Weak solutions to the total variation flow in metric measure spaces

Wojciech Górny

University of Vienna, University of Warsaw

CEDYA/CMA 2022 Zaragoza, 21 July 2022

p-Laplacian evolution equation

Consider the model problem

$$\begin{cases} u_t = \operatorname{div}(|\nabla u|^{p-2}\nabla u) & \text{on } (0,T) \times \mathbb{R}^N; \\ u = u_0 & \text{on } \{0\} \times \mathbb{R}^N. \end{cases}$$

How to formulate this in a metric measure space?

2/18

Gradient flow of the Dirichlet energy

One possible way is to consider the energy

$$\Phi(u) = \frac{1}{p} \int_{\Omega} |\nabla u|^p$$

well-defined over $L^2(\mathbb{R}^N) \cap W^{1,p}(\mathbb{R}^N)$ and apply the classical semigroup theory (Brezis, Crandall, Komura, ...) to get existence and uniqueness of solutions to the gradient flow

$$u_t + \partial \Phi(u) \ni 0$$
,

where $\partial \Phi(u)$ is the subdifferential of Φ .

 (\mathbb{X}, d) - complete and separable, u - Radon measure.

We can define the *Cheeger energy*

$$\mathsf{Ch}_{p}(u) = \frac{1}{p} \int_{\mathbb{X}} |Du|^{p} \, d\nu$$

for $u \in L^2(\mathbb{X}, \nu) \cap W^{1,p}(\mathbb{X}, d, \nu)$ and view the *p*-Laplace equation as its gradient flow in $L^2(\mathbb{X}, \nu)$.

 (\mathbb{X}, d) - complete and separable, ν - Radon measure.

We can define the *Cheeger energy*

$$\mathsf{Ch}_{p}(u) = \frac{1}{p} \int_{\mathbb{X}} |Du|^{p} \, d\nu$$

for $u \in L^2(\mathbb{X}, \nu) \cap W^{1,p}(\mathbb{X}, d, \nu)$ and view the *p*-Laplace equation as its gradient flow in $L^2(\mathbb{X}, \nu)$.

The whole machinery works (existence, uniqueness, gradient bounds...).

Why do we want to study it in more detail?

∃ →

< 1 k

Why do we want to study it in more detail?

To get a 'pointwise' characterisation;

Why do we want to study it in more detail?

To get a 'pointwise' characterisation;

A lot of geometric properties of (X, d, ν) are encoded in the *p*-Laplace gradient flow: curvature, tangent spaces, ...

Why do we want to study it in more detail?

To get a 'pointwise' characterisation;

A lot of geometric properties of (X, d, ν) are encoded in the *p*-Laplace gradient flow: curvature, tangent spaces, ...

To cover the case of the total variation flow;

Why do we want to study it in more detail?

To get a 'pointwise' characterisation;

A lot of geometric properties of (X, d, ν) are encoded in the *p*-Laplace gradient flow: curvature, tangent spaces, ...

To cover the case of the total variation flow;

To allow for initial data in $L^1(\mathbb{X}, \nu)$;

Why do we want to study it in more detail?

To get a 'pointwise' characterisation;

A lot of geometric properties of (X, d, ν) are encoded in the *p*-Laplace gradient flow: curvature, tangent spaces, ...

To cover the case of the total variation flow;

To allow for initial data in $L^1(\mathbb{X}, \nu)$;

To study asymptotics.

Standard requirements: (X, d) complete, separable. ν is a Radon measure, which is finite on bounded subsets.

Standard requirements: (X, d) complete, separable. ν is a Radon measure, which is finite on bounded subsets.

Derivatives are replaced by upper gradients; we say that g is an upper gradient of u, if for all curves $\gamma : [0, l_{\gamma}] \to \mathbb{X}$

$$|u(\gamma(l_{\gamma}))-u(\gamma(0))|\leq \int_{0}^{l_{\gamma}}g(\gamma(t))|\dot{\gamma}(t)|\,dt.$$

Standard requirements: (X, d) complete, separable. ν is a Radon measure, which is finite on bounded subsets.

Derivatives are replaced by upper gradients; we say that g is an upper gradient of u, if for all curves $\gamma : [0, l_{\gamma}] \to \mathbb{X}$

$$|u(\gamma(l_{\gamma}))-u(\gamma(0))|\leq \int_{0}^{l_{\gamma}}g(\gamma(t))|\dot{\gamma}(t)|\,dt.$$

 $u \in W^{1,p}(\mathbb{X}, d, \nu) \Leftrightarrow u \in L^p(\mathbb{X}, \nu)$ and there exists $g \in L^p(\mathbb{X}, \nu)$.

