Knots and contact structures

Vera Vértesi

Contact structures

Knots in contact 3–manifolds

Appendix

Knots and contact structures

Vera Vértesi

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2009

Thanks for P. Massot and S. Schönenberger for some of the pictures

Thermodynamics

E	internal energy
Т	temperature
5	entropy
Р	pressure
V	volume

First Law of Thermodynamics

$$dE = \delta Q - \delta W$$

(Q = processed heat, W = work on its surroundings) for a reversible process $\delta Q = T dS$, $\delta W = P dV$

$$dE = TdS - PdV$$

Since E, S and V are thermodynamical functions of a state, the above is true non-reversible processes too.

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Thermodynamics – geometric setup

Define the 1-form:

$$\alpha = dE - TdS + PdV$$

States of the gas are on integrals of ker α .

How many independent variables are there? = What is the maximal dimension of an integral submanifold?

$$\alpha \wedge (d\alpha)^2 = dE \wedge dT \wedge dS \wedge dP \wedge dV$$

$$(d\alpha = -dT \wedge dS + dP \wedge dV \neq 0)$$

 \Rightarrow Max dimensional integral manifolds are 2 dimensional.

Deduce state equations for ...

- ideal gases;
- ... van der Waals gases.

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Contact structures - definition

Contact structure

on a (2n + 1)-manifold M is a "maximally nonintegrable" hyperplane distribution ξ in the tangent space of M.

Locally: $\xi = \ker \alpha$ $(\alpha \in \Omega_1(M))$ "maximally nonintegrable" $\Leftrightarrow \alpha \wedge (d\alpha)^n \neq 0$

Standard contact structure On $\mathbb{R}^{2n+1} = \{(x_1, \dots, x_n, y_1, \dots, y_n, z)\} \xi_{st} = \ker \alpha$

$$\alpha_{\rm st} = dz + \sum_{i=0}^{n} x_i dy_i$$

 α is contact: $(d\alpha = \sum_{i=0}^{n} dx_i \wedge dy_i)$

$$\alpha \wedge (d\alpha)^n = 2^n dz \wedge dx_1 \wedge dy_1 \wedge \cdots \wedge \wedge dx_n \wedge dy_n \neq 0$$

Darboux's theorem

Every contact manifold locally looks like $(\mathbb{R}^{2n+1}, \xi_{st})$.

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Contact structures - origin

- thermodynamics;
- odd dimensional counterparts of symplectic manifolds;
- classical mechanics, contact element (Sophus Lie, Elie Cartan, Darboux);
- Hamiltonian dynamics;
- geometric optics, wave propagation (Huygens, Hamilton, Jacobi);
- Natural boundaries of symplectic manifolds.

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Contact structures – applications

- ► (Eliashberg) New proof for Cerf's Theorem: Diff(S³)/Diff(D⁴) = 0;
- (Akbulut–Gompf) Topological description of Stein domains;
- (Ozsváth–Szabó) HF detects the genus of a knot;
- (Ghiggini, Juhász, Ni) HFK detects fibered knots;
- (Kronheimer-Mrowka) First step to the Poincaré conjecture: Every nontrivial knot in S³ has property P;
- (Kronheimer–Mrowka) Knots are determined by their complement;
- (Kronheimer-Mrowka, Ozsváth-Szabó) The unknot, trefoil and the figure eight knot are determined by their surgery.

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Contact structures on 3-manifolds

Standard contact structure on \mathbb{R}^3

Contact structure (n=1)

on a 3-manifold Y is a "maximally nonintegrable" plane distribution ξ in the tangent space of Y.

"maximally nonintegrable" \Leftrightarrow it rotates (positively) along any curve tangent to ξ

Darboux's theorem

 $\xi = \ker(dz + xdy) \\ = \langle \frac{\partial}{\partial x}, x \frac{\partial}{\partial z} - \frac{\partial}{\partial y} \rangle$

Contact structures locally look like (\mathbb{R}^3, ξ_{st}) .

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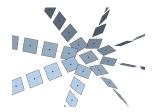
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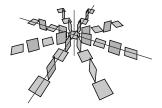
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Examples

$$\xi_{\rm sym} = dz + r^2 d\vartheta = \langle \frac{\partial}{\partial r}, r^2 \frac{\partial}{\partial z} - \frac{\partial}{\partial \vartheta} \rangle$$



$$\xi_{\rm OT} = \ker(\cos r \, dz + r \sin r \, d\vartheta) = \langle \frac{\partial}{\partial r}, r \sin r \frac{\partial}{\partial z} - \cos r \frac{\partial}{\partial \vartheta} \rangle$$



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Equivalence of contact structures

Contact isotopy

Two contact structures are isotopic if one can be deformed to the other with an isotopy of the underlying space. $\exists \Psi_t : Y \to Y$, with $\Psi_0 = id$ and $(\Psi_1)_*(\xi_0) = \xi_1$

 $\xi_{\rm sym}$ and $\xi_{\rm st}$ are isotopic:

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Do all 3-manifolds admit contact structures?

