86th Séminaire Lotharingien de Combinatoire

Bad Boll - September 8, 2021



Slack realization spaces and realizability of polytopes

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joint work with João Gouveia (U Coimbra) and Amy Wiebe (FU Berlin)

A classical problem in Polytope Theory concerns the existence of a convex realization of a given abstract polytope (lattice).

Theorem (Steinitz, 1922) A graph **G** is the edge graph of a **3**-polytope if and only if **G** is simple, planar and **3**-connected.

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Similar results do not exist in higher dimension.

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Question Can we find certificates without any prescribed structure?

The Slack Variety

P abstract **d**-dim polytope with vertices v_1, \dots, v_n and facets F_1, \dots, F_m .

Symbolic slack matrix $S_P(\mathbf{x})$: sparse generic matrix whose (i, j) entry is zero if $v_i \in F_i$ and a variable otherwise.



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Slack variety $\mathcal{V}_{\mathcal{P}} := \overline{\{\xi \in \mathbb{R}_*^{\mathcal{N}} : \operatorname{rank}(S_{\mathcal{P}}(\xi)) \leq d + 1\}} = \mathcal{V}(I_{\mathcal{P}})$ (slack ideal).

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Theorem (Gouveia, M., Thomas, Wiebe, 2019)

{Realizations of polytope **P** up to projective equivalence} $\longleftrightarrow^{1:1} \mathcal{V}_P \cap \mathbb{R}^{N}_{++}$ up to column and row scalings by positive scalars.

In particular, **P** is **not realizable** if and only if $\mathcal{V}_{P} \cap \mathbb{R}_{++}^{N} = \emptyset$.

The Grassmannian Variety

Gr(d + 1, n) be the Grassmannian variety coordinatized by Plücker coordinates $\{p_J : J \subseteq \{1, ..., n\}, |J| = d + 1\}$.

 $\Gamma_{o} = \{p_{J} : J \subseteq F_{i} \text{ facet of } P\} \text{ and } \Gamma_{1} = \{p_{J} : J \text{ facet extension of } P\}.$

Facet extension: $J = \{j_0, ..., j_d\}$, where $j_0, ..., j_{d-1}$ span a facet of **P** and j_d is not on that facet.

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Grassmannian variety of P:

$$\operatorname{Gr}(P) := \prod_{\Gamma_1} \left\{ \left\{ \xi \in \operatorname{Gr}(d+1,n) : \begin{array}{l} p_J(\xi) = 0 & \text{if } J \in \Gamma_0 \\ p_J(\xi) \neq 0 & \text{if } J \in \Gamma_1 \end{array} \right\} \right\}$$

where Π_{Γ_1} is the signed projection onto the coordinates of $\Gamma_1.$

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Theorem (Gouveia, M., Wiebe, 2020+) The Grassmannian variety Gr(P) and the slack variety V_P are essentially equivalent.

In particular, **P** is not realizable if and only if $Gr(P) \cap \mathbb{R}_{++}^N = \emptyset$.

P is not realizable if a certain variety has no positive points.

Theorem (Becker, 1986) A real variety $\mathcal{V}(I) \subseteq \mathbb{R}^N$ has no positive point if and only if there is an element of I of the form

$$\mathbf{x}^{lpha} + \sum \mathbf{x}^{eta_i} \sigma_i(\mathbf{x}),$$

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In the case of **Gr**(*P*), the witness polynomials are called **final polynomials** and were used for certifying non-realizability [Bokowski, Sturmfels, 1989], [Bokowski, Richter, 1990].

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An alternative is to consider scalar σ_i . We say that a polynomial is **positive** if it is non-zero and has non-negative coefficients.

Proposition Given a real variety $\mathcal{V}(I) \subseteq \mathbb{R}^N$, if I contains a positive polynomial, then $\mathcal{V}(I)$ has no positive points.

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Slack model: slack ideal generated in higher degree, lower number of variables that can be further reduced by parametrizing the variety.

Let **P** be an abstract **d**-dimensional polytope.