Standard requirements: (X, d) complete, separable. ν is a Radon measure, which is finite on bounded subsets.

Derivatives are replaced by upper gradients; we say that g is an upper gradient of u, if for all curves $\gamma : [0, l_{\gamma}] \to \mathbb{X}$

$$|u(\gamma(l_{\gamma}))-u(\gamma(0))|\leq \int_{0}^{l_{\gamma}}g(\gamma(t))|\dot{\gamma}(t)|\,dt.$$

 $u \in W^{1,p}(\mathbb{X}, d, \nu) \Leftrightarrow u \in L^p(\mathbb{X}, \nu)$ and there exists $g \in L^p(\mathbb{X}, \nu)$.

"Minimal g" will be denoted |Du|.

How to introduce differentials and gradients?

∃ →

< 1 k

How to introduce differentials and gradients?

Consider a Riemannian manifold M and its cotangent bundle T^*M . It has the following properties:

How to introduce differentials and gradients?

Consider a Riemannian manifold M and its cotangent bundle T^*M . It has the following properties:

• It is equipped with a smooth differential structure;

How to introduce differentials and gradients?

Consider a Riemannian manifold M and its cotangent bundle T^*M . It has the following properties:

- It is equipped with a smooth differential structure;
- We can multiply its sections (1-forms) by smooth functions;

How to introduce differentials and gradients?

Consider a Riemannian manifold M and its cotangent bundle T^*M . It has the following properties:

- It is equipped with a smooth differential structure;
- We can multiply its sections (1-forms) by smooth functions;
- The differential $f \mapsto df$ is a linear and continuous map;

How to introduce differentials and gradients?

Consider a Riemannian manifold M and its cotangent bundle T^*M . It has the following properties:

- It is equipped with a smooth differential structure;
- We can multiply its sections (1-forms) by smooth functions;
- The differential $f \mapsto df$ is a linear and continuous map;
- If two functions have the same differential, they differ by a constant.

21.07.2022

How to introduce differentials and gradients?

Consider a Riemannian manifold M and its cotangent bundle T^*M . It has the following properties:

- It is equipped with a smooth differential structure;
- We can multiply its sections (1-forms) by smooth functions;
- The differential $f \mapsto df$ is a linear and continuous map;
- If two functions have the same differential, they differ by a constant.

Gigli's construction aims to create a metric analogue of T^*M and TM.

Define the pre-cotangent module

$$PCM_{p} = \left\{ \{(f_{i}, A_{i})\}: \quad f_{i} \in W^{1,p}(\mathbb{X}, d, \nu), \quad \sum_{i} \|Df_{i}\|_{L^{p}(A_{i}, \nu)} < \infty \right\}$$

with A_i a partition of X into Borel sets.

47 ▶

Define the pre-cotangent module

$$PCM_p = \left\{ \{(f_i, A_i)\} : \quad f_i \in W^{1,p}(\mathbb{X}, d, \nu), \quad \sum_i \|Df_i\|_{L^p(A_i, \nu)} < \infty \right\}$$

with A_i a partition of X into Borel sets.

Consider the equivalence relation on PCM_p given by

$$\{(f_i, A_i)\} \sim \{(g_j, B_j)\} \Leftrightarrow |D(f_i - g_j)| = 0 \quad \nu - a.e. \text{ on } A_i \cap B_j.$$

8/18

Define the pre-cotangent module

$$PCM_{p} = \left\{ \{(f_{i}, A_{i})\}: \quad f_{i} \in W^{1,p}(\mathbb{X}, d, \nu), \quad \sum_{i} \|Df_{i}\|_{L^{p}(A_{i}, \nu)} < \infty \right\}$$

with A_i a partition of X into Borel sets.

Consider the equivalence relation on PCM_p given by

$$\{(f_i, A_i)\} \sim \{(g_j, B_j)\} \Leftrightarrow |D(f_i - g_j)| = 0 \quad \nu - a.e. \text{ on } A_i \cap B_j.$$

We call the map $|\cdot|_* : PCM_p / \sim \to L^p(\mathbb{X}, \nu)$:

$$|\{(f_i, A_i)\}|_* := |Df_i| \quad \nu - a.e. \text{ on } A_i$$

the pointwise norm on PCM_p/\sim .