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Do all 3-manifolds admit contact structures? Yes (Martinet)

several proof using different technics:

- (Martinet, 1971) surgery along transverse knots;
- (Thurston-Winkelnkemper, 1975) open books;
- (Gonzalo, 1978) branched cover;
- (Ding-Geiges-Stipsicz) surgery along Legendrian knots.

How many contact structures does a 3-manifold admit?

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How many contact structures does a 3-manifold admit?

 ∞

Lutz twist: Once a contact structure is found we can modify it in the neighborhood of an embedded torus.

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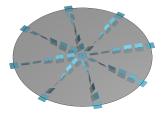
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Tight vs. overtwisted contact structures overtwisted disc

 $D \hookrightarrow Y$ such that D is tangent to ξ

$$\begin{aligned} \xi_{\rm OT} &= \ker(\cos r \, dz + r \sin r \, d\vartheta) \\ &= \langle \frac{\partial}{\partial r}, r \sin r \frac{\partial}{\partial z} - \cos r \frac{\partial}{\partial \vartheta} \rangle \end{aligned}$$



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Appendix

ξ → *overtwisted* (⊇ overtwisted disc) *ξ* → *tight* (not overtwisted) Theorem (Eliashberg):

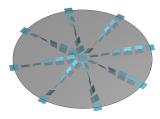
{overtwisted ctct structures}/isotopy \leftrightarrow {2-plane fields}/homotopy

⇒ tight contact structures are "interesting" geometric meaning: boundaries of complex/symplectic 4–manifolds

Tight vs. overtwisted contact structures overtwisted disc

 $D \hookrightarrow Y$ such that D is tangent to ξ along ∂D

$$\begin{split} \xi_{\rm OT} &= \ker(\cos r \, dz + r \sin r \, d\vartheta) \\ &= \langle \frac{\partial}{\partial r}, r \sin r \, \frac{\partial}{\partial z} - \cos r \, \frac{\partial}{\partial \vartheta} \rangle \end{split}$$



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Appendix

ξ \rightarrow overtwisted (\supseteq overtwisted disc) ξ \rightarrow tight (not overtwisted) Theorem (Eliashberg):

 $\{\texttt{overtwisted ctct structures}\}/\texttt{isotopy} \leftrightarrow \{\texttt{2-plane fields}\}/\texttt{homotopy}$

⇒ tight contact structures are "interesting" geometric meaning: boundaries of complex/symplectic 4–manifolds

Do all 3-manifolds admit tight contact structures?

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Do all 3-manifolds admit tight contact structures?

• (Eliashberg) S^3 admits a unique tight contact structure: ξ_{st} ;

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Do all 3-manifolds admit tight contact structures?

- (Eliashberg) S³ admits a unique tight contact structure: ξ_{st}; but:
- ► (Etnyre-Honda)-Σ(2, 3, 5), the Poincaré homology sphere with reverse orientation does not admit tight contact structure;
- ► (Lisca-Stipsicz) there exist ∞ many 3-manifold with no tight contact structure.

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How many tight contact structures does a 3-manifold admit?

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Do all 3-manifolds admit tight contact structures?

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How many tight contact structures does a 3-manifold admit? Characterization done on:

- (Giroux, Honda) Lens spaces;
- (Honda) circle bundles over surfaces;
- (Ghiggini, Ghiggini–Lisca–Stipsicz, Wu, Massot) some Seifert fibered 3–manifolds.

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Methods for classification

How can we prove tightness?

- fillability;
- Legendrian knots.

How can we distinguish contact structures?

- homotopical data;
- contact invariant from HF-homologies (Seifert fibered 3-manifolds);
- embedded surfaces;

if we know the contact structure on the surface, then it is also known in a neighborhood of the surface

How the contact structure on a surface can be encoded?

- characteristic foliation;
- on convex surfaces a multicurve is enough.

embedded curves.