Inputs:

- F: list of facets of abstract polytope P as lists of vertex labels
- d: dimension of P
- k: maximum number of factors in the products of constraints
- *l*: maximum degree of constraints to consider

Aim: Find a (k, l)-positive polynomial in \mathcal{V}_P .

The algorithm is implemented in Macaulay2 and Gurobi.

Step 1: Construct parametrization of $S_P(\mathbf{x})$

- Consider or construct an orientation of the facets of P.
- Choose a flag $\mathcal{F} = \{F_1, \dots, F_{d+1}\}$ of facets of **P**:

 $F_1 \supseteq (F_1 \cap F_2) \supseteq \cdots \supseteq (F_1 \cap \cdots \cap F_{d+1}) = \emptyset.$



- Consider the reduced symbolic slack matrix S_F(x), whose transpose rows are S^{v_i}_F.
- Construct the parametrized slack matrix entries

 $\mathsf{S}_{\mathsf{P}}(\mathbf{x}_{\mathcal{F}})_{ij} := \det[\mathsf{S}_{\mathcal{F}}^{\mathsf{v}_{j_1}} \cdots \mathsf{S}_{\mathcal{F}}^{\mathsf{v}_{j_d}} \; \mathsf{S}_{\mathcal{F}}^{\mathsf{v}_i}] = p_{\{\mathsf{v}_i\} \cup F_j}(\mathsf{S}_{\mathcal{F}}(\mathbf{x})),$

where v_{j_1}, \ldots, v_{j_d} span facet F_j .

Step 2: Construct constraints for linear program

The set of entries of $S_P(\mathbf{x}_F)$ and any products thereof gives us a collection of positive polynomials.

- Let $G_{k,l} = \{g_1, ..., g_M\}$ be the set of entries of $S_P(\mathbf{x}_F)$ of degree $\leq l$ and of products of $\leq k$ of these entries, where $g_i = \sum_{\alpha} a_i^{\alpha} \mathbf{x}^{\alpha}$.
- We store the coefficients of **g**_i in a matrix

$$\mathcal{M}_{\boldsymbol{k},\boldsymbol{l}} = \begin{array}{cccc} \boldsymbol{x}^{\alpha_1} & \boldsymbol{x}^{\alpha_2} & \cdots & \boldsymbol{x}^{\alpha_t} \\ g_1 \\ g_2 \\ \vdots \\ g_M \end{array} \begin{bmatrix} a_1^{\alpha_1} & a_1^{\alpha_2} & \cdots & a_1^{\alpha_t} \\ a_2^{\alpha_1} & a_2^{\alpha_2} & \cdots & a_2^{\alpha_t} \\ \vdots & \vdots & \ddots & \vdots \\ a_M^{\alpha_1} & a_M^{\alpha_2} & \cdots & a_M^{\alpha_t} \end{bmatrix}$$

Notice that $\mathcal{M}_{k,l}$ records the linearization of the polynomials in $G_{k,l}$, that will be the constraints of our linear program.

We solve the following dual program whose coefficient matrix is the transpose of $\mathcal{M}_{k,l}$ using **Gurobi**:

min 1 –
$$\sum_{i=1}^{M} c_i$$
 subject to $\sum_i c_i a_i^{\alpha} = 0$ for all α
 $\sum_{i=1}^{M} c_i \leq 1$
 $c_i \geq 0$ for all $i = 1, ..., M$.

This is always feasible and its optimal values are **o** or **1**. If it is **o**, then we have a non-realizability certificate for **P** as $\sum g_i = \mathbf{o}$.

[Doolittle, 2020+] constructed some 4-dimensional simplicial spheres whose realizability was not known.