Define the pre-cotangent module

$$PCM_{p} = \left\{ \{(f_{i}, A_{i})\}: \quad f_{i} \in W^{1,p}(\mathbb{X}, d, \nu), \quad \sum_{i} \|Df_{i}\|_{L^{p}(A_{i}, \nu)} < \infty \right\}$$

with A_i a partition of X into Borel sets.

Consider the equivalence relation on PCM_p given by

$$\{(f_i,A_i)\}\sim\{(g_j,B_j)\}\Leftrightarrow |D(f_i-g_j)|=0\quad
u-{\sf a.e.} \text{ on } A_i\cap B_j.$$

We call the map $|\cdot|_* : PCM_p / \sim \to L^p(\mathbb{X}, \nu)$:

$$|\{(f_i, A_i)\}|_* := |Df_i| \quad \nu - \text{a.e. on } A_i$$

the pointwise norm on PCM_p/\sim .

The closure of PCM_p/\sim with respect to the norm $\||\{(f_i, A_i)\}|_*\|_{L^p(\mathbb{X},\nu)}$ is called the *cotangent module* $L^p(T^*\mathbb{X})$. It is an L^{∞} -normed module.

The map $d: W^{1,p}(\mathbb{X}, d, \nu)
ightarrow L^p(\mathcal{T}^*\mathbb{X})$ given by $df:=(f,\mathbb{X})$

is the differential. It is linear and continuous.

▲ 同 ▶ → 三 ▶

The map $d: W^{1,p}(\mathbb{X}, d, \nu) \to L^p(T^*\mathbb{X})$ given by

 $df := (f, \mathbb{X})$

is the differential. It is linear and continuous.

The vector fields are defined via duality:

$$L^{q}(T\mathbb{X}) := (L^{p}(T^{*}\mathbb{X}))^{*}, \quad \frac{1}{p} + \frac{1}{q} = 1.$$

 $X \in L^q(T\mathbb{X})$ is a gradient of f, if

$$df(X) = |X|^q = |df|^p_* \quad \nu - a.e.$$

The map $d: W^{1,p}(\mathbb{X}, d, \nu) \to L^p(T^*\mathbb{X})$ given by

 $df := (f, \mathbb{X})$

is the differential. It is linear and continuous.

The vector fields are defined via duality:

$$L^{q}(T\mathbb{X}) := (L^{p}(T^{*}\mathbb{X}))^{*}, \quad \frac{1}{p} + \frac{1}{q} = 1.$$

 $X \in L^q(T\mathbb{X})$ is a gradient of f, if

$$df(X) = |X|^q = |df|^p_* \quad \nu - a.e.$$

(In the Euclidean case, we have $X = |\nabla u|^{p-2} \nabla u$.)

Divergence of a vector field

 $f \in L^{r}(\mathbb{X}, \nu)$ is the divergence of $X \in L^{q}(T\mathbb{X})$, if

$$\int_{\mathbb{X}}$$
 fg $d
u = -\int_{\mathbb{X}} dg(X) \, d
u$

for all $g \in W^{1,p}(\mathbb{X}, d, \nu) \cap L^{r'}(\mathbb{X}, \nu)$. We write $f = \operatorname{div}(X)$.

< (17) > < (17) > <

10 / 18

Divergence of a vector field

 $f \in L^{r}(\mathbb{X}, \nu)$ is the divergence of $X \in L^{q}(T\mathbb{X})$, if

$$\int_{\mathbb{X}} \mathsf{fg} \ \mathsf{d}
u = - \int_{\mathbb{X}} \mathsf{d} \mathsf{g}(X) \ \mathsf{d}
u$$

for all $g \in W^{1,p}(\mathbb{X}, d, \nu) \cap L^{r'}(\mathbb{X}, \nu)$. We write $f = \operatorname{div}(X)$.

These objects are a priori nonlocal!

く 何 ト く ヨ ト く ヨ ト

The *p*-Laplacian evolution equation

Recall that we study the gradient flow of the Cheeger energy

$$\operatorname{Ch}_p(u) = \frac{1}{p} \int_{\mathbb{X}} |Du|^p \, d\nu.$$

We use the Gigli structure to provide a characterisation of ∂Ch_p .