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Legendrian knot

is a knot L whose tangents lie in the contact planes:

$$TL \in \xi$$
 or $\alpha(TL) = 0$



We have already seen Legendrian knots:

- an oriented plane field is a contact structure, if it "rotates" along Legendrian foliations..
- the boundary of an OT disc is Legendrian.
- ξ is tangent to D along $\partial D \Leftrightarrow \xi$ does not "twist" as we move along ∂D

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Classical Invariants

Thurston-Bennequin number

tb(L) = lk(L, L')

where L' is a push off L' of L in the transverse direction;

If Σ a Seifert surface of L (i.e. $\partial \Sigma = L$), then:

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. . . .

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$$tb_{\Sigma}(L) = \operatorname{lk}(L, L') = \#(L \cap \Sigma)$$

Note: $D \text{ is OT} \Leftrightarrow tb_D = 0$

▶ Jump back to the proof

Rotation number rot(L) is a relative Euler number of ξ on Σ w.r.t. TL Knots in $(S^3, \xi_{\rm st})$

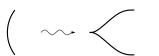
Recall: $\xi = \ker(dz + x dy)$ $TK \subset \xi \iff x = -\frac{dz}{dy} \neq \infty$



Claim:

Any knot can be put in Legendrian position.

Proof:







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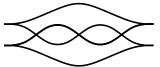
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(1,1,1)

Knots in $(S^3, \xi_{\rm st})$

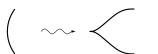
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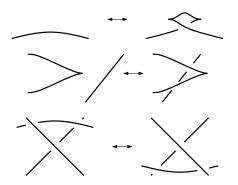
Legendrian isotopy

Legendrian isotopy

lsotopy through Legendrian knots.

Legendrian Reidemeister moves

Legendrian isotopic knots are related by the following moves:



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(1,1,1)

Are they Legendrian isotopic?

Legendrian unknots



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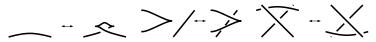
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(1,1,1)

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Which ones are Legendrian isotopic?

Remember:



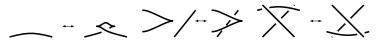
Are they Legendrian isotopic?

Legendrian unknots



Which ones are Legendrian isotopic?

Remember:



 $A \cong B \checkmark$

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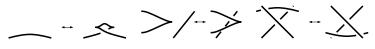
Are they Legendrian isotopic?

Legendrian unknots



Which ones are Legendrian isotopic?

Remember:



 $A \cong B \checkmark$ and $C \cong D$:



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rotation number:

er: >

for the Legendrian unknots:



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The two definition agree in $(S^3, \xi_{st} = dz + xdy)$

 $\mathbf{\mathbf{N}}$

The "new definition"

=3-0-2=1



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1.1.1

The two definition agree in $(S^3, \xi_{st} = dz + xdy)$

 $\mathbf{\mathbf{N}}$

The "new definition"

=3-0-2=1

The "old definition"

$$tb_{\Sigma}(L) = lk(L, L') = #(L \cap \Sigma)$$

where L' is a push off in the transverse direction and Σ is a Seifert surface of L.



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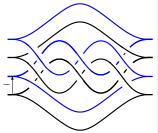
standard contact structure The two definition agree in $(S^3, \xi_{\rm st} = dz + xdy)$



The "old definition"

$$\textit{tb}_{\Sigma}(\textit{L}) = \mathrm{lk}(\textit{L},\textit{L}') = \#(\textit{L} \cap \Sigma)$$

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1.1.1

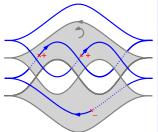
The two definition agree in $(S^3, \xi_{st} = dz + xdy)$



The "old definition"

$$\textit{tb}_{\Sigma}(\textit{L}) = \mathrm{lk}(\textit{L},\textit{L}') = \#(\textit{L} \cap \Sigma)$$

where L' is a push off in the transverse direction and Σ is a Seifert surface of L. $\frac{\partial}{\partial z}$ is a transverse direction: tb = 1 + 1 - 1 = 1



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The two definitions agree in general $\sqrt{}$

A new smooth knot invariant

tb can be decreased: $tb(L_{\pm}) = tb(L) - 1$ $rot(L_{\pm}) = rot(L) \pm 1$

Definition:

K is a smooth knot type, then:

 $\overline{tb}(K) = \max\{tb(L) : L \text{ is Legendrian repr. of } K\}$

Bennequin inequality:

 Σ is a (genus g) Seifert surface for a Legendrian knot L, then: $tb(L) + |rot(L)| \leq -\chi(\Sigma)$

(S^3, ξ_{st}) is tight. If L is the unknot then $tb(L) + |rot(L)| \le -\chi(D) = -1$, thus $tb(L) \le -1$. So $tb(L) \ne 0$

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Appendi:

 \overline{tb} distinguishes mirrors. Right and left-handed-trefoils



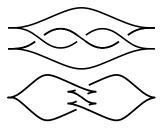


Bounds for the Thurston Bennequin number The Seifert surface of the trefoil is a punctured torus, thus

$$tb(L) + |rot(L)| \leq -\chi(\Sigma) = 1$$

the right handed trefoil realizes this bound $(\overline{tb} = 1)$:

but the left handed trefoil does not. $(\overline{tb} = -6)$



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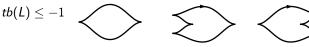
Classification of Legendrian unknots

 ${\sf Legendrian\ isotopy} \Rightarrow$

smoothly isotopy;

▶ tb ''=''.

