
z \in \Omega}} e^{x_{1} \log (1-z)} S(z)=1_{\mathcal{H}(\Omega)}\langle\langle X\rangle\rangle
\end{array}\right.
$$

Let us give here, as an example, a construction of $G_{0}$ ( $G_{1}$ can be derived or checked by symmetry).
satisfies the one sided evolution equation (LM)

$$
\mathbf{d}(S)=\left(\frac{x_{0}}{z}+\frac{x_{1}}{1-z}\right) \cdot S
$$

hence $T=\left(\sum_{w \in X^{*}} \alpha_{0}^{z}(w) w\right) e^{-x_{0} \log (z)}$ satisfies the two sided evolution equation (TSM)

$$
\mathbf{d}(T)=\left(\frac{x_{0}}{z}+\frac{x_{1}}{1-z}\right) \cdot T+T \cdot\left(-\frac{x_{0}}{z}\right)
$$

Now, using Radford's theorem, one proves that $S$ is group-like, factorizes through (MRS) and that $\lim _{z \rightarrow 0} T(z)=1$.
This asymptotic condition on $T$ implies that $S=G_{0}$.

## Conclusion

- For Series with variable coefficients, we have a theory of Noncommutative Evolution Equation sufficiently powerful to cover iterated integrals and multiplicative renormalisation
- MRS factorisation allows to remove singularities with simple counterterms
- MRS factorisation can be performed in many other cases (like stuffle for harmonic functions)
- Use of combinatorics on words gives a necessary and sufficient condition on the "inputs" to have linear independance of the solutions over higher function fields.
- Picard (Chen) solutions admit enlarged indexing w.r.t. compact convergence on $\Omega$ (polylogarithmic case) but Drinfeld's $G_{0}$ has a domain which includes only some rational series.
- Localization is possible (under certain conditions).


## Thank you for your attention.

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Hoang.Ngocminh@lipn.univ-paris13.fr Gerard.Duchamp@lipn.univ-paris13.fr gheduchamp@gmail.com

## Figure: CAP18 \& CAP19




[^0]:    ${ }^{2}$ Data structures are Letters (1,2), Vector fields (3) and Matrices (4).
    83rd Seminaire Lotharingien de $\overline{\text { Combinatoire }}$

[^1]:    V.C. Bùi, Matthieu Deneufchâtel,G.H.E. Ducl Non-commutative differential equations.