Theorem (G.-Mazón, JFA 2022) Let $1 . We say that <math>(u, v) \in \mathcal{A}_p$ iff $u \in L^2(\mathbb{X}, \nu) \cap W^{1,p}(\mathbb{X}, d, \nu)$, $v \in L^2(\mathbb{X}, \nu)$, and there exists $X \in L^q(T\mathbb{X})$ with $\operatorname{div}(X) \in L^2(\mathbb{X}, \nu)$ s.t. $-\operatorname{div}(X) = v$; $du(X) = |du|_*^p = |X|^q \quad \nu - a.e.$

Then, $\partial Ch_p = \mathcal{A}_p$.

11/18

く 白 ト く ヨ ト く ヨ ト

Sketch of proof

It is easy to check that $\mathcal{A}_p \subset \partial Ch_p$. Since ∂Ch_p is maximal monotone, we need to show that also \mathcal{A}_p is maximal monotone.

< 4 → <

Sketch of proof

It is easy to check that $\mathcal{A}_p \subset \partial Ch_p$. Since ∂Ch_p is maximal monotone, we need to show that also \mathcal{A}_p is maximal monotone.

Minty theorem: a monotone operator A is maximal iff R(I + A) = H.

Sketch of proof

It is easy to check that $\mathcal{A}_p \subset \partial Ch_p$. Since ∂Ch_p is maximal monotone, we need to show that also \mathcal{A}_p is maximal monotone.

Minty theorem: a monotone operator A is maximal iff R(I + A) = H.

We need to show that for all $g \in L^2(\mathbb{X}, \nu)$ there exists $u \in D(\mathcal{A}_p)$ and $X \in L^q(T\mathbb{X})$ with $\operatorname{div}(X) \in L^2(\mathbb{X}, \nu)$ such that

1. (1/)

$$-\operatorname{div}(X) = g - u;$$
$$du(X) = |du|_*^p = |X|^q \quad \nu - \text{a.e.}$$

We cannot resort to approximations! Instead, we prove this by finding a functional G such that the above is the dual to the minimisation of G.

Back to the gradient flow

Theorem (G.-Mazón, JFA 2022)

For any $u_0 \in L^2(\mathbb{X}, \nu)$ and all T > 0 there exists a unique weak solution u(t) of the p-Laplacian evolution equation in the following sense:

There exists $u \in C([0, T]; L^2(\mathbb{X}, \nu)) \cap W^{1,2}_{loc}(0, T; L^2(\mathbb{X}, \nu)), u(0, \cdot) = u_0$, for a.e. $t \in (0, T)$ $u(t) \in W^{1,p}(\mathbb{X}, d, \nu)$, and there exist vector fields $X(t) \in L^q(T\mathbb{X})$ with $\operatorname{div}(X(t)) \in L^2(\mathbb{X}, \nu)$ such that

$$\operatorname{div}(X(t)) = u_t(t, \cdot)$$
 in \mathbb{X} ;

$$du(t)(X(t)) = |du(t)|_*^p = |X(t)|^q \quad \nu$$
-a.e. in X.

く 目 ト く ヨ ト く ヨ ト

How to do this for p = 1?

We need to replace $W^{1,p}(\mathbb{X}, d, \nu)$ with $BV(\mathbb{X}, d, \nu)$, and the pairing du(X) with the Anzellotti pairing given by

$$\langle (X, Du), f \rangle := -\int_{\mathbb{X}} u \, df(X) \, d\nu - \int_{\mathbb{X}} u \, f \operatorname{div}(X) \, d\nu.$$

Here, $f \in \operatorname{Lip}(\mathbb{X})$ has compact support. This formula defines a Radon measure and the condition $du(X) = |du|_*^p = |X|^q$ is replaced with $||X||_{\infty} \leq 1$ and $(X, Du) = |Du|_{\nu}$.

How to do this for p = 1?

We need to replace $W^{1,p}(\mathbb{X}, d, \nu)$ with $BV(\mathbb{X}, d, \nu)$, and the pairing du(X) with the Anzellotti pairing given by

$$\langle (X, Du), f \rangle := -\int_{\mathbb{X}} u \, df(X) \, d\nu - \int_{\mathbb{X}} u \, f \operatorname{div}(X) \, d\nu.$$

Here, $f \in \text{Lip}(\mathbb{X})$ has compact support. This formula defines a Radon measure and the condition $du(X) = |du|_*^p = |X|^q$ is replaced with $||X||_{\infty} \leq 1$ and $(X, Du) = |Du|_{\nu}$.