Example 1: Doolittle's sphere

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One of them has **11** vertices and **44** facets. We consider the flag with positively oriented facets

$$\mathcal{F} = \{F_1 = \{5, 6, 7, 8\}, F_2 = \{6, 7, 8, 9\},\$$

$$F_3 = \{7, 8, 9, 10\}, F_4 = \{1, 3, 11, 7\}, F_5 = \{4, 8, 11, 9\}\}.$$

A reduced slack matrix
$$S_{\mathcal{F}}(\mathbf{x})$$
 is

∑ X _(1,1)	X _(1,2)	x _(1,3)	0	X _(1,5)]
X _(2,1)	X _(2,2)	X _(2,3)	X _(2,4)	X _(2,5)
X _(3,1)	Х _(3,2)	х _(3,3)	0	x _(3,5)
X _(4,1)	Х _(4,2)	Х _(4,3)	x _(4,4)	0
0	X _(5,2)	x _(5,3)	X _(5,4)	x _(5,5)
0	0	x _(6,3)	x _(6,4)	x _(6,5)
0	0	0	0	X _(7,5)
0	0	0	X _(8,4)	0
X _(9,1)	0	0	X _(9,4)	0
X _(10,1)	X _(10,2)	0	X _(10,4)	X _(10,5)
$[X_{(11,1)}]$	X _(11,2)	X _(11,3)	0	ο」

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Proposition (Gouveia, M., Wiebe, 2021+) A **(4,2)-positive polynomial** certificate of non-realizability is:

$$S_{(10,6)}S_{(8,11)}S_{(5,2)}S_{(11,2)} + S_{(9,12)}S_{(10,7)}S_{(3,2)}S_{(11,2)} + S_{(4,7)}S_{(8,8)}S_{(3,2)}S_{(11,2)}$$

$$+S_{(9,13)}S_{(6,5)}S_{(3,2)}S_{(10,2)}+S_{(10,6)}S_{(8,10)}S_{(2,2)}S_{(11,2)}+S_{(9,13)}S_{(6,9)}S_{(3,2)}S_{(4,2)}=0\text{,}$$

where we use some additional facets $F_6, ..., F_{13}$.

Example 2: Combinatorial Prismatoids

Prismatoid: all vertices lie in two parallel hyperplanes. Used by **Francisco Santos** to construct a

counterexample to the Hirsch Conjecture.



[Criado, Santos, 2019] constructed 4092 abstract 5-dimensional non*d*-step prismatoids.

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Theorem (Gouveia, M., Wiebe, 2021+) The **40** Criado-Santos prismatoids with **14** and **15** vertices are not realizable as convex polytopes.

Prismatoid #3513 has dimension 5, 14 vertices and 94 facets. We consider the flag:

$$\mathcal{F} = \{F_1 = \{1, 2, 6, 8, 14\}, F_2 = \{1, 6, 8, 14, 9\}, F_3 = \{1, 5, 8, 9, 14\}, F_4 = \{\mathbf{8}, \mathbf{9}, \mathbf{10}, \mathbf{11}, \mathbf{12}, \mathbf{13}, \mathbf{14}\}, F_5 = \{6, 8, 9, \mathbf{12}, \mathbf{11}\}, F_6 = \{\mathbf{1}, \mathbf{2}, \mathbf{3}, \mathbf{4}, \mathbf{5}, 6, 7\}\}.$$

and remove the vertices forming the triangle {2, 4, 7}.

We found a (3, 3)-positive polynomial certificate of non-realizability:

 $S_{(8,7)}S_{(12,8)}S_{(13,5)} + S_{(12,8)}S_{(11,9)}S_{(10,5)} + S_{(3,5)}S_{(13,8)}S_{(10,5)} = 0$,

where we use some additional facets F₇, F₈, F₉.

Pfeifle found a certificate with 5 terms of degree 4.

- The **slack model** provides a simple method for studying realizability problems through the search for positive polynomials.
- Brute force: we do not search for certificates of a certain form (such as bi-quadratic final polynomials).
- This approach is doable and effective, but the complexity grows fast.

What's next:

- Implement the method in a **unique system** optimized for computations with matrices and polynomials. This would make previously intractable realizability problems possible.
- Develop new strategies to reduce the size of computations (e.g., vertex selection, exploit symmetry).

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Thank you for listening!