We have seen:

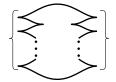


Theorem (Eliashberg-Fraser):

For any pair

$$\{(t,r):t+|r|\leq -1 \ \& \ r\equiv t \mod 2\}$$

there is exactly one Legendrian unknot with tb = t and rot = r



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 $(\cdot,\cdot)_{i\in I}$

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Proof on the "Algebraic Geometry and Differential Topology Seminar" this Friday

Classification of Legendrian knots

For the unknot we had: tb "=" & rot "=" ⇔ Legendrian isotopic

Definition:

A knot type is called *Legendrian simple* if *tb* and *rot* is enough to classify its Legendrian representations.

Legendrian simple knots:

- (Eliashberg-Fraser) unknot;
- (Etnyre-Honda) torus knots, figure eight knot;

•

Chekanov's example:

First example for a Legendrian nonsimple knot: the $\mathbf{5}_2$ knot



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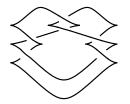
Legendrian simple knots

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Some nonsimple knot types

Checkanov's example:

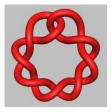




tb = 1 and rot = 0

Other nonsimple knot types:

- (Epstein-Fuchs-Meyer) twist knots;
- ► Ng
- Ozsváth–Szabó–Thurston



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Legendrian simple knots

. . . .

Further classification results

Classification of nonsimple knot types

- ▶ (Etnyre–Honda) Can classify Legendrian realizations of K₁#K₂ in terms of the classification of the Legendrian realizations of L₁ and L₂
- ▶ (Etnyre-Honda) (2,3)-cable of the (2,3) torus-knot;
- (Etnyre–Ng-V) Classification of Legendrian twist knots (work in progress).

Legendrian Twist knots with maximal tb

- (Chekanov, Epstein–Fuchs–Meyer):
 n are known to be different
- ► (Etnyre–Ng-V) There are exactly $\begin{bmatrix} \frac{(2n+1)}{2} + 1)^2}{2} \end{bmatrix}$ different Legendrian representations (work in progress).



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1.1.1

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Appendix

Thanks for your attention!

Equivalent characterizations of contact structures

(Y,ξ) is contact iff locally:

- ξ is totally nonintegrable;
- $\xi = \ker \alpha$, where $\alpha \in \Omega^1(Y)$ and $\alpha \wedge d\alpha \neq 0$;
- ξ rotates (positively) along a Legendrian foliation;

- ξ rotates (positively) along any Legendrian foliation;
- ξ is isotopic to (\mathbb{R}^3, ξ_{st}) ;
- ξ is isotopic to $(\mathbb{R}^3, \xi_{sym})$;

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Property P

Surgery

cut out a tubular neighborhood of Kglue back along a diffeomorphism $\phi: \mathcal{T}^2 o \mathcal{T}^2$

such a map is determined by $\phi(\mu)=
ho\mu'+q\lambda'$

The surgery is then called $\frac{p}{q}$ -surgery

Property P

K has Property P if surgery along K cannot give a counterexample for the Poincaré Conjecture.

Fact (Lickorish, Wallace)

Any 3-manifold can be obtained from S^3 by surgery along a link.

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Lutz twist

Lutz twist

We can change ξ along a knot $T \pitchfork \xi$: ξ is standard along T: on $\nu(T)$

$$\xi = \ker(\cos(\frac{\pi}{2}r)dt + r\sin(\frac{\pi}{2}r)d\varphi)$$

Change ξ on $\nu(T)$ to:

$$\xi' = \ker(\cos(\pi - \frac{3\pi}{2}r)dt + r\sin(\pi - \frac{3\pi}{2}r)d\varphi)$$

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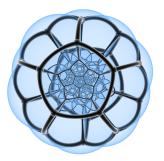
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Jump back to the classification

Poincaré homology sphere

from the dodecahedron:

Glue each pair of opposite faces of the dodecahedron by using the minimal clockwise twist.



a factor of SO(3)

with the rotational symmetries of the dodecahedron (A_5)

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