The pairing (X, Du) agrees with du(X) for Lipschitz functions and satisfies the 'expected' properties such as the validity of a Gauss-Green formula.

くぼう くほう くほう しゅ

The total variation flow

We understand the TV flow as the gradient flow of the 1-Cheeger energy

$$\mathsf{Ch}_1(u) = \int_{\mathbb{X}} |Du|_{\nu}.$$

Under a bit more restrictive assumptions on ν , we use the Gigli structure and the new Anzellotti pairing to provide a characterisation of ∂Ch_1 .

Theorem (G.-Mazón, JFA 2022)

We say that $(u, v) \in A_1$ iff $u \in L^2(\mathbb{X}, \nu) \cap BV(\mathbb{X}, d, \nu)$, $v \in L^2(\mathbb{X}, \nu)$, and there exists $X \in L^{\infty}(T\mathbb{X})$ with $\|X\|_{\infty} \leq 1$ and $\operatorname{div}(X) \in L^2(\mathbb{X}, \nu)$ s.t.

$$-\operatorname{div}(X) = v;$$

$$(X, Du) = |Du|_{
u}$$
 as measures.

Then, $\partial Ch_1 = A_1$.

< □ > < □ > < □ > < □ > < □ > < □ >

Back to the gradient flow

Theorem (G.-Mazón, JFA 2022)

For any $u_0 \in L^2(\mathbb{X}, \nu)$ and all T > 0 there exists a unique weak solution u(t) of the total variation flow in the following sense:

There exists $u \in C([0, T]; L^2(\mathbb{X}, \nu)) \cap W^{1,2}_{loc}(0, T; L^2(\mathbb{X}, \nu)), u(0, \cdot) = u_0$, for a.e. $t \in (0, T)$ $u(t) \in BV(\mathbb{X}, d, \nu)$, and there exist vector fields $X(t) \in L^{\infty}(T\mathbb{X})$ with $||X||_{\infty} \leq 1$ and $\operatorname{div}(X(t)) \in L^2(\mathbb{X}, \nu)$ such that

$$\operatorname{div}(X(t)) = u_t(t, \cdot)$$
 in \mathbb{X} ;

 $(X(t), Du(t)) = |Du(t)|_{\nu}$ as measures on \mathbb{X} .

・ 同 ト ・ ヨ ト ・ ヨ ト …

Extensions: bounded domains

We need to work under assumptions that guarantee existence of a linear and continuous trace operator.

 $(u, v) \in \mathcal{A}_{\mathcal{N}}$ (resp. \mathcal{A}_{f}) if and only if $u, v \in L^{2}(\Omega, \nu)$, $u \in BV(\Omega, d, \nu)$ and there exists a vector field $X \in L^{\infty}(T\Omega)$ with $||X||_{\infty} \leq 1$ s.t.

$$-{
m div}_0(X)=v$$
 in $\Omega;$

 $(X, Du) = |Du|_{\nu}$ as measures;

 $(X \cdot \nu_{\Omega})^{-} = 0$ (resp. $(X \cdot \nu_{\Omega})^{-} \in \operatorname{sign}(T_{\Omega}u - f)$) $|D\chi_{\Omega}|_{\nu} - a.e.$ on $\partial\Omega$.

▲□ ▲ □ ▲ □ ▲ □ ● ● ● ●

Extensions: L^1 initial data

If $\nu(\mathbb{X}) < \infty$, then for any $u_0 \in L^1(\mathbb{X}, \nu)$, there exists a unique *entropy* solution of the total variation flow in the following sense:

• $u \in C([0, T]; L^1(X, \nu)) \cap W^{1,2}_{loc}([0, T]; L^1(X, \nu));$

•
$$u(0, \cdot) = u_0;$$

- For a.e. $t \in [0, T]$ and all k > 0 we have $T_k u(t) \in BV(\mathbb{X}, d, \nu)$;
- There exist vector fields $X(t) \in L^{\infty}(T\mathbb{X})$ with $\operatorname{div}(X(t)) \in L^{1}(\mathbb{X}, \nu)$ and $\|X(t)\|_{\infty} \leq 1$ s.t.

$$\operatorname{div}(X(t)) = u_t(t, \cdot)$$
 in \mathbb{X} ;

 $(X(t), DT_k u(t)) = |DT_k u(t)|_{\nu}$ as measures for all k > 